



Evaluating and Implementing a New Pillar Fracturing Technology Using Local Sand for Proppants in the Middle East, see page 2

Determining Effective Mixture Viscosities in Oil-Water Flows for Downhole Oil Field Operations, see page 24





Resin coated proppants typically used in the hydraulic fracturing process.

## On the Cover

Sample used for fracture conductivity testing in the laboratory to measure the proppant conductivity. This experimental setup allows engineers to evaluate the crushing of the proppant material under downhole stress, temperature, and pressure conditions.

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# Evaluating and Implementing a New Pillar Fracturing Technology Using Local Sand for Proppants in the Middle East

Dr. Fakuen F. Chang, Naresh K. Purusharthy, Mohamed Khalifa, and Dr. Raed Rahal

## ABSTRACT

Using local natural silica sand as a proppant can significantly reduce costs as hydraulic fracturing activities increase in the Middle East. Though natural sand resources in the region are abundant, they are mechanically weaker than the typical proppants necessary to fracture deep gas reservoirs. Using chemicals to bind sand grains to form competent pillars within a hydraulic fracture can help sustain conductivity at high closure stress and prevent mobilization of the crushed fines. A laboratory study demonstrated that this approach can generate stable and highly conductive channels with a near infinite fracture conductivity. A field trial of such technology was performed.

Careful evaluation was performed on many gas wells to select a candidate based on the plain strain modulus and other petrophysical parameters. Before the primary fracturing treatment, a diagnostic fracture injection test and minifrac were conducted to calibrate rock properties used in the fracturing design. The proppant was placed by pulsed pumping to render proppant pillars of resin bonded local sand. Among the pillars are wide channels through which the reservoir fluid can be effectively produced. The post-fracturing treatment flow back sample analysis showed neither proppant nor fines production. The field test results indicated that this technique, which was being performed for the first time in the Middle East, can be a viable means to enhance productivity in low permeability formations.

This article describes the experimental study to evaluate the feasibility of using low-cost raw sand in combination with a pillar fracturing technique to fracture high stress formations. The engineering approach for design, implementation, and assessment of such a technique in a gas reservoir is also presented.

## INTRODUCTION

Fracturing is a primary technique used worldwide for stimulating oil and gas wells, both in conventional reservoirs and unconventional resources. With an increasing focus on deep and tight gas exploration and production, both cost-effectiveness and uncompromised productivity are extremely important to unlock the economics of these plays. Technologies to achieve these objectives include a combination of the proper chemicals

and materials with novel engineering designs.

Hydraulic fracturing in tight gas reservoirs requires pumping significant amounts of high strength ceramic or bauxite proppants that can withstand high closure stress, and therefore, maintain fracture conductivity. As fracturing activity increases, cost-effectiveness becomes a key driver for the continuous growth of the market. Silica sand is a low-cost material that is an abundantly available natural resource. Being able to widely apply such material for fracturing can significantly improve the economic viability of the treatment. Several research and development and engineering initiatives have been performed to achieve this goal<sup>1</sup>. This article documents one such initiative related to the investigation of using weak Saudi Arabian local sand combined with resin chemicals to determine the feasibility of fracturing with this low-cost material.

To improve the performance of fracturing treatments using weak local sand, a non-cured resin system that coats the sand just before it is introduced to the fracturing fluid was used. Inside the fracture this resin allows the building of aggregated pillars that have the propping strength necessary to withstand high closure stress and allow highly conductive flow paths to form around the sand aggregates. In addition to providing support against fracture closure, the resin bonded sand pillars are more ductile at the grain contact points. Therefore, crushing becomes less severe, and even if crushed fines occur, they tend to be confined within the cured resin network instead of becoming mobilized. These mechanisms enable the fracturing of deep gas wells to be accomplished using this low-cost material<sup>2</sup>.

Laboratory studies show that the local sand in its raw state can be significantly crushed at 5,000 psi and higher; however, when resin coating is applied to form consolidated pillars, the pillar strength is sufficient to withstand closure stresses greater than 12,000 psi. Parallel testing using commercial high-strength proppants (HSPs) indicated comparable performance. The effluent contained almost no fines from the crushed particles. The conductivity remained near infinite, indicating flow channels are propped open effectively, even at high closure stress. The pillar fracturing design method was executed in the Middle East using HSPs. The resin coating process has been regularly used on location, so its methods for implementation have matured operationally. Laboratory test results showed that replacing the HSP with local sand performs equally well, but at a much lower cost.





Fig. 1. A resin cured 20/40-mesh local sand pillar loaded on a conductivity measurement slab.

## EXPERIMENTAL

A thorough laboratory study was conducted to help engineer the process necessary to implement the local sand, which is intrinsically weak, into fracturing field treatments on high-stress formations. The experiments were designed to: (1) optimize strength of the aggregated pillars by addressing the bonding mechanism between the sampled sand and resin to identify formulations to render strong and resilient structures capable of surviving closure stress at downhole temperatures; (2) evaluate conductivity through the aggregates and channels to determine engineering parameters for designing the fracturing treatment; and (3) determine fracture conductivity as a function of closure stress and fines prevention under cyclic stress.

### Laboratory Evaluation of Pillar Fracturing Technology

Rectangular shaped strips of cured resin with 20/40-mesh local sand were prepared by mixing the resin with sand and then curing them at 275 °F for 12 hours. Various concentrations of the resin were mixed with 11 g of sand to prepare a 1" × 5" strip — using a mold — and then cured, Fig. 1. The cured strip was placed inside an API cell for conductivity testing, leaving space for channels on both sides within the test cell chamber between two pistons. The cell was then placed into a Dake® press, plumbed, confined, and then the pistons applied stress to 2,000 psi. The test cell temperature was increased to 300 °F, and 2% potassium chloride (KCl) brine was pumped continuously through the chamber at 2 mL/min. After 24 hours, closure stress was increased to the desired level for 48 hours while maintaining a continuous brine flow. Conductivity was measured intermittently.

### Unconfined Compressive Strength

Figure 2a shows one pillar of 1" diameter and 3" length that was created with resin cured coated 20/40-mesh local sand, and Fig. 2b shows one pillar that was created with resin cured coated 20/40-mesh HSP sand — in a brass cell at 275 °F for 12 hours. The surfaces at both the ends of the pillars were made uniform using sandpaper. Then, the unconfined compressive strength (UCS) of these pillars was determined using an INSTRON® press.

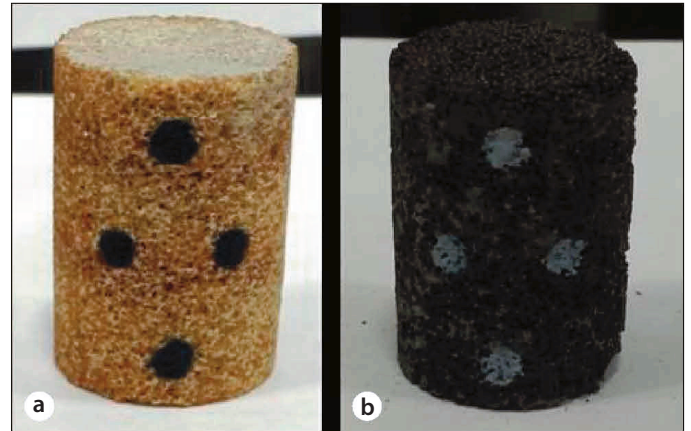


Fig. 2. Resin cured cores of: (a) 20/40-mesh local sand, and (b) 20/40-mesh HSP sand.

### Cyclic Testing Procedure

A 100-ton Dake® press was used for applying the experimental closure stress on the channels enclosed in the API conductivity cell. The API conductivity cell with channel setup using the resin and 20/40-mesh sand cured in a rectangular strip shape was loaded into the Dake® press, a closure stress of 1,000 psi was maintained for 12 hours, and a 2% KCl brine flow rate of 2 mL/min was applied while maintaining the temperature at 300 °F.

After 12 hours at 1,000 psi and 300 °F, the closure stress was increased to 8,000 psi and allowed to stabilize for 1 hour at a flow rate of 2 mL/min. Then, the flow rate was increased to 80 mL/min and the conductivity was measured. This flow rate was

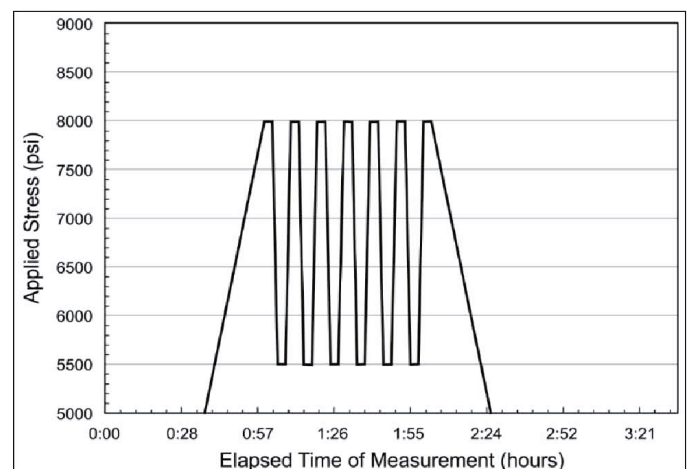


Fig. 3. Stress cycles applied during the fracture conductivity measurements.

Property	A Sand 20/40-mesh	D Sand 20/40-mesh	A Sand 16/30-mesh	D Sand 16/30-mesh	D Sand 30/50-mesh	Northern White Sand 20/40-mesh	Brown Sand 20/40-mesh
Specific gravity	2.64	2.63	—	—	2.65	2.65	2.65
Acid solubility (%)	3.76	0.55	2.22	1.11	0.55	0.6-0.7	0.9
Krumbein sphericity	0.64	0.72	0.77	0.73	0.65	0.7-0.9	0.64
Krumbein roundness	0.70	0.71	0.66	0.6	0.68	0.7-0.9	0.62
<b>Crush Resistance Test (% fines)</b>							
1,000 psi	—	0.3	—	—	0.51	—	—
2,000 psi	1.3	1.5	3.3	4.7	1.18	0.7	0.7
3,000 psi	—	5.4	—	—	3.56	—	2.0
4,000 psi	10.5	17.1	22.9	26.1	6.71	1.6	6.7
5,000 psi	—	—	—	—	15.67	2.6	—
6,000 psi	24.5	—	37.0	39.4	—	—	—

Table 1. A comparison of the properties of the sand — size and crush resistance properties

maintained for six stress cycles, and the temperature was maintained at 300 °F. The first stress cycle was completed by decreasing the closure stress to 5,500 psi, and after achieving a stable closure stress of 5,500 psi, increasing again to 8,000 psi. At the end of six such stress cycles in approximately 1 hour, the conductivity was measured again at 80 mL/min and recorded.

Figure 3 depicts the stress cycles applied for the fracture conductivity measurements. The same test was repeated for two other flow rates: 150 mL/min and 250 mL/min.

The effluent during the conductivity measurement was filtered for measuring the fines generated, if any.

## Results

For the local sand to be considered as a viable product for propping hydraulic fractures, the API crush strength and physical appearance characteristics were first measured. Table 1 compares the properties of the sands from several sources.

It was observed that the local sand showed high fines generation beginning at low closure stress, compared to conventional white and brown sands. The “A Sand” 20/40-mesh that showed superior properties among the local sands tested was selected for further testing.

UCS measurements were performed on local sand and resin aggregates at room temperature. Various resin-to-sand mass ratios were used to optimize the formulation for rendering the highest strength. Figure 4 shows the high, medium, and low resin-to-sand mass ratio results. For 30/50-mesh, the sand pillar formed by resin coated sand was actually stronger than the HSP pillar when a low resin-to-proppant ratio was used. Subsequently, for the 20/40-mesh, the sand pillars were stronger than the HSP pillars at all levels of resin-to-proppant ratios. Figure 4 results also show the higher the resin-to-sand mass ratio,

the higher the UCS of the aggregate can be formed. This indicates that in a resin consolidated pillar, the overall load-bearing capacity is dominated by the resin matrix and the bonding strength between the resin and the sand or proppant grains rather than the intrinsic strength of the grains. This allows using weaker grains to create pillars for fracturing as long as the bonding strength is sufficient.

The formulation that produced the highest UCS was the A Sand 20/40-mesh pillar, formed by a high resin-to-sand mass ratio. This formulation was selected to perform a modified<sup>3</sup> conductivity channel measurement to evaluate its durability for maintaining conductivity and preventing fines production at 10,000 psi and 12,000 psi closure stress and 300 °F. The results of the modified API conductivity testing with the pillar as the proppant medium showed that the conductivity remained constant at 22,132 md-ft and 11,498 md-ft at 10,000 psi and 12,000 psi, respectively.

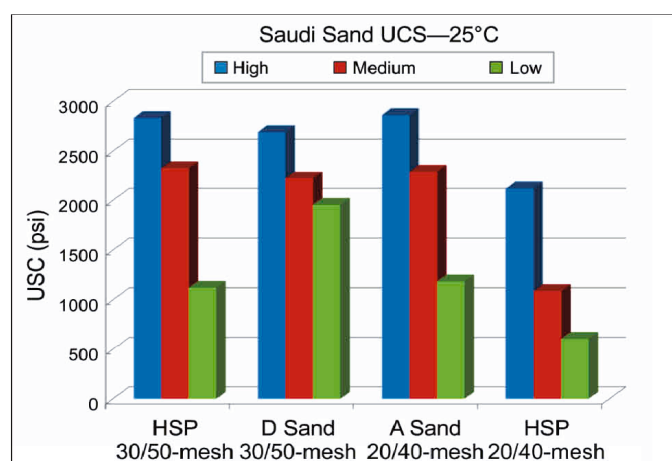


Fig. 4. UCS comparison for local sand and HSP vs. conventional proppants at room temperature.



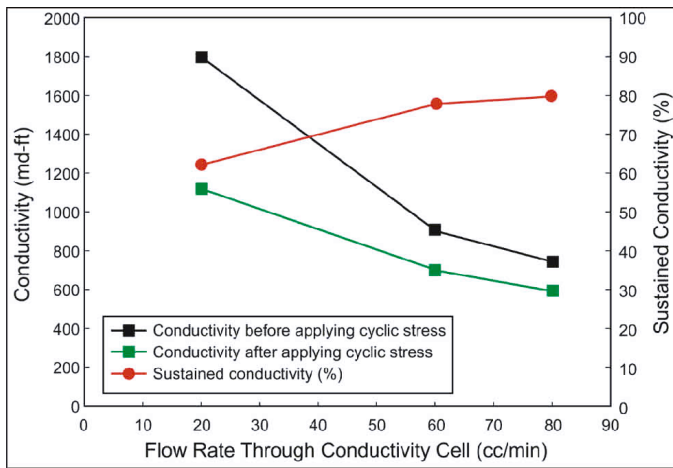


Fig. 5. Sustained conductivity channel using an A Sand 20/40-mesh consolidated pillar with a lower concentration of resin-to-sand mass.

Evaluation of conductivity performance under cyclic stress showed that a pillar of A Sand 20/40-mesh with a lower resin-to-sand mass ratio sustained conductivity of 60% to 80% after experiencing six complete stress cycles, Fig. 5.

Further testing using A Sand 20/40-mesh with a medium resin-to-sand mass ratio showed a loss of conductivity when the number of cycles increased. The regained conductivity declined below 30% after 18 cycles, though the absolute conductivity was still high at greater than 10,000 md-ft, Fig. 6.

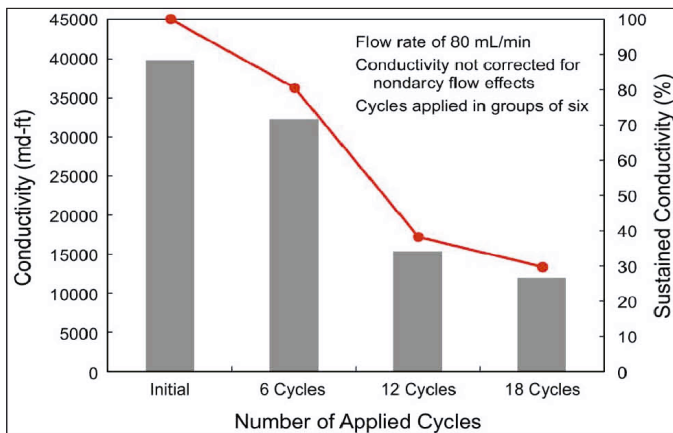


Fig. 6. Sustained conductivity of the medium resin-to-sand concentration pillar fracturing channels as a function of stress cycling.

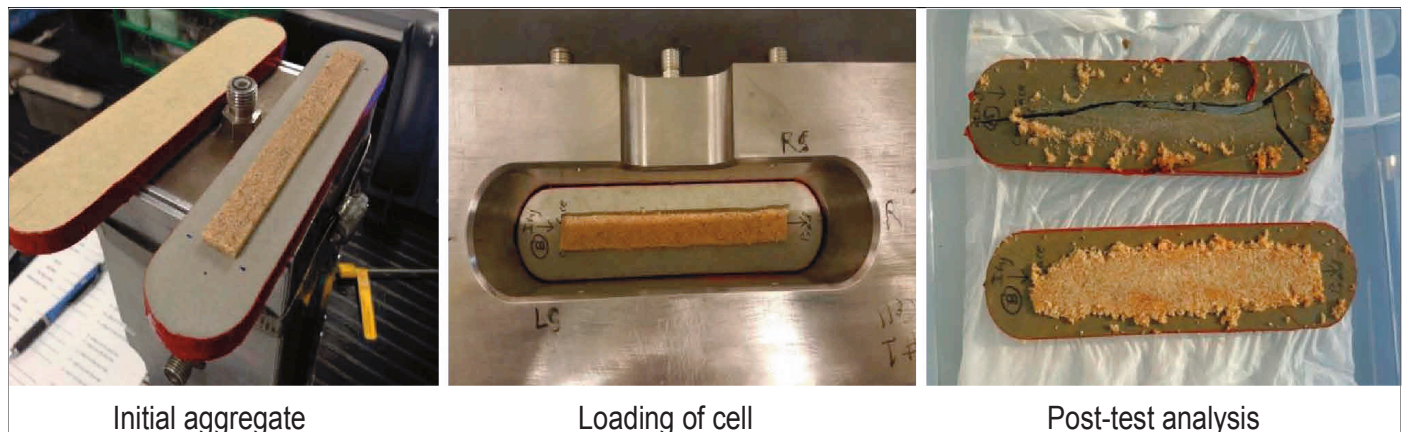


Fig. 7. Aggregate survivability investigation, showing the post-test results (right).

Post-test aggregate survivability investigations showed that the resin consolidated sand aggregate remained at the center of the fracture, leaving clear channels on both sides of the pillar, Fig. 7. The aggregates and channel were determined to be intact after the test. No fines generation occurred during the conductivity measurements. The observed conductivity reduction after the stress cycles was caused by a reduction of fracture width as the pillar deformed plastically; however, the channels remained open without fines plugging. Therefore, the overall conductivity was still high, even after a 75% fracture width reduction.

## CASE STUDY

The pillar fracturing treatment was conducted in a sandstone gas reservoir having a bottom-hole static temperature of 263 °F. The vertical well was planned to be fractured across a 20 ft perforated interval. To properly evaluate the suitability of the candidate well and determine the merit of the resin consolidated pillar fracturing technique, the treatment was designed to include: (1) an injection test, step rate test, minifrac, and flow back after minifrac to measure the gas flow rate; and (2) the primary proppant fracturing treatment followed by flow back to measure the post-fracturing gas flow rate.

Fracturing operations began with an injection test being pumped using a total volume of 58 barrels (bbl) of treated water at a stable rate of 16 bbl/min. The breakdown pressure was observed at approximately 5,330 psi, Fig. 8, and pressure decline analysis estimated a reservoir permeability of approximately 0.06 md.

The fracture data determination was later performed with approximately 350 bbl of 35 lbm/1,000 gal cross-linked fluid flushed with 212 bbl of 20 lbm/1,000 gal linear gel at a pump rate of 30 bbl/min. A high-definition temperature survey was performed to evaluate the fracture height growth and calibrate the pressure match accordingly. Figure 9 shows the treating pressure and fracture data analysis result.

After deliberate pressure matching and model calibration, the primary pillar fracturing treatment was redesigned to meet specific design parameter requirements. The new

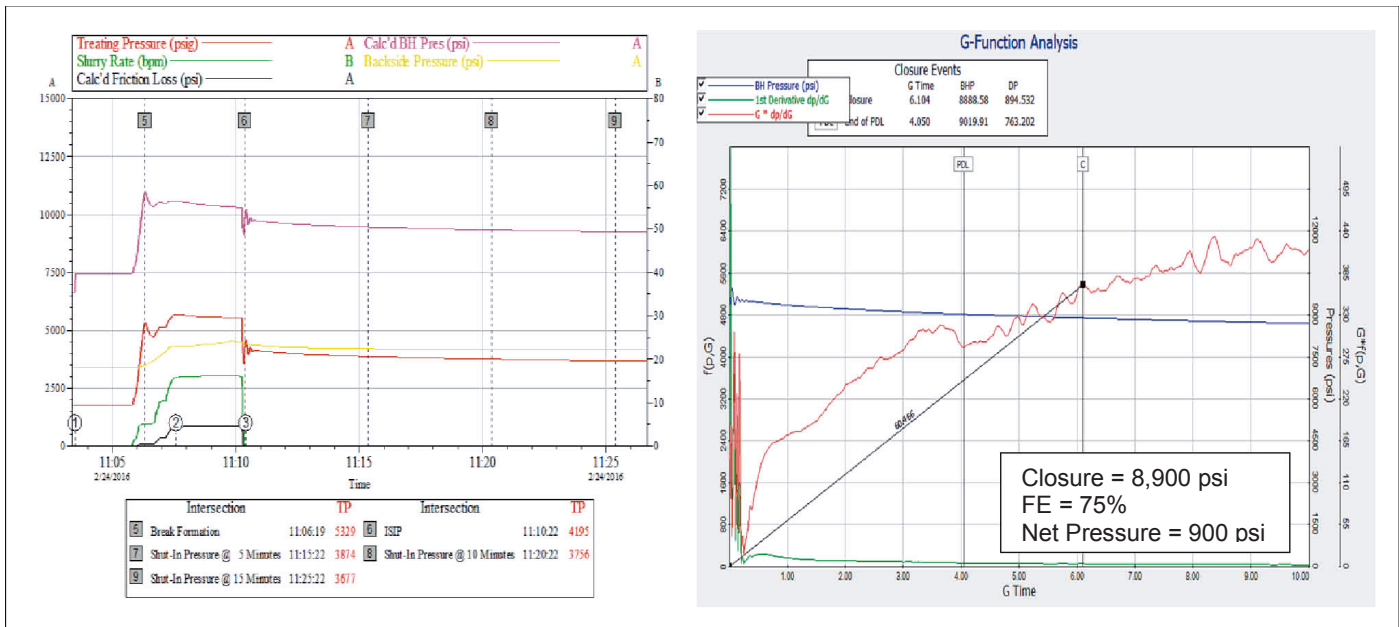


Fig. 8. Injection test data and analysis.

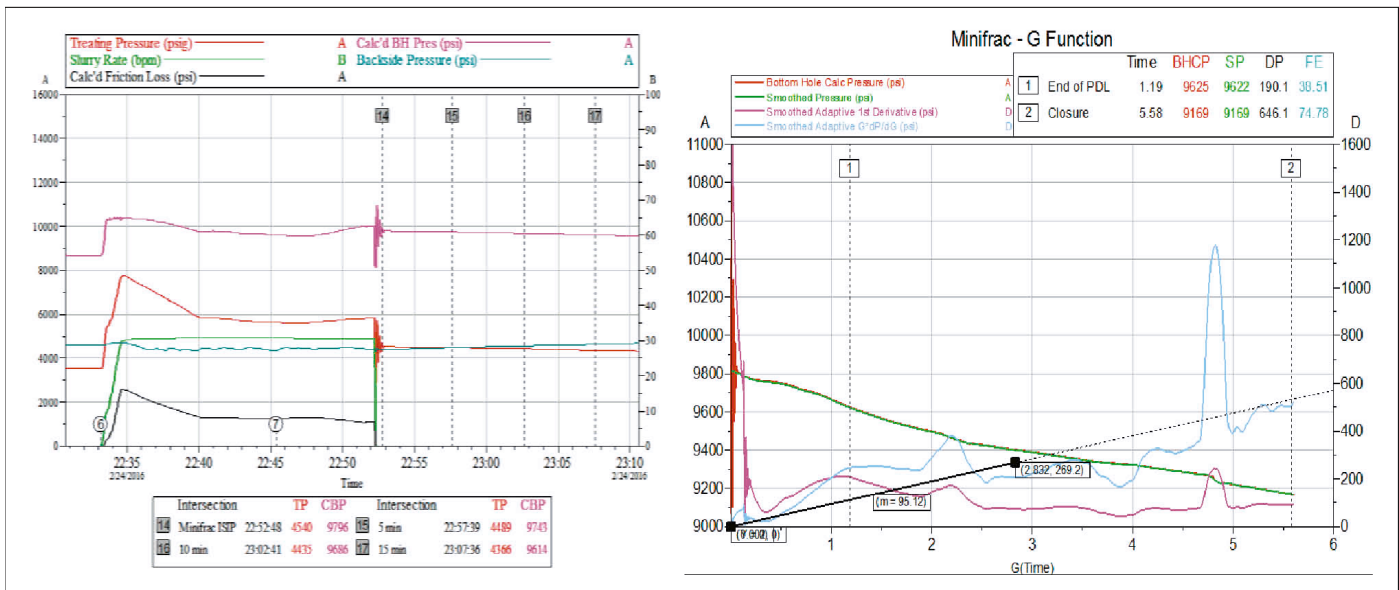


Fig. 9. Fracturing data determination and analysis.

design for the pillar fracturing treatment consisted of 1,798 bbl of 35 lbm/1,000 gal cross-linked gel as well as 490 bbl of 30 lbm/1,000 gal cross-linked gel to place 81,600 lbm of sand coated with resin. This was followed by 187 bbl of 20 lbm/1,000 gal linear gel carrying 72,600 lbm of 20/40-mesh intermediate strength proppant coated with the same resin. The treatment was performed at an average pumping rate of 30 bbl/min. The sand laden slurry was pumped in pulsating mode to create pillars that would promote an infinitely conductive path through them. It is important to reiterate that the sand has low compressive strength, and the key objective was to achieve the creation of sand pillars. The key to maintaining infinite conductivity is the capability of confining the crushed sand within the pillar. This was achieved by including a resin capable of binding the crushed sand particles, thereby preventing pillars from collapsing. Figure 10 shows the sequential pulsing and

proppant placement pattern during the primary fracturing treatment, and the fracture geometry from the design model.

The efficiency of this unique approach was proven when the well was put on flow back. During this period, the well was able to deliver an acceptable gas rate at sufficiently high flowing wellhead pressure. No fines or sand production were observed during the entire flow back period of 3 days.

## CONCLUSIONS

Pillar fracturing technology using local sand and a resin coating to form aggregates could be a viable solution to fracturing reservoirs having closure stresses much higher than the intrinsic proppant grain crushing resistance. As shown by this laboratory and field study, several key elements should be addressed to help ensure the successful application of such a process:



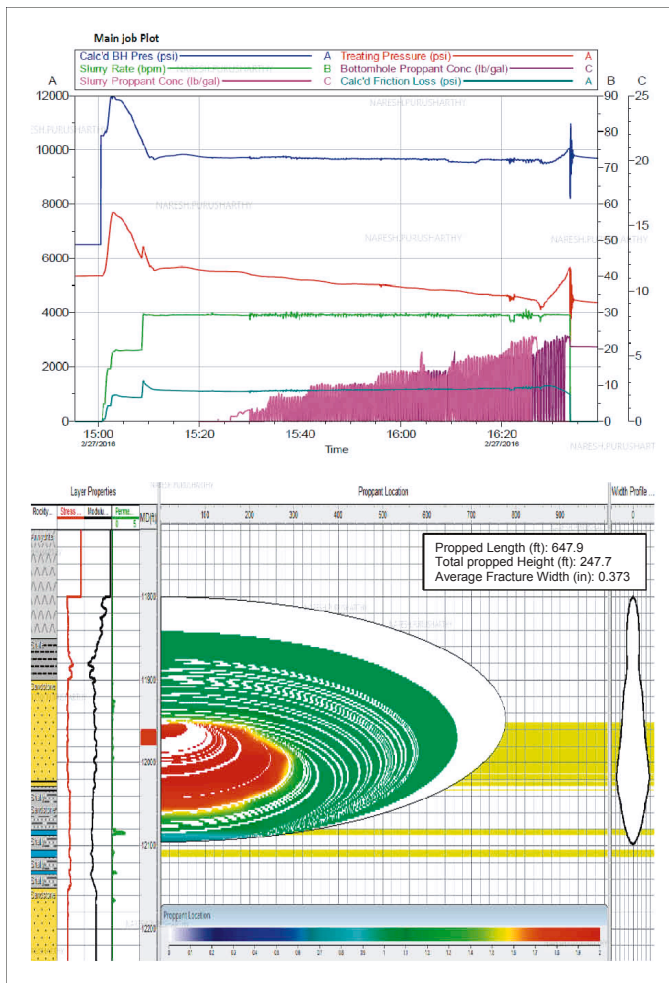


Fig. 10. Primary fracturing treatment; sequential pulsing and proppant placement pattern from the design model.

- Optimize the resin-to-sand mixture to render the high compressive strength of the pillar.
- Formulate the chemicals to attain high bonding strength between the resin material and sand grains.
- Select a competent formation that does not generate fines, or that could cause significant embedment.
- Incorporate cyclic stress testing into conductivity measurements to determine the stability of the aggregated pillars.

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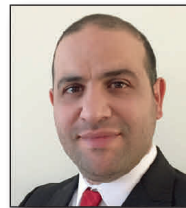


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During his career, Raed has published more than 25 papers and has been awarded four patents.



# Development of Scaling Resistant Coatings for High Temperature Sour Gas Service

Dr. Lawrence Kool, Dr. Qiliang Wang, Dr. Nidal A. Ghizawi, Dr. Fauken F. Chang, and Hui Zhu

## ABSTRACT

Iron sulfide scaling is one of the primary causes of impairment of gas production in deep sour reservoirs in Saudi Arabia. The wells are typically acid fractured and completed with carbon steel tubing. The combination of corrosion of tubes caused by hydrogen sulfide ( $H_2S$ ) and iron dissolved from the tubes during the acidizing process at high temperature, though inhibited, leads to significant scaling issues. This scale in tubulars can cause significant production losses and restricts well access for surveillance and intervention operations. A fundamental solution, therefore, is required to prevent iron sulfide scale formation and deposition along downhole tubulars. One cost-effective approach to mitigating scaling in downhole tubing is to develop high performance coatings for carbon steel tubing. This article describes the development of novel coating materials and methods and evaluation of their effectiveness in preventing iron sulfide scale.

## INTRODUCTION

Scaling of production tubing<sup>1</sup> is the primary reason<sup>2</sup> for loss of gas production<sup>3</sup> in deep sour reservoirs in Saudi Arabia. These wells are completed with carbon steel production tubing. The primary component of the scale is iron sulfide, with iron ions generated by hydrogen sulfide ( $H_2S$ ) and acid attacks of the steel during acid treatment. The iron sulfide scale can cause significant production losses and restricts access to the well for surveillance and intervention. A fundamental solution to this scaling problem is required. Our approach was to develop cost-effective, high performance coatings for the inner surface of the carbon steel production tubing.

## EXPERIMENTAL PROCEDURE

A high-pressure, high temperature (HPHT) autoclave facility with rotating cage and sour gas capability was established in laboratories for safely handling  $H_2S$  gas exposure of coated and uncoated test coupons to simulate field conditions. It was crucial that strictly anoxic conditions be maintained in the autoclave after loading to assure that only iron(II) sulfide (FeS) scaling occurred, without any possibility of oxidation.

This apparatus was used to screen T95 steel coupons under conditions where uncoated coupons rapidly developed FeS scales from the direct reaction of steel with  $H_2S$  under HPHT conditions in synthetic brine — having a similar composition of the Saudi Arabian field. Once baseline conditions were established, coupons completely coated on all sides with various coating formulations were subjected to the same environment to probe their resistance to direct attack by HPHT  $H_2S$  and to indirect scaling caused by externally produced FeS.

The equipment setup allows each experiment to test five coating formulations and one uncoated control sample. In every case, the control coupon scaled heavily and shed significant amounts of suspended FeS into the brine. This suspended FeS was then re-deposited on the five coated coupons (visible as white clusters in Fig. 1a). After testing, the coupons were thoroughly rinsed in running deionized water to dislodge any loosely adherent solids, then air-dried, and weighed to determine the extent to which they had lost or gained weight. They were then examined by scanning electron microscope (SEM), energy dispersive X-ray spectroscopy (EDS), and X-ray fluorescence to rank their anti-scaling performance. These data were used to make a down selection of the best anti-scaling coatings for these conditions.

## RESULTS

### Types of Coatings Tested

Our initial hypothesis was that if we were to develop a coating that was resistant to corrosion by  $H_2S$ , then this coating should not only prevent the formation of FeS via corrosion of the steel, but also prevent deposition of preformed FeS owing to the lack of a driving force for adhesion. Prevention of the formation of corrosion products on the metal surface was expected to minimize scale initiation. In addition to being unreactive with respect to corrosion, the coatings need to have the following attributes:

- Nonstick with respect to scalant species, e.g., complex oxides, carbonates and sulfides.
- Wear and abrasion resistant to survive damage from

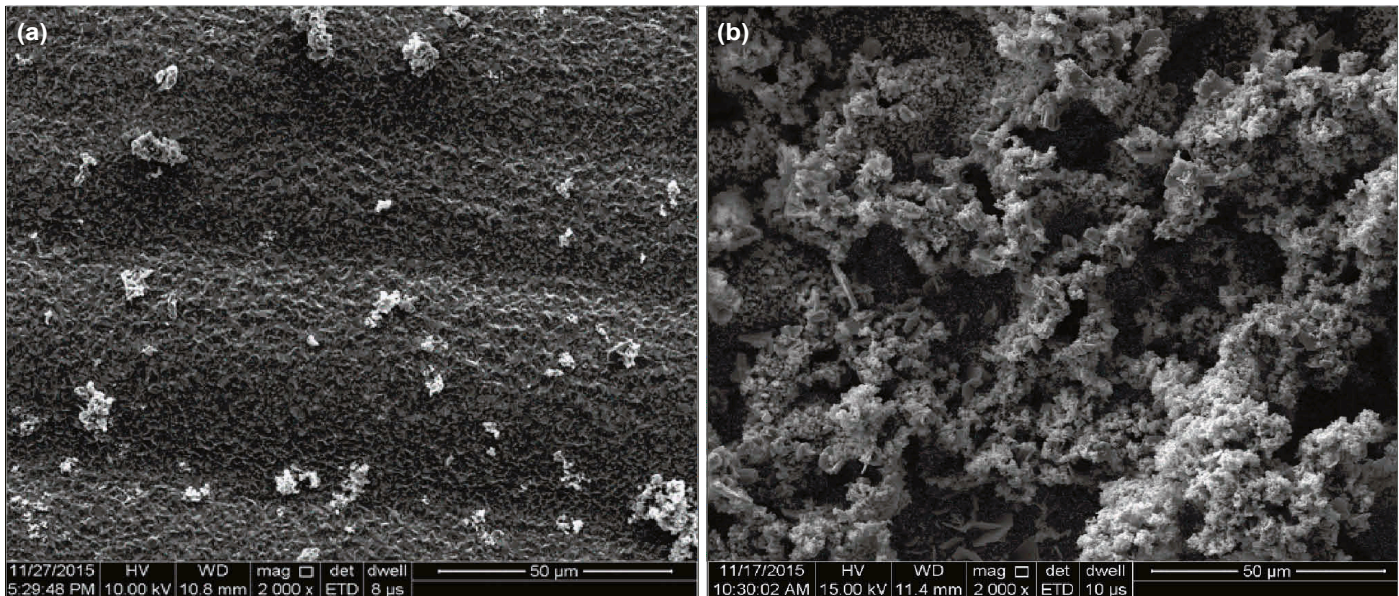


Fig. 1. Coated T95 steel (a), and uncoated T95 steel (b) after scaling test.

tools and other insertions into the tubing.

- Sufficiently adherent to survive during rapid depressurization from an initial high surrounding pressure.
- Applicable to the internal diameter of 40 ft long tubing.
- Capable of lasting 20+ years.

Electroless nickel plating (ENP) has several key advantages. Since it is an electroless process, i.e., it uses a chemical reductant rather than electric current, it can be deposited on the internal diameter of the tubing without the need for electrodes. It is a non-line of sight process that provides an even, conformal, uniform coating on all wetted surfaces. It also can be formulated to contain a level of phosphorus that imparts superior corrosion resistance in a sour gas environment. The phosphorus level can be tailored to provide a range of microstructures, ductilities and deposition rates. A key feature of ENP coatings is that particles of a second material can be introduced into the solution and embedded in the ENP coating during the coating process to impart desired properties such as wear, abrasion and erosion resistance.

### Scaling Test Conditions

The HPHT apparatus that we used for this program consisted of a rotating cage autoclave that was pressurized with H<sub>2</sub>S gas and immersed in brine. Figure 1b shows a SEM image of typical iron sulfide scale produced in the apparatus on uncoated T95 coupons. Figure 2a is a SEM image of the deposit consisting of two types of iron sulfide; crystalline hexagonal and amorphous mackinawite. Figure 2b is an EDS identification of the two types of iron sulfide scale — produced at 160 °C, 16,000 kPa — that formed on an uncoated coupon, with the coupon providing the sole source of iron for sulfide formation. Figure

3 shows the basis for the identification of these two forms by X-ray powder diffraction (XRD) analysis. Figure 4 is a cross-sectional micrograph of a typical coating after HPHT H<sub>2</sub>S exposure. Note that there is no evidence of attack or corrosion of the base T95 steel, but there is a thin layer of heazelwoodite

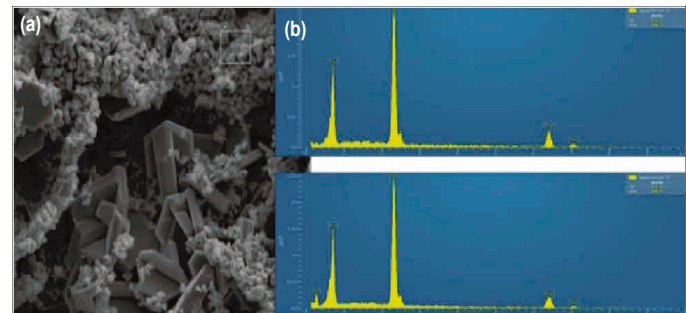


Fig. 2. (a) A SEM image of the deposit consisting of two types of iron sulfide; crystalline hexagonal and amorphous mackinawite, and (b) EDS identification of the two types of iron sulfide scale produced at 160 °C, 16,000 kPa on bare coupons, confirming the presence of iron and sulfur in the expected proportions.

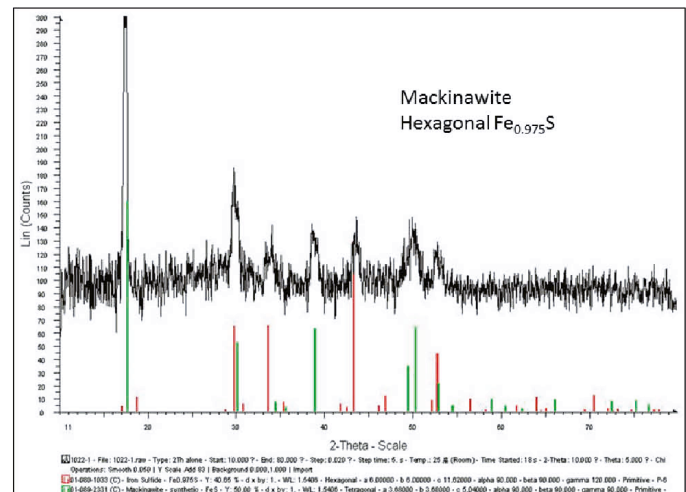


Fig. 3. XRD spectra confirming mackinawite and hexagonal forms of iron sulfide scale formed on the uncoated coupons treated in the HPHT autoclave.



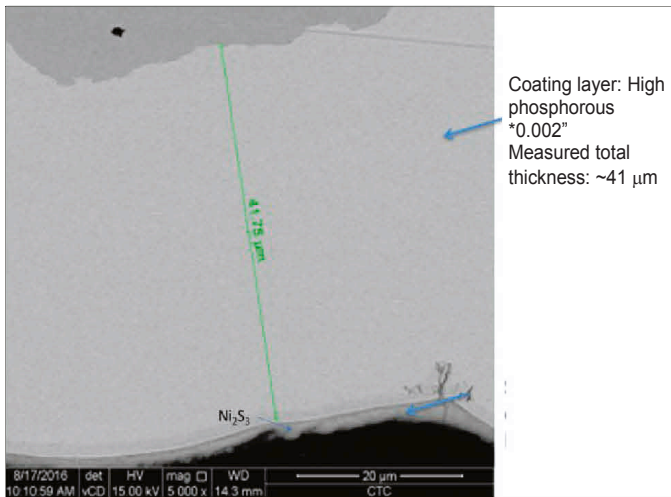


Fig. 4. A typical coating after HPHT  $H_2S$  exposure showing an absence of corrosion of the T95 substrate.

( $Ni_3S_2$ ) deposited on the top of the ENP coating surface.

Note that in each set of experiments, six coupons were included in the rotating cage, five with experimental coatings and one with no coating (bare T95). We have found that uncoated coupons always form copious quantities of FeS scale — as confirmed by EDS and XRD spectroscopy — and lose weight during exposure owing to the reaction of  $H_2S$  with the steel to form FeS, then some loss of adhesion and suspension of FeS and re-deposition on the autoclave walls and the five coated coupons to varying degrees, depending upon the affinities of FeS for the coating surfaces. We confirmed by SEM, EDS and XRD analysis of metallographic cross-sections of representative coatings that the FeS deposited on the coated coupons did not form from corrosion of the coupons. Our analyses detected only coating components, with no FeS embedded within or beneath the coatings.

Several criteria were considered to differentiate the candidate coatings. These were:

1. Mass gain caused by accumulation of FeS on the coated samples.
2. Macroscopic visual inspection of the samples after treatment to rank changes in color, uniformity of color, and integrity of the coating.
3. SEM examination of the morphologies of any accumulated scale.
4. EDS and XRD analyses of the treated surfaces to identify scalant species.

## Coating Screening Results

Figure 5 shows some representative coupons before and after HPHT  $H_2S$  exposure to the scaling conditions previously described. Note that uncoated coupons — included in each cage set of six — always formed a heavy, black iron sulfide deposit, while none of the coated samples formed the black

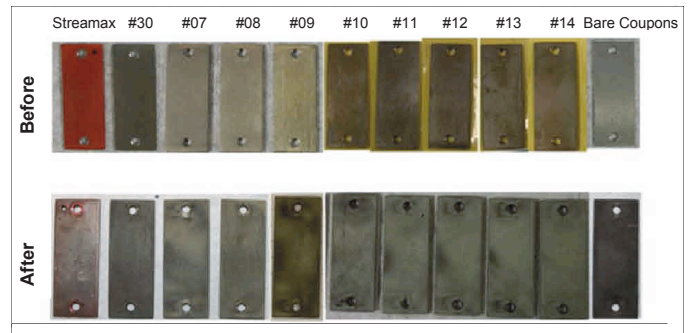


Fig. 5. Representative images of test coupons before and after HPHT  $H_2S$  autoclave exposure.

deposit. There were some minor, but macroscopically noticeable, changes in color, owing to the formation — to varying degrees — of  $Ni_3S_2$  upon HPHT reaction of  $H_2S$  with nickel in the coatings. Note that the formation of  $Ni_3S_2$  appears to be beneficial, owing to its fine microstructure, apparent tenacity and slow growth rate. In addition,  $Ni_3S_2$  has a very low affinity for attachment of FeS. Ultimate down selection to the best anti-scaling coating was based upon a combination of the lack of adhesion of scale to the surface, formation of a slow growing, microcrystalline, protective  $Ni_3S_2$  scale and good abrasive wear performance.

Figure 6 compares the hydrophobicity of the coatings prior to exposure to HPHT  $H_2S$ . The hydrophobicity is measured by the contact angle measurement using the ASTM D7334 procedure. The contact angle greater than  $90^\circ$  indicates a hydrophobic surface. In general, when the contact angle exceeds  $120^\circ$ , the surface is considered super hydrophobic. Most coatings are either hydrophobic or superhydrophobic<sup>4</sup>, which is expected to correlate with nonstick behavior with respect to water-soluble scale<sup>5</sup>.

## Selection of Highest Rank Coating Candidates for in-Depth Evaluation

Table 1 shows the results of the initial HPHT screening experiments on coated coupons. The coatings are ranked by color, with dark green being the most promising coatings, light green

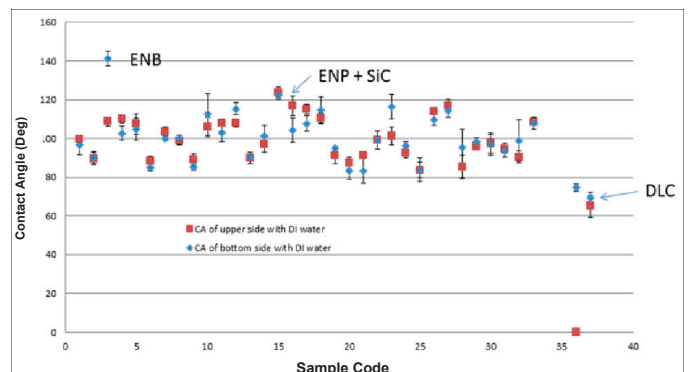


Fig. 6. Contact angle measured for all coatings (ASTM D7334: Standard Practice for Surface Wettability of Coatings, Substrates and Pigments by Advancing Contact Angle Measurement). DLC is a diamond-like carbon, included for comparison.



Coupon No.	Matrix	Underlayer	Particles	% Particles	Heat Treated?	% Mass Gain	FeS Scaling Resistance Score	Comments
1	ENP 25 $\mu$ m Hi-P	ENP 25 $\mu$ m Hi-P	No	0	No	Very Low	Good	Ni <sub>3</sub> S <sub>2</sub>
2	ENP 50 $\mu$ m Hi-P	ENP 25 $\mu$ m Hi-P	No	0	No	0.0147	Good	Ni <sub>3</sub> S <sub>2</sub>
3	Ni-B	ENP 25 $\mu$ m Hi-P	No	0	Yes	0.018	Good	Ni <sub>3</sub> S <sub>2</sub>
4	PTFE-HP	ENP 25 $\mu$ m Hi-P	PTFE	Med	Yes	0.0927	Very Good	Ni <sub>3</sub> S <sub>2</sub>
5	PTFE-HP	ENP 25 $\mu$ m Hi-P	PTFE	Med	No	0.051	Very Good	Ni <sub>3</sub> S <sub>2</sub>
6	ENP Low-P	ENP 25 $\mu$ m Hi-P	BN	Low	No	0.0613	Very Good	Ni <sub>3</sub> S <sub>2</sub>
7	ENP Low-P	ENP 25 $\mu$ m Hi-P	BN	Low	Yes	0.156	Good	Ni <sub>3</sub> S <sub>2</sub>
8	ENP Low-P	ENP 25 $\mu$ m Hi-P	Talc	Low	Yes	0.1084	Good	Ni <sub>3</sub> S <sub>2</sub>
9	ENP Low-P	ENP 25 $\mu$ m Hi-P	Talc	Low	No	0.0754	Good	Ni <sub>3</sub> S <sub>2</sub>
10	ENP Mid-P	ENP 25 $\mu$ m Hi-P	Diamond	Low	No	0.0312	Very Good	Ni <sub>3</sub> S <sub>2</sub>
11	ENP Mid-P	ENP 25 $\mu$ m Hi-P	Diamond	Low	Yes	0.0601	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
12	ENP Low-P	ENP 25 $\mu$ m Hi-P	Diamond	High	Yes	0.0563	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
13	ENP Low-P	ENP 25 $\mu$ m Hi-P	Diamond	High	No	0.0533	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
14	ENP Mid-P	ENP 25 $\mu$ m Hi-P	SiC	Med	No	0.0143	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub> spalled after 2X
15	ENP Mid-P	ENP 25 $\mu$ m Hi-P	SiC	Med	Yes	0.0121	Very Good	Ni <sub>3</sub> S <sub>2</sub>
16	Ni-B	None	No	0	No	0.0285	Very Good	No Ni <sub>3</sub> S <sub>2</sub>
17	ENP Hi-P	None	PTFE	Med	No	0.0744	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
18	ENP Hi-P	None	PTFE	Med	Yes	0.1549	Very Good	Ni <sub>3</sub> S <sub>2</sub>
19	ENP Low-P	None	BN	Low	Yes	0.1068	Very Good	Ni <sub>3</sub> S <sub>2</sub>
20	ENP Low-P	None	BN	Low	No	0.0669	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
21	ENP Low-P	None	Talc	Low	No	0.0688	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
22	ENP Low-P	None	Talc	Low	Yes	0.1027	Good	Ni <sub>3</sub> S <sub>2</sub>
23	ENP Mid-P	None	Diamond	Low	Yes	0.1086	Good	Ni <sub>3</sub> S <sub>2</sub>
24	ENP Mid-P	None	Diamond	Low	No	0.0252	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
25	ENP Low-P	None	Diamond	High	No	0.0258	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
26	ENP Low-P	None	Diamond	High	Yes	0.0395	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
27	ENP Mid-P	None	SiC	Med	Yes	0.0319	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>

28	ENP Mid-P	None	SiC	Med	No	0.0065	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>
29	ENP Mid-P	ENP 25 μm Mid-P	No	0	No	0.0099	Very Good	No Ni <sub>3</sub> S <sub>2</sub> detected
30	ENP Hi-P Black	None	PTFE	Med	No	0.0829	Good	Fine Ni <sub>3</sub> S <sub>2</sub>
31	ENP Low-P	None	BN	Low	Yes	—	Good	Fine Ni <sub>3</sub> S <sub>2</sub>
32	ENP Low-P Black	None	Diamond	High	No	0.0082	Very Good	Fine Ni <sub>3</sub> S <sub>2</sub>

Table 1. Results of the initial HPHT screening experiments on coated coupons

as promising coatings, and yellow, less promising. We assigned these rankings based upon several factors: % mass gain, as a measure of FeS deposition, SEM examination of FeS morphology on the surface, contact angle, and Ni<sub>3</sub>S<sub>2</sub> microstructure. The mass gain measurements included a combination of weight gain from Ni<sub>3</sub>S<sub>2</sub> growth and re-deposition onto coated coupons of iron sulfide dislodged from the uncoated coupon. Note that every coated coupon performed better than the uncoated control coupons, which turned black during HPHT exposure and lost mass, owing to the detachment of FeS corrosion products that redeposited to varying degrees on other coupons immersed in the same brine solution — clearly visible as isolated clusters previously shown in Fig. 1a.

The mass decrease of uncoated (control) coupons was typically 0.2% to 0.3%. The mass increase of the coated coupons provided a direct indication of the degree to which exogenously formed FeS adheres to the coating surfaces. Mass gains of the various coated coupons, exposed under identical conditions, can be compared directly as a way of ranking the coatings. Again, these mass gains represent a combination of the mass increase associated with Ni<sub>3</sub>S<sub>2</sub> formation and FeS accumulation.

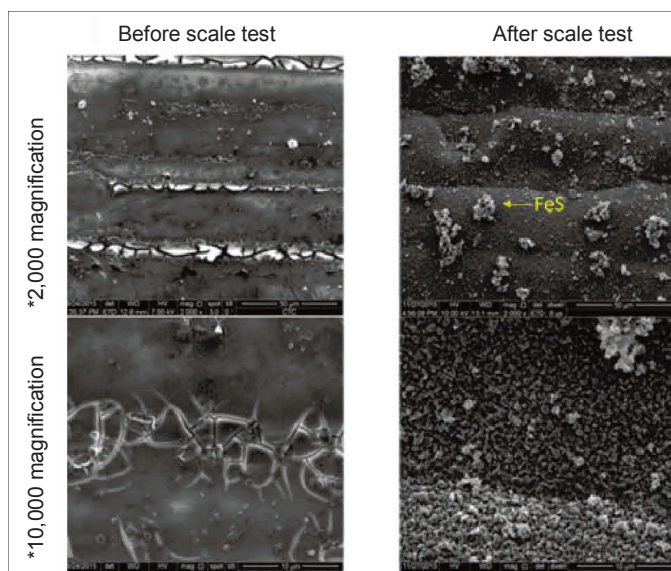


Fig. 7. SEM images of coating #1, high-P ENP, two 25 μm layers, before and after scaling test, showing a nanotextured surface, which has little affinity for mackinawite deposits.

These two sources of mass gain can be differentiated by closely comparing the SEM images of FeS deposits that are clearly visible (vide infra).

Figure 7 shows results for coating #1, a high phosphorus (Hi-P), electroless nickel coating that was 25 mm thick with a 25 mm underlayer of Hi-P ENP that contained no embedded particles and was not heat treated after coating. Shown are 2,000x and 10,000x magnification SEM images of coating #1 before and after the scaling test. Note that lighter colored deposits (re-deposition from uncoated T95 control) have been identified by XRD and EDS as mackinawite. Also, in the post-treatment images, the Ni<sub>3</sub>S<sub>2</sub> coating is a conformal, nanocrystalline coating with low affinity for FeS deposits. The FeS deposits clearly stand proud of the nanotextured Ni<sub>3</sub>S<sub>2</sub> coating, apparently minimizing contact between the FeS and the mackinawite deposit. This coating is a good example of one that forms a tenacious, microcrystalline Ni<sub>3</sub>S<sub>2</sub> scale that shows little affinity for FeS. The source of the FeS was the uncoated T95 coupon in the same rotating cage autoclave.

Figure 8 shows the results of the scaling test with coating #3 (electroless nickel boron with a Hi-P underlayer), which has a

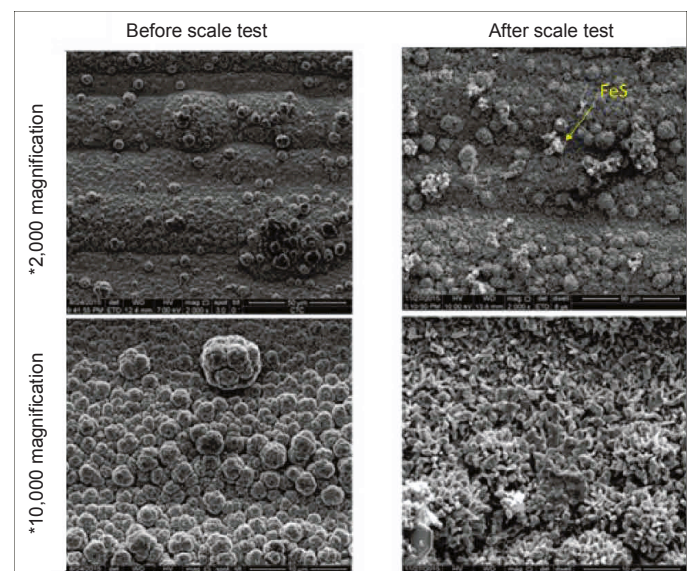


Fig. 8. SEM images of coating #3 (electroless nickel boron with a Hi-P underlayer) showing very low accumulation of externally generated FeS (lighter colored particles).

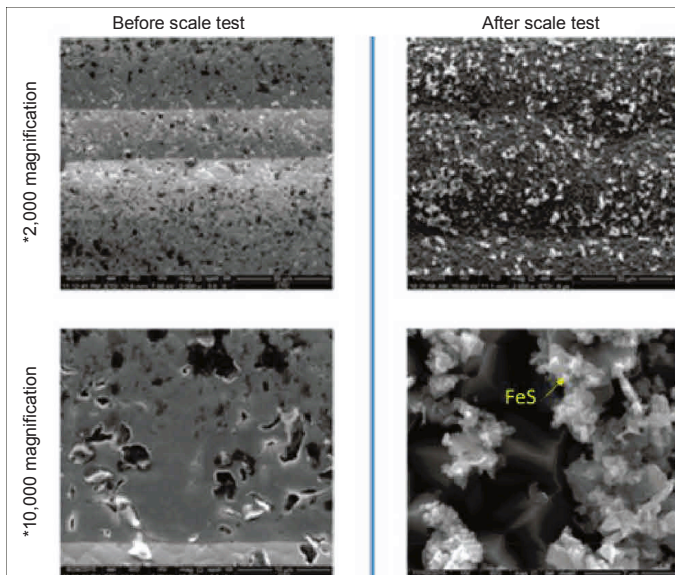


Fig. 9. SEM images of coating #8 (ENP, Low-P plus talc, heat treated) before and after exposure.

unique surface microstructure (microspheroids). This structure results in a very high contact angle,  $> 140^\circ$ , which appears to correlate with extremely low accumulation of externally generated FeS. Note the continuous coverage of the spheroids with tenacious nanocrystalline  $\text{Ni}_3\text{S}_2$ . This combination of microspheroids covered with nanocrystalline  $\text{Ni}_3\text{S}_2$  feature affords a superhydrophobic, nonstick surface. Although sample #1 shows an excellent anti-FeS deposition characteristic, the higher contact angle measured in sample #3 may deliver even better nonstick properties than sample #1. It is therefore worth further testing for its overall performance.

For comparison, coating #8 contains embedded talc particles in a Low-P ENP matrix, Fig. 9. The anti-stick properties of this coating are not as good as other coatings, as is evident from the larger sized clusters and relatively high concentration of deposited mackinawite particles.

### Extended Testing of Down Selected Coatings

Screening of the anti-scaling performance of 30+ coatings led to a down selection of six coatings for closer scrutiny. These coatings were those numbered 1, 2, 3, 15, 16, and 29 in Table 1. Coupons 2 and 3 were down selected because we were interested in looking more closely at the lack of heat treatment in coating #2, and the uniquely hydrophobic electroless nickel boron (ENB) coating. Additional, fresh coupons were coated and these were subjected to repeated HPHT scaling conditions. We focused on the evolution of  $\text{Ni}_3\text{S}_2$  crystal morphologies grown on the selected coatings to learn more about how the robustness of the scale might vary among the coatings. In addition to these HPHT scaling tests, the coatings, with and without  $\text{Ni}_3\text{S}_2$ , were subjected to explosive decompression testing (EDT) and abrasive loop wear testing.

Figure 10 shows SEM images of coating #3 after two

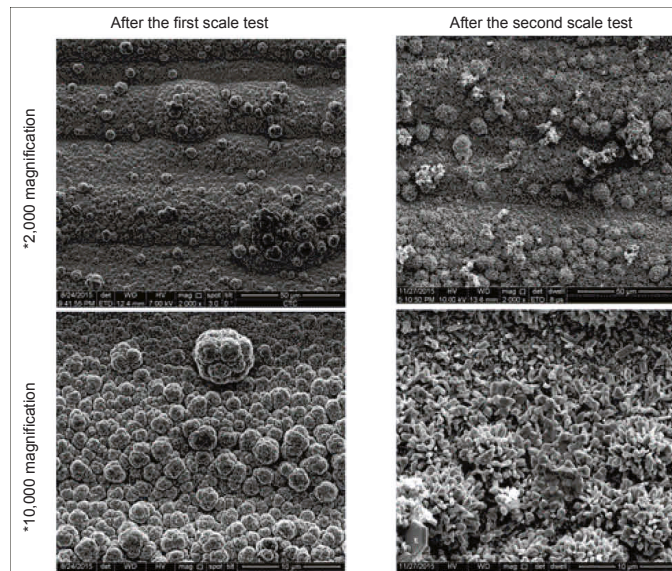


Fig. 10. SEM images of coating #3 (25  $\mu\text{m}$  high photos ENP underlayer with 25  $\mu\text{m}$  ENB overlayer, heat treated at 350  $^\circ\text{C}$ ) after one and two scale tests.

successive scaling tests. This coating is particularly anti-stick with respect to FeS. This observation is consistent with it being one of the more hydrophobic coatings, as was established in the contact angle measurements. We speculate that this enhanced hydrophobicity is related to the nano-nodular microstructure of the surface, which makes it difficult for FeS deposits to achieve sufficient contact with the surface to adhere. Note that nanocrystalline  $\text{Ni}_3\text{S}_2$  also grows on the ENB surface, but with a finer microstructure than what is observed with ENP. This  $\text{Ni}_3\text{S}_2$  deposit conforms nicely to the underlying nodular ENB surface, indicating that good adhesion can be expected.

### Coating Adhesion Testing

We expected all the down selected coatings to have strong adhesion to their T95 substrates based on previous experience with electroless nickel coatings, which are known to have a metallurgical bond between the coating and the substrate. This bonding is further promoted during heat treatment of the coating, which causes inter-diffusion of the coating and substrate, or diffusion bonding. This expectation was borne out in the HPHT  $\text{H}_2\text{S}$  exposures (vide supra), in which only one sample (#14), showed minor spallation of the  $\text{Ni}_3\text{S}_2$  layer after two cycles of exposure. The spalling of the  $\text{Ni}_3\text{S}_2$  layer could cause re-exposure of the metal to the  $\text{H}_2\text{S}$  downhole and therefore losing its corrosion and scale protection functionality. Nevertheless, we carried out adhesion testing by means of an EDT, which was devised and carried out by a local university in Shanghai. In addition to the adhesion of the applied coatings, we were even more curious about how tenacious the  $\text{Ni}_3\text{S}_2$  would be in the EDT. The EDT apparatus includes two liquid layers: (1) a bottom aqueous brine layer, and (2) a top layer that is a mixture of kerosene and toluene.

The experimental sequence of soaking in brine for 17 hours



at 2 MPa, heating for 3½ hours at 150 °C, boosting over 2 minutes to 56 MPa, holding at 150 °C at 56 MPa and sudden decompression in 2.3 seconds, was conducted on the down selected coatings. Note that five of the coupons (2, 3, 15, 29, and 31) had previously been exposed at HPHT in the scaling rig and had robust coatings of Ni<sub>3</sub>S<sub>2</sub> developed over multiple HPHT cycles in the rotating cage autoclave. After EDT, the coupons were examined by SEM and showed spallation of neither the original coating nor exposed coating having Ni<sub>3</sub>S<sub>2</sub> overlayers.

## CONCLUSIONS

A total of 32 different coatings have been tested in a rotating cage apparatus under HPHT H<sub>2</sub>S atmosphere. Six coupons were tested in each batch: five coated and one uncoated T95 steel coupon. All the coatings prevented corrosive formation of FeS scale, in contrast to the bare coupons, which scaled heavily with FeS. The uncoated coupons lost mass during treatment because the steel was consumed to form FeS scale and a fraction of the scale formed lost adhesion in the rapidly stirred autoclave, re-depositing, to varying degrees, on the other five coupons.

The electroless nickel phosphorus and ENB coatings formed a tenacious, microcrystalline to nanocrystalline Ni<sub>3</sub>S<sub>2</sub> scale that showed very low affinity for FeS adhesion. The iron sulfide and Ni<sub>3</sub>S<sub>2</sub> scales were characterized by EDS and XRD analyses. Contact angle measurements of the tested coatings indicated that most are hydrophobic, and some were superhydrophobic.

Based upon these initial screening results, we down selected a set of six coatings for further evaluation. We have also conducted explosive decompression as a gauge of coating adhesion, as well as abrasion testing to differentiate the down selected coatings. We will be looking at extended exposure times in high temperature sour gas wells to gauge the growth rate and surface morphology of the protective Ni<sub>3</sub>S<sub>2</sub> scale and evaluate the anti-scaling performance.

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## BIOGRAPHIES



**Dr. Lawrence Kool** joined the research staff at the GE Global Research Center in 1999 as a Senior Research Chemist, and now works as a Senior Inorganic Chemist. He has been responsible for the development and global implementation of

environmentally friendly chemical processes that are used in services technologies for gas turbine and aircraft engine components. Lawrence developed selective methods for removing environmental coatings from superalloy components while causing no damage to the underlying substrate.

He joined the GRC after spending four years at GE Superabrasives, where he developed and implemented — in Ohio and Ireland — environmentally benign chemical processes for manufacturing man-made diamonds from metallic catalysts.

Before joining GE, Lawrence was an Assistant Professor of Chemistry at Boston College, where he taught organic, inorganic and organometallic chemistry at both the undergraduate and graduate levels. His research group focused on the development of organoplatinum catalysts for the activation of C-H bonds, the catalytic partial oxidation of methane, and novel organometallic complexes of group IV transition metals. In addition to his work at GE, Lawrence was an Adjunct Professor of Chemistry at Siena College, where he taught inorganic chemistry.

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Lawrence received his B.S. degree in Chemistry from University of Michigan, Ann Arbor, MI, and his Ph.D. degree in Chemistry from University of Massachusetts, Amherst, MA.



**Dr. Qiliang “Luke” Wang** completed his postdoctoral training with Prof. Mason Tomson at the Brine Chemistry Consortium at Rice University, Houston, TX, where he explored mineral scales solubility and the kinetics of precipitation in oil

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Frank is an inventor and recipient of 23 granted U.S. patents, and he is the author of more than 40 Society of Petroleum Engineers (SPE) technical papers.

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coating development in heat exchangers, and anti-corrosion coating development for overhead pipelines in an oil refinery.

In 2006, she received her M.S. degree in Inorganic Chemistry and Materials from East China University of Science and Technology, Shanghai, China.

# Impact of Water Chemistry on Crude Oil-Brine-Rock Interfaces: A New Insight on Carbonate Wettability from Cryo-BIB-SEM

Dr. Ahmed Gmira, Dr. Dongkyu Cha, Dr. Sultan M. Al-Enezi, and Dr. Ali A. Yousef

## ABSTRACT

There is increasing evidence that SmartWater Flooding through the tuning of injection water chemistry and ionic composition, has a significant impact on the recovered oil, but the exact underlying mechanism by which this occurs is not well understood, and is supposed to be caused by complex interactions occurring at the fluid-fluid and fluid-rock interfaces. Most of the laboratory studies reported so far have been focused on characterization of an oil-brine-rock system and wettability alteration at microscale and macroscale using classic measurements, including contact angle, interfacial tension, nuclear magnetic resonance, zeta potential, and coreflooding.

Subsequently, those techniques depend strongly on rock heterogeneities, roughness and fluids distribution inside the pores. Therefore, a direct visualization at pore scale is needed to identify fluids distribution in situ, wettability state at pore scale, and wettability alteration by injection water composition tuning. We used broad ion beam (BIB) slope cutting in combination with a scanning electron microscope (SEM) under cryogenic conditions (cryo-BIB-SEM) to study oil-brine-rock interfaces. Direct imaging at the nanoscale level allows investigation of the porosity, in situ preserved fluids, and combined with energy dispersive X-ray spectroscopy (EDS), identify crude oil and brine distribution, and quantifies the wettability state by measuring the contact angle at pore level.

In this study, we compare carbonate rock samples that have been aged in crude oil and saturated with high and low ionic strength brines. In both samples, we investigate oil and brine distribution in the carbonate porous matrix. Results show that ion milling at cryogenic conditions allows the preparation of a large smooth cross section. The presence of pinning points contribute to the hydrocarbon adherence to the carbonate rock surface. SEM images indicate that in the presence of high ionic strength brine, large trapped oil patches have an elongated shape, following the rock surface morphology. Meanwhile, the oil droplets have a pseudo-spherical shape in the presence of low ionic strength brine, in addition to a distinct boundary between the oil and brine phase. Statistical analysis of the in situ contact angle and oil-brine-rock interface demonstrate the sensitivity of cryo-BIB-SEM approach to sub-micron scale wettability alteration caused by ionic strength variations.

## INTRODUCTION

Enhancing oil recovery in carbonate reservoirs by adjusting the ionic composition of the injected water has recently been widely investigated, and has proven its efficiency at laboratory and field scales. This ongoing extensive work is mainly driven by attractive economics during the implementation phase compared to other enhanced oil recovery techniques. There is a consensus that salinity and ionic formulation dramatically affect the oil-brine carbonate rock system, and wettability alteration is believed to be the main driving factor based on the abundant literature that describes the potential mechanisms involved in tuned water injection.

Findings from laboratory studies supported by some field tests have shown the favorable effects of diluted seawater on oil recovery in carbonate reservoirs<sup>1-4</sup>. Those fundamental studies pointed out the undesirable effect of monovalent ions ( $\text{Na}^+$  and  $\text{Cl}^-$ ) and the key role of multivalent ions ( $\text{Ca}^{2+}$ ,  $\text{Mg}^{2+}$ , and  $\text{SO}_4^{2-}$ ) along with connectivity enhancement between micropores and macropores caused by anhydrite dissolution<sup>5</sup>. Al Geer et al. (2016)<sup>6,7</sup> demonstrated the sensitivity of oil-brine interfacial tension and contact angle measurements to ionic composition in an attempt to decouple the effect of individual single ions. Al Otaibi and Yousef (2015)<sup>8</sup> described a zeta potential measurement on carbonates, the contribution of individual ions and SmartWater Flooding recipes in altering the rock surface charges, which is considered a key mechanism in rock wettability alteration.

The ionic composition of the injected water was also found responsible for affecting the rheological properties at the oil-brine interface, where ions valency, brine salinity, pH, and aging, contribute strongly to modify interfacial rheology and oil-brine interactions<sup>9,10</sup>. All the above studies pointed out that wettability alteration is strongly affecting the petrophysical properties at the centimeter to micrometer scale of a reservoir rock, such as the distribution of fluids, fluid saturation and fluid flow in porous media. The responsible mechanisms for this wettability alteration are not well understood at the pore scale. Therefore, nanometer scale exploration and direct sub-micron visualization are needed to investigate fluid-rock interfaces, contact lines, contact angles, and fluids distribution in the complex rock porosity matrix.



A novel way to visualize the distribution of oil and water in situ is to freeze the liquid-bearing rock, fracture it, and examine the exposed fracture surface with a scanning electron microscope (SEM); this process showed promising results in the early 1980s<sup>11, 12</sup>. Sutanto et al. (1990)<sup>13</sup> started investigating sandstone wettability alteration using cryogenic SEM (cryo-SEM) and identified oil and water locations inside the exposed pore space and illuminated the mechanisms of oil-water displacement in strongly water wet and mixed wet sandstones. Robin et al. (1995)<sup>14</sup> have shown, by using the analytical possibilities of cryo-SEM — topographic contrast, chemical contrast, and local elemental analysis by X-ray spectrometry — coupled with cryogenic conditions, that it is possible to differentiate brine from oil to visualize fluid distribution and local wettability.

Desbois et al. (2013)<sup>15</sup> implemented a broad ion beam (BIB) polisher into a SEM at cryogenic temperature, which allowed for the first time, the observation of pore and grain details of preserved fluid and reservoir rocks and in situ oil-water-rock contacts with nanometer resolution. Cha et al. (2015)<sup>16</sup> revealed for the first time the in situ distribution of mono and divalent ions around oil droplets and the effect of water salinity on the interfacial layer thickness using a cryo-high resolution transmission electron microscope and a cryo-SEM. Schmatz et al. (2015)<sup>17</sup> used a cryo-SEM extended by energy dispersive X-ray spectroscopy (EDS) chemical analysis to study reservoir sandstone, saturated with oil and brine. They observed the non-wetting oil phase separated from quartz surfaces by a thin brine film, but also direct contacts between oil and rock at pinning points. A recent feasibility study by Schmatz et al. (2017)<sup>18</sup> demonstrated the effect of variation of the flooding brine chemistry on the in situ fluid distribution in limestone at a nanometer scale. They have presented for the first time, a new generation of the cryo-BIB-SEM method, in which all preparation and analyzing steps are performed in separated devices that are connected in a closed cryogenic and vacuum workflow. Cryo-SEM, in combination with high resolution EDS mapping, allowed the quantification of oil droplet size, length of oil-rock interfaces, and a pseudo-2D contact angle in the presence of brine and oil.

In this article, we present a nanoscale approach to the wettability characterization of carbonate rocks using the cryo-BIB-SEM method in an attempt to identify phase distribution — oil and brine — and pores from the BIB-SEM images. We compare carbonate rock samples aged in crude oil and exposed to brines with high and low ionic strength to assess pore connectivity, oil and brine distribution, oil-rock contact areas, as well as an estimation of the 2D in situ contact angle directly inferred from the SEM images segmentation.

## METHODOLOGY

Carbonate rock samples were initially saturated with connate water (capillary imbibition) for 24 hours at room condition, and followed by an imbibition with crude oil in a desiccator at

	Brine 1	Brine 2
Na <sup>+</sup>	18,240	9,120
Mg <sup>2+</sup>	2,110	1,055
Ca <sup>2+</sup>	650	325
SO <sub>4</sub> <sup>2-</sup>	4,290	2,145
Cl <sup>-</sup>	32,200	16,100
HCO <sub>3</sub> <sup>-</sup>	120	60
pH	6.8	7.6
Total Dissolved Solids (ppm)	57,610	28,805

Table 1. Composition of the injected brines

low vacuum for a few days. After that, samples were aged in brine with two different ionic strengths for a few days. Table 1 lists the composition of both brines used.

The cryo-BIB-SEM procedure allows for the preparation of a representative high quality cross section (mm<sup>2</sup>), using a SEM, and an argon ion beam at cryogenic temperatures to study carbonate rock pores filled with crude oil and brine. Saturated rocks were plunged in frozen, and stirred in slushy nitrogen to minimize the formation of ice crystals, known as the Leidenfrost effect<sup>19</sup>. Frozen samples were attached in a sample holder with an ion milling resistant mask (titanium), and cut with a diamond blade saw under cryogenic conditions. Samples were then transferred from the nitrogen bath to a cryo-preparation chamber, using a transfer device, at cryogenic and vacuum conditions.

Frozen samples were sputter coated with a 10 nm thick layer of tungsten to prevent charging effects and transferred to the SEM sample cryo-stage, ready for BIB cutting at cryogenic conditions. The in situ BIB cross-sectioning unit is used as described by Desbois et al. (2013)<sup>15</sup>, three argon ion beams are channeled across the titanium mask to produce a sharp edged beam for a flat cross-sectioning surface. After BIB milling, the whole cross section was investigated using secondary electrons and back scattered electron (BSE) detectors. Simultaneously, EDS mappings were conducted for identification of the chemical elements and distribution across the carbonate rock porous matrix. Large areas of the rock's cross section were imaged, providing mosaic maps compiled from up to hundreds of single images at high resolution. Statistical analysis provides contact angle distribution, estimation of the rock matrix, oil and brine distribution and also morphological insights on the oil-brine-rock interface.

## RESULTS AND DISCUSSIONS

The cryo-BIB-SEM provides a large cross section area (few mm<sup>2</sup>), smooth and damage-free. High resolution imaging, combined with chemical mapping, allowed for the identification of existing phases (rock, oil and brine) and their distribution within the pore space. Imaging large areas of the cross section at high resolution required stitching systematically high



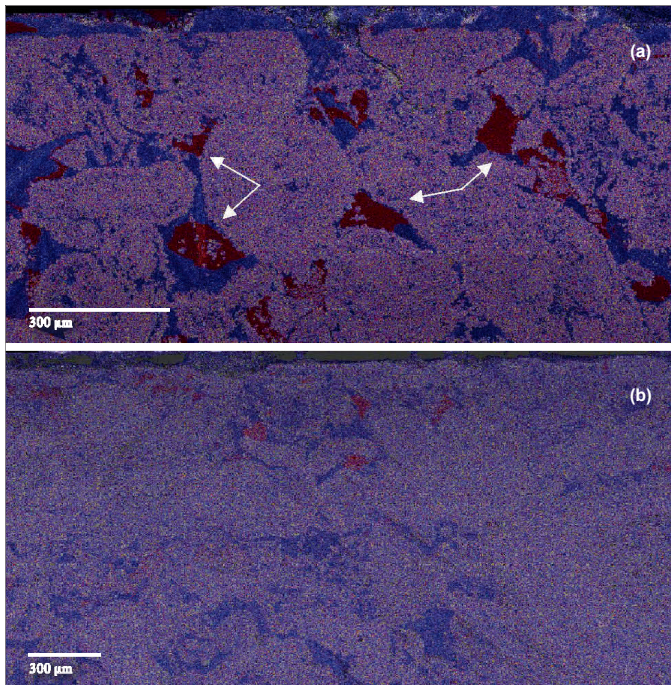


Fig. 1. Overview of the carbonate rock cross section overlaid with an EDS map with distributed elements of oil (red), brine (blue) and gray (carbonate): (a) Carbonate rock injected with oil and high ionic strength brine (300 nm/pixel resolution), and (b) Carbonate rock injected with oil and low ionic strength brine (600 nm/pixel resolution).

resolution single captured images to mosaic images. BSEs, secondary electrons, and EDS map mosaics were compiled from up to 100 single images (1,024 × 768 pixel, 20% overlap) captured simultaneously at 15 kX magnification with 20 nm pixel resolution. The locations for the high resolution mosaic maps were selected from cross section overviews, captured and compiled in a similar way as the high resolution mosaics, but at lower magnification.

Figures 1a and 1b are an EDS layered overview of the produced cross section of carbonate rock flooded with high and low ionic strength brine, respectively. Both samples showed a predominately water-wet to mixed wet behavior with a heterogeneous porous matrix. The observed dual porosity in carbonate rocks included numerous large pores of more than 100 μm in diameter as well as micropores. In both samples, a large proportion of oil was found in large pores (see arrows) in addition to oil in microscopic pores.

In the sample flooded with high ionic strength brine, a

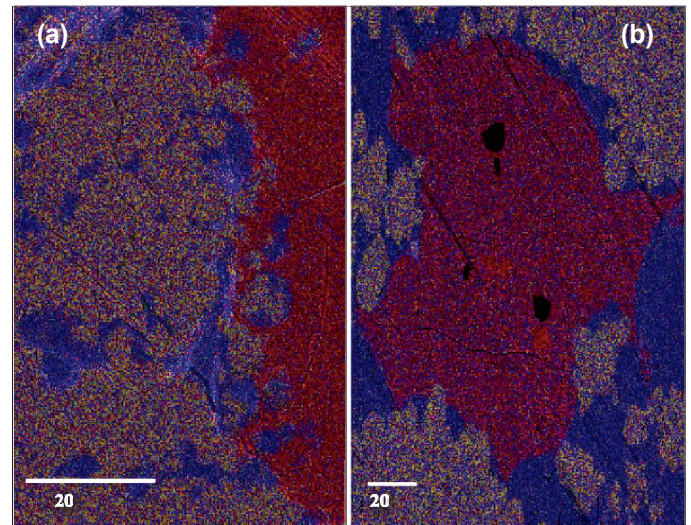


Fig. 2. High resolution SEM images (15 kX magnification, 20 nm pixel resolution) showing oil phase distribution in the carbonate rock's porous space: (a) Elongated films following the rock surface flooded with high ionic strength brine, and (b) Distinct boundaries between the oil droplets and the surrounding water phase seen trapped in the pores flooded with low ionic strength brine. Oil is red, brine is blue, and the carbonate rock is gray.

macroscopic distribution of oil phase is observed, where large oil patches are trapped in the large pores, forming elongated films that follows the rock surface morphology, Fig. 2a. Oil and brine phases also have the tendency to mix together within the pore space. In the sample flooded with low ionic strength brine, we observe distinct boundaries between the oil droplets and the surrounding water phase, Fig. 2b.

Figures 3a to 3d are examples of high resolution image stacks used for phase identification and automated segmentation. The images showed that most of the rock surface for this specific location is covered by brine. A large oil pocket was found trapped in the existing large porosity, in a nearly spherical shape with an average length and width of 50 μm at the longest axis. We also notice the visible pore contour (red arrows) and non-filled elongated pores illustrated by white arrows — at a width of 2 μm. Figure 3a shows the secondary electron signal as an example of a large, continuous, oil film trapped in carbonate pores with multiple contact points at the carbonate rock surface. The presence of pinning points and asperities at the carbonate's surface is favorable to oil adhesion as illustrated in the chemical map, Fig. 3b.

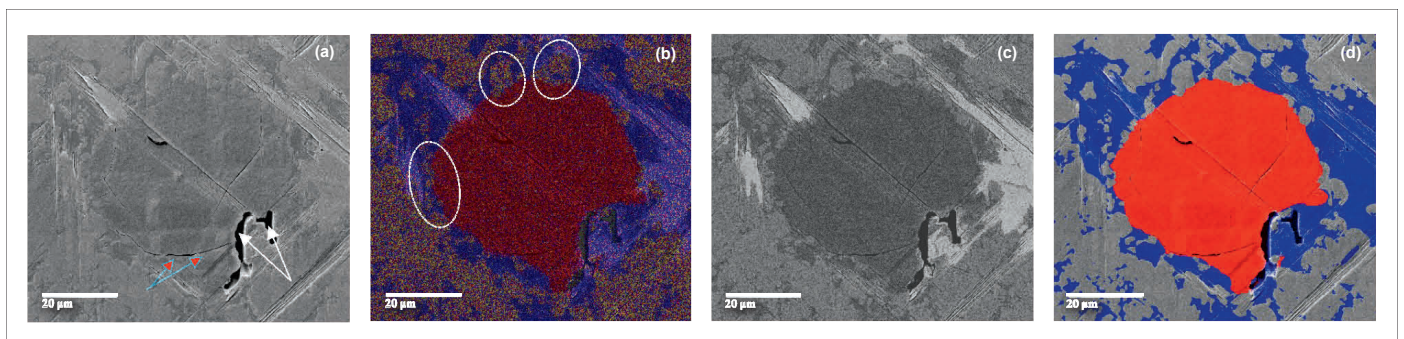


Fig. 3. Example of an image stack (20 nm pixel resolution) for image analysis workflow: (a) secondary electron signal, (b) EDS, (c) BSE, and (d) segmentation.

The segmentation algorithms combine information from the BSE images with input from the typically lower resolved EDS maps and produce phase maps of the mosaics at the resolution of the BSE images, Fig. 3c. The segmented images allowed for statistical analysis of the spatial phase distribution and phase interaction, such as the pinning points and the oil-brine-rock contact angle. Figure 3d is an automated segmentation of the captured SEM image overlaid with EDS distribution for a selected location. The focus was on selecting locations showing interesting morphological features and the presence of all three phases: oil, brine, and rock.

The oil-brine-rock contact angle is derived from a fitted line at the contact of oil with the carbonate rock surface and oil with brine, respectively, Fig. 4. The in situ contact angle is defined as the angle enclosed by the oil-brine and rock-brine interface, and was measured at all triple points for both samples flooded with low and high ionic strength brine to evaluate the potential of a cryo-BIB-SEM workflow and image analysis in sensing in situ carbonate rock wettability and potential alteration caused by various parameters of the injected brine, including ionic strength. Results were filtered manually for unreliable measurements, usually caused by strong interface curvature.

The contact angle measurement, Fig. 5, showed a smaller contact angle — mean contact angle of 56°, median at 47°, count was 518 — for the carbonate sample flooded with low ionic strength brine, compared to the contact angle determined for the carbonate sample flooded with high ionic strength brine — mean contact angle 71°, median at 66°, count was 1,616. The contact angle histograms show a higher proportion of the low contact angle values for the low ionic strength brine while the sample with higher ionic strength shows a higher proportion of the high contact angle values.

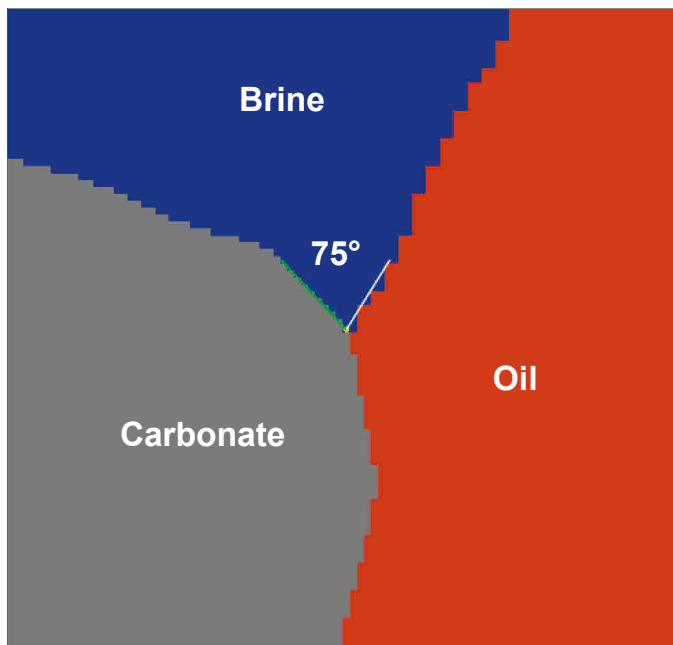


Fig. 4. An example of the segmented three part contact line location that allows the estimation of an in situ contact angle between the carbonate rock surface, oil, and brine.

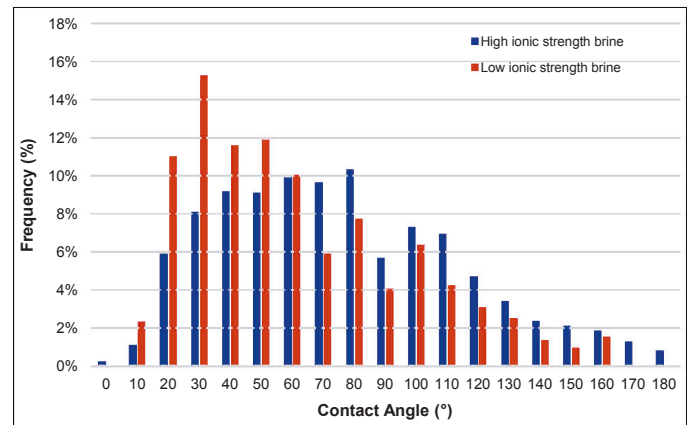


Fig. 5. Frequency of the contact angle measured from an automated SEM image analysis for carbonate rocks injected with high and low ionic strength brine.

Both carbonate rock samples were highly heterogeneous with the presence of dual porosity, large pores and micrometric pores. The relative phase distribution was determined using segmented phases derived from the overview mosaic images previously shown in Fig. 1. Figure 6a shows the sample flooded with high ionic strength brine, which contained 85% area calcium carbonate, 10% area brine, and 4% area oil. Figure 6b shows the sample flooded with low ionic strength brine, which contained 77% area calcium carbonate, 23% area brine, and 1% area oil. The difference in the total pore space measured in the selected areas for both samples, with 14% in the sample with high ionic strength brine, and 24% in the sample with low ionic strength brine, shows that the cross section area, which was selected for high resolution imaging, was not completely representative for the rock, due to the pronounced heterogeneity.

We have conducted a cryo-BIB-SEM study for a direct characterization of the carbonate rock's porosity, fluids identification and distribution at sub-micron scale. Surface preparation using BIB milling under cryogenic conditions allowed for a large surface area, smooth and damage-free. Overview mosaics were obtained by stitching up to 100 single images to cover the whole cross section. Two carbonate rock samples were exposed to both crude oil and brines at low and high ionic strengths to characterize the carbonate's wettability changes with the cryo-BIB-SEM workflow. In both samples, we have observed heterogeneous porosity ranging from micropores to large macropores

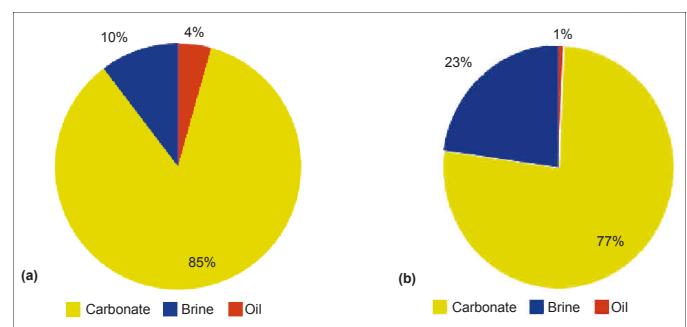


Fig. 6. Relative phase distribution in a carbonate rock sample flooded with (a) high ionic strength brine, and (b) low ionic strength brine, where calcium carbonate, brine, and oil are colored yellow, blue, and red, respectively.



with more than 100  $\mu\text{m}$  in length. The experimental protocol aimed to prepare samples with a mixed wet initial state to study the cryo-BIB-SEM protocol to the variation in injected brine ionic strength. The two selected cross sections were not representative of the carbonate rock due to the heterogeneity in place, differences in estimated porosity and oil distribution.

The saturation protocol followed for the sample's preparation consisted of capillary imbibition of brine, then oil imbibition at low vacuum pressure, and finally a spontaneous flood with brine at low and high ionic strength brines. It is likely that the saturation protocol did not affect the small pores as oil imbibition will require a higher entry pressure. Subsequently, the large number of selected locations gives a fair statistical analysis and an idea about the oil-brine-rock interfaces and chemical variations that occur at the nanoscale level. At high ionic strength, a macroscopic distribution of large oil patches trapped in large pores was observed in an elongated shape that follows the rock surface curvature. Oil and brine phases were also observed to mix together while there are distinct boundaries between the oil and brine phases in the rock sample flooded with low ionic strength brine. In situ contact angles were estimated using an automated images segmentation.

As previously shown in Fig. 5, the contact angles of oil-brine-rock with low ionic strength brine were lower than those estimated for the carbonate rock sample flooded with high ionic strength brine. This indicates a higher water-wet character when using low ionic strength brine in agreement with previous studies<sup>3, 20</sup>. Oil droplets were also observed to have an affinity for asperities, considered as pinning points that contribute to oil adherence at the carbonate rock surface.

The contact angle estimation from image segmentation could be influenced by various parameters causing an overestimation of the contact angle due to the size of image pixels, oil droplets, and pores. A post-filtration was applied manually to all the selected locations to exclude the large curvatures and pinning points at the interface that contribute to the contact angle overestimation. Segmentation of images provided a statistical analysis of the in situ contact angle and results show a relatively less oil wet rock surface for the sample flooded with low ionic strength brine compared to the one flooded with high ionic strength brine.

At this stage, the presented feasibility study shows the potential of cryo-BIB to prepare a suitable surface area for high resolution imaging and SEM imaging combined with automated segmentation could potentially provide new insights of the oil-brine-rock interface at nano and sub-micron scale, identify trapped phases inside the porous matrix, and quantify the distribution of the different phases. The cryo-BIB-SEM method also allows a statistical evaluation of the 2D contact angle and the oil-brine-rock interfaces.

## CONCLUSIONS

We presented a cryo-BIB-SEM feasibility study to investigate the oil-brine-rock interface at a sub-micron scale and investigate

the sensitivity toward variations of the injected brine ionic strength. The following conclusions can be drawn based on the initial imaging analysis:

- Ion milling at cryogenic conditions allows the preparation of a smooth rock cross section, free of damages, thereby providing access to the trapped fluids in carbonate porosity.
- Existing dual porosity influences the oil and brine distribution in the porous matrix as a large amount of oil droplets were located in the largest pores in addition to a small portion of oil located in microporosity.
- Tendency of oil to adhere to the carbonate rock surface is emphasized by the presence of pinning points.
- Differences of oil and brine phase distribution were observed in low and high ionic strength brines.
- A 2D contact angle statistical analysis shows the sensitivity of the cryo-BIB-SEM technique to sub-micron scale chemical variations at the oil-brine-rock interface.

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## BIOGRAPHIES



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Ali is currently leading more than 50 EOR scientists, engineers, and technicians. Those EOR researchers are dedicated to development of various EOR processes, including SmartWater Flooding, carbon dioxide and chemical EOR technologies, as well as other novel processes with the clear target of meeting Saudi Aramco's objective. He was the impetus for Saudi Aramco's SmartWater Flooding revolution: a patented award-winning technology. In 2011, this technology won the ADIPEC Award for Innovation and Technology. Its implementation is the industry's first multi-well pilot of SmartWater Flooding.

In 2016, Ali was the recipient of the prestigious Society of Petroleum Engineers (SPE) IOR Pioneer Award for his pioneering contributions made to the advancement of recovery technologies in the field of IOR/EOR. He also received the very prestigious award of The Custodian of the Two Holy Mosques Prize for Inventors and Talents in 2017.

Ali has written over 60 technical papers and reports and has more than eight granted patents. He is currently an active member of SPE and has chaired several SPE workshops and forums, helped organize several petroleum engineering related conferences, and taught courses on IOR/EOR and waterflooding.

Ali received his B.S. degree in Chemical Engineering from King Fahd University of Petroleum and Minerals (KFUPM), Dhahran, Saudi Arabia, and his M.S. and Ph.D. degrees, both in Petroleum Engineering, from the University of Texas at Austin, Austin, TX.



# Determining Effective Mixture Viscosities in Oil-Water Flows for Downhole Oil Field Operations

Dr. Chidrim E. Ejim and Dr. Jinjiang Xiao

## ABSTRACT

In downhole oil field operations that involve pumping oil and water, information on mixture viscosity is important to further understand the performance of the downhole production equipment. This study presents a method for determining the effective absolute viscosity of oil-water mixtures by applying fluid mechanics' first principles to data representative of downhole production measurements. Knowledge of effective absolute viscosity in upstream and downstream oil field operations is essential to extend equipment life and optimize production operations.

A 7" 26 lb/ft pipe and a 3½" 9.20 lb/ft pipe, typically used as casing and tubing, respectively, in field operations were installed in an oil-water flow loop. The volume flow rates during the tests varied from 2,000 barrels per day (bpd) to 12,000 bpd, representative of target field production rates. The tests were performed at different inclinations to represent varying well deviation angles. For each oil and water flow rate, the corresponding pressure drop measurements across a fully developed section of the flow were measured. Using fundamental hydraulic relationships, the effective absolute viscosities of the oil-water mixtures were determined.

The results showed that as water cut varied, the effective mixture absolute viscosity also changed, and in some cases this was substantial. The highest effective absolute viscosity of 500 centipoise (cP) occurred at the mixture flow rate corresponding to 2,000 bpd and 40% water cut. In general, mixture flow rates of 2,000 bpd and water cuts between 40% and 60% consistently showed the highest effective absolute mixture viscosities, which varied between 160 cP to 500 cP. For water cuts outside the 40% to 60% range, the effective absolute viscosities were about 120 cP and less. These results indicate that the effective mixture viscosity is about two and close to three orders of magnitude of pure oil and pure water viscosities, respectively. The results also suggest that certain flow rates and water cuts significantly affect the viscosity of oil-water flows.

Other results showed that for a given mixture flow rate, the effective viscosities were about the same order of magnitude for the different inclinations. This indicates that the well deviation angle has minimal or negligible influence on the effective mixture's absolute viscosity. From the combined results

the technique used in this study provides additional insight to ascertain the effective viscosity of oil-water mixtures during field operations. This study highlights the importance of having the capability to determine the effective absolute viscosity of oil-water mixtures during oil field production operations. The methodology is simple and has the advantage of easy integration into a flow measurement system. Such systems are beneficial tools for reservoir engineers, production engineers and field operators in general, for making appropriate production modifications during operations, to increase asset life and maximize hydrocarbon recovery.

## INTRODUCTION

Oil and water are some of the reservoir fluids produced from downhole to the surface in many oil and gas field operations. In some cases, the oil and water may be separated downhole with only the oil produced to the surface and the water re-injected back into the reservoir. Subsequently, either due to capacity handling, or complex completion layout, not all operators utilize downhole oil-water separators. Instead, during production, the oil and water have to be produced to the surface as a liquid-liquid mixture, where the oil and water are either separated at the well site or transported to a processing facility further downstream, where the separation process occurs.

Electric submersible pumps (ESPs) are a type of artificial lift method used in the oil and gas industry to either lift reservoir fluids from dead wells, or boost production from naturally flowing wells. ESPs operate favorably when pumping pure liquids, e.g., water or oil, or liquid with very low gas content. Depending on the proportions of oil and water, or water cut, from the reservoir, the viscosity of oil-water mixtures can vary substantially. A phenomenon known as phase inversion occurs when the mixture flow changes from a continuous water to continuous oil, or vice versa. At the point of phase inversion, the viscosity of the mixture is significantly higher than the viscosity of pure oil or pure water.

Under such flow conditions, the performance of the ESP, such as the head developed by the pump, degrades considerably and any attempt to increase the flow rate or head by adjusting motor conditions can lead to motor overload and

potential failure of the ESP system. Current ESP installations are equipped with downhole sensors that can measure parameters such as intake and discharge pressure, intake and discharge temperature, motor vibration, motor oil and winding temperature, as well as motor current. Estimating the oil-water mixture viscosity downhole is desirable to give the operator additional information on the downhole flow condition the ESP is operating in, and subsequently setup a series of remedial or operational actions to mitigate against potential failure of the ESP system, thereby increasing operational efficiency.

Previous studies on viscosities of solutions are present in the literature, which show relationships between the continuous and dispersed phases within the mixture<sup>1</sup>. Other studies have involved experimental work on oil-water flows in horizontal pipelines, in which the ultimate objective was to develop a viscosity prediction model for this type of flow<sup>2</sup>. Additional studies on the effect of mixing intensity on oil-water mixture viscosities at different temperatures have also been performed<sup>3</sup>, in which the inversion point was observed to occur at about 35% water cut. Some studies have been undertaken on predicting viscosities in oil-water mixtures using an intelligent model<sup>4</sup>. The researchers reported a very good fit of the model to the laboratory data. Yet some other work was done by measuring oil-water viscosity variation with water cut at atmospheric pressure under different temperatures and shear rates, where a modified viscosity correlation was developed<sup>5</sup>.

Li et al. (2016)<sup>5</sup> observed an inversion point at 20% water cut. In the above studies, given the various potential water cuts that phase inversion can occur, it is evident that a single model to determine the effective viscosity of oil and water mixtures may not be fully transferable to all oil-water systems due to the complex flow regimes inherent in these mixtures. A method to determine the effective viscosity of oil-water mixtures downhole has to be on a case-by-case basis. A direct measurement method will be very beneficial to field operators as it provides production viscosity information representative of downhole fluid characteristics from a specific well.

Such a method is discussed in this work, which also looks into the effect of oil-water mixture flow rates on the effective oil-water mixture viscosity. The work also shows the effect of flow conduit inclination angle on the effective oil-water mixture viscosity. The information from such direct measurements can be used by the operator to make proper adjustments to field equipment during production operations to further extend the life of the equipment and also improve the overall operating economics of the field asset.

## BACKGROUND THEORY

Viscosity estimation requires an understanding of the pressure drop of the flow through pipes or annular conduits. From elementary fluid mechanics, it can be shown from the first

principle that the total pressure drop in a fluid flowing in a conduit can be given as:

$$\Delta p_t = \rho g L \sin \theta + \frac{f L \rho V^2}{D_h} \quad (1)$$

In Eqn. 1, the first term on the right-hand side represents the pressure drop due to gravitational acceleration, whereas the second term is the pressure drop due to friction and expressed as the Darcy-Weisbach equation. The parameters in Eqn. 1 are defined as:  $\Delta p_t$  = total pressure drop,  $\rho$  = fluid density,  $g$  = acceleration due to gravity,  $L$  = distance across which the pressure drop occurred,  $\theta$  = inclination angle of the conduit from the horizontal,  $f$  = friction factor,  $V$  = average fluid velocity across the conduit, and  $D_h$  = hydraulic diameter of the conduit.

For a general case of flow through conduits with internal and outer diameters of  $D_i$  and  $D_o$ , respectively, and volume flow rate,  $Q$ , the velocity,  $V = \frac{Q}{0.25\pi(D_o^2 - D_i^2)}$ , and  $D_h = D_o - D_i$ .

In fluid literature<sup>6</sup>, the friction factor is typically expressed by the Colebrook-White equation, as shown in Eqns. 2 and 3:

$$\frac{1}{\sqrt{f}} = -0.86 \ln \left( \frac{\varepsilon/D_h}{3.7} + \frac{2.51}{Re\sqrt{f}} \right) \quad (2)$$

$$Re = \frac{4\rho Q}{\pi\mu D_h} \quad (3)$$

where,  $\varepsilon$  is the absolute roughness of the wetted pipe wall,  $Re$  is the Reynolds Number, and  $\mu$  is the absolute viscosity of the fluid.

To obtain the absolute viscosity using Eqns. 2 and 3 requires knowledge of the friction factor,  $f$ . The  $f$  equation is of an implicit form, and therefore, the  $f$  cannot be solved for explicitly; however, Asker et al. (2014)<sup>7</sup> reviewed a number of  $f$  relationships for flow in pipes. They found that one of the correlations with the best result is that by Serghides (1984)<sup>8</sup>, which is valid for all  $Re$  and relative roughness ( $\varepsilon/D_h$ ), and has a percent error of 10<sup>-4</sup>%. The Serghides equation is shown in Eqns. 4 to 7:

$$\frac{1}{\sqrt{f}} = A - \frac{(B-A)^2}{C-2B+A} \quad (4)$$

where:

$$A = -2.0 \log_{10} \left( \frac{\varepsilon/D_h}{3.7} + \frac{12}{Re} \right) \quad (5)$$

$$B = -2.0 \log_{10} \left( \frac{\varepsilon/D_h}{3.7} + \frac{2.51A}{Re} \right) \quad (6)$$

$$C = -2.0 \log_{10} \left( \frac{\varepsilon/D_h}{3.7} + \frac{2.51B}{Re} \right) \quad (7)$$

With the  $f$  expression obtained from Eqns. 4 to 7, and substituting this into Eqn. 1, together with all the other variables known during testing, the absolute viscosity of the fluid can be determined.

These equations can be extended to systems involving the flow of oil and water to estimate the absolute viscosity of the

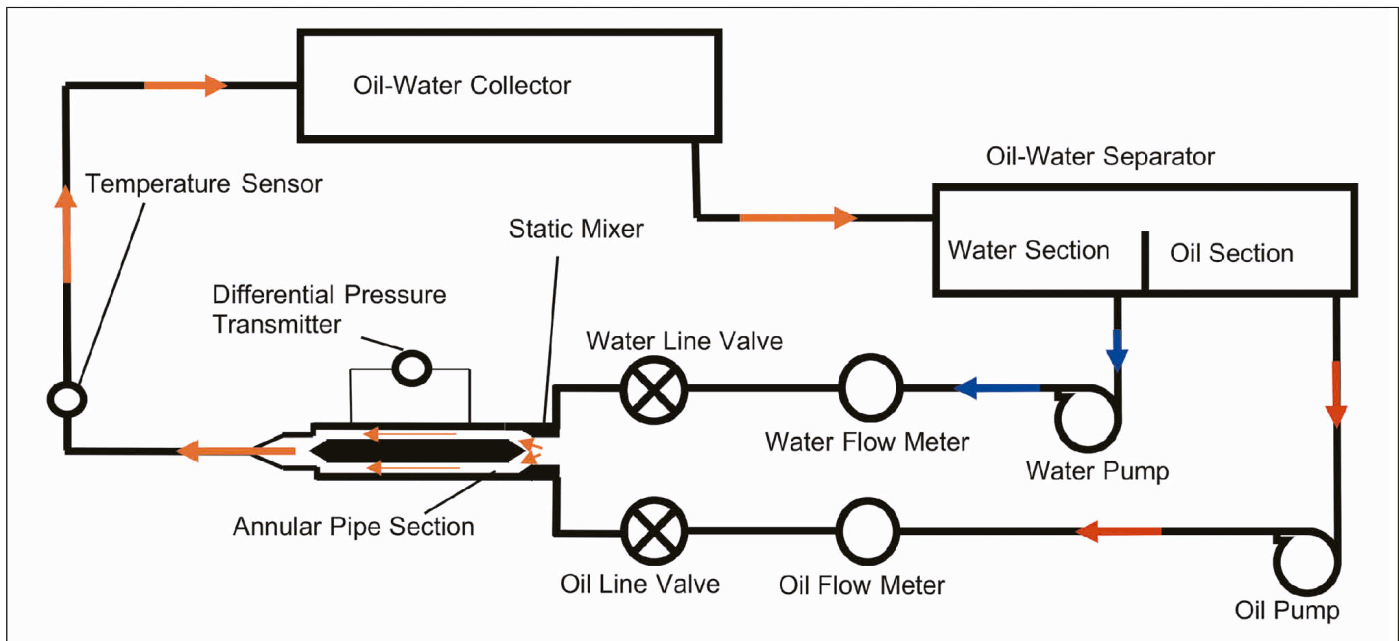


Fig. 1. A schematic of the test layout used to estimate the oil-water mixture viscosity.

oil-water mixture. In such systems, from mass balance and assuming a homogeneous mixture, the fluid parameters in Eqn. 3 can be represented by Eqns. 8 to 10:

$$Q_m = Q_o + Q_w \quad (8)$$

$$\rho_m = \alpha_o \rho_o + \alpha_w \rho_w \quad (9)$$

$$\rho_m = \frac{Q_o}{Q_w + Q_o} \rho_o + \frac{Q_w}{Q_w + Q_o} \rho_w \quad (10)$$

where  $Q_m$  = mixture flow rate,  $Q_o$  = oil flow rate,  $Q_w$  = water flow rate,  $\rho_m$  = mixture density,  $\rho_o$  = oil density,  $\rho_w$  = water density,  $\alpha_o$  = oil cut, and  $\alpha_w$  = water cut.

## EXPERIMENTAL LAYOUT AND PROCEDURE

Figure 1 is a schematic of the test layout used to estimate the oil-water mixture viscosity. Mineral oil (EXXSOL D80) and water were used as the test fluids. The fluids are held in separate sections of an oil-water separator, with each fluid supplied into the system by their respective pumps. Flow control and measurement were accomplished using the valves and turbine flow meters, respectively, on each line. Flows from the oil and water lines enter a static mixer section, where the fluids are properly mixed before the mixture enters the annular pipe section. The annular section is comprised of a smaller casing within a larger casing size, representative of a typical annulus formed between a casing internal diameter and an equipment outer diameter in a wellbore.

Pressure drop measurements were made by a differential pressure transmitter from pressure taps within the straight section of the annular pipe section. The taps were located to allow the oil-water mixture to have a fully developed flow

within the measurement section downstream of the static mixer. The annular section is mounted on an adjustable frame that can be tilted to various inclination angles. Further downstream after the fluid pressure drop measurements, the oil-water mixture flows through a return line, where the mixture temperature is measured using a temperature sensor. The oil-water mixture flow rate through the test loop is assumed isothermal because of the large liquid reservoir volume used during the test. The oil-water mixture flows into a collector tank and then into an oil-water separator tank, where the fluids are separated by gravity and the flow process is repeated within the closed loop flow system. Table 1 shows the fluid

	Density (lb/ft <sup>3</sup> )	Absolute Viscosity (cP)	Flow Range (bpd)
EXXSOL D80 Oil	48.1	1.328	0 to 12,000
Water	61.9	0.668	0 to 12,000

Table 1. Oil and water fluid properties at 102 °F

Description	Dimensions
Smaller diameter of annular section (D <sub>i</sub> )	3.50"
Larger diameter of annular section (D <sub>o</sub> )	6.28"
Distance between pressure taps (L)	38.98"
Absolute pipe roughness for commercial steel pipe (ε)	1.5 × 10 <sup>-4</sup> * ft
Annular pipe inclination angles from horizontal (θ)	0°, 40°, 60°, 90°

\*From Flowserve, 2010.

Table 2. Additional test information<sup>9</sup>



properties at the average test temperature of 102 °F, and Table 2 presents other test information.

In performing the tests, the system was allowed to stabilize to the required flow conditions before the required test data were acquired. For each inclination angle of the annular test section and a specific water cut, about four to five data points were collected for varying flow rates of water and oil. The total flow rates tested were 2,000 barrels per day (bpd), 4,000 bpd, 6,000 bpd, 8,000 bpd, 10,000 bpd, and 12,000 bpd, with corresponding water cuts of 0%, 20%, 40%, 60%, 80%, and 100%, respectively. In total, about 142 data points were collected. Subsequently, all the test variables were substituted into Eqns. 1 to 10, and the effective absolute viscosities of the respective oil-water mixtures were subsequently computed.

## RESULTS

For brevity, the number of plots in this section have been selected to demonstrate the trends of absolute viscosity variation for the different parameters studied. The results have been divided to show the variation of absolute viscosity with water cut at a given inclination angle and varying total mixture flow rates and the variation of absolute viscosity with water cut at a given mixture flow rate and different inclination angles.

### Effect of Total Flow Rate

Figure 2 shows the variation of effective mixture absolute viscosity with water cut for total flow rates of 2,000 bpd to 12,000 bpd in increments of 2,000 bpd, for a 0° inclination angle — horizontal orientation of the annular test section. From the plot, for each of the total flow rates studied during the test, the general trend is that the effective mixture viscosity increases from 0% water cut with considerably high viscosity in the 40% to 60% water cut range, and subsequently decreases significantly as the water cut approaches 100%. These trends in oil-water mixture viscosity variation are similar to observations that have been made in open literature cited earlier. One of the consequences of such high viscosities has been attributed to the complex flow structure between oil and water, which, at certain water cuts, causes a phase inversion from a water continuous mixture to an oil continuous mixture or vice versa.

The highest effective mixture viscosity in Fig. 2 is about 400 cP, which occurs at 40% water cut and a mixture flow rate of 2,000 bpd. It is also observed that as the mixture flow rate is increased to 4,000 bpd, the maximum effective absolute viscosity decreased to about 80 cP, which still occurs at 40% water cut. As the mixture flow rate is increased up to 12,000 bpd, the maximum effective viscosity continues to decrease further, such that there is a negligible difference in the mixture absolute viscosity. At these high flow rates and 40% water cut, the maximum viscosity decreased to about 16 cP.

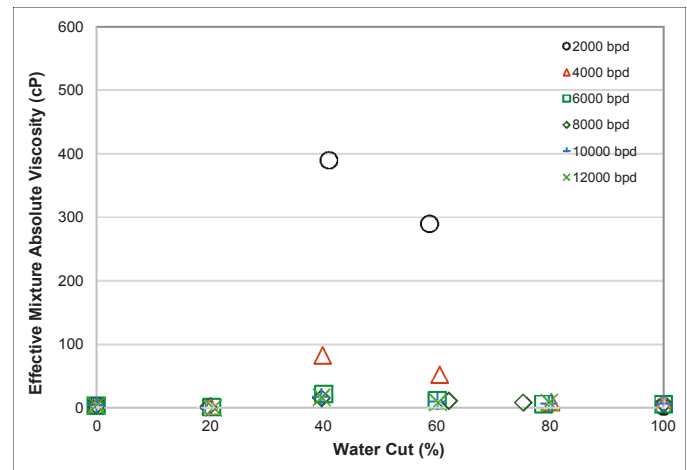


Fig. 2. The variation of absolute viscosity with water cut at different total flow rates ( $\theta = 0^\circ$ ).

Figures 3 and 4 show the effective mixture absolute viscosity variation with water cut, at inclination angles of 40° and 90°, respectively — vertical orientation of the annular test section. Both figures also show a similar trend in variation of effective absolute viscosity with an increase in water cut, similar to Fig. 2. As seen in Fig. 3, the highest mixture viscosity observed occurred at 40% water cut. The corresponding

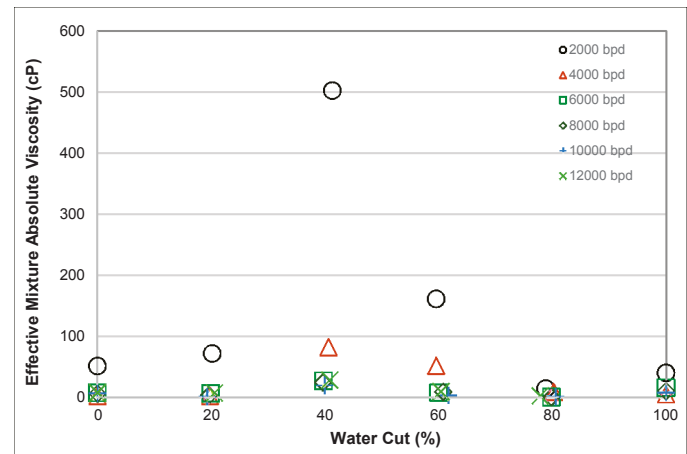


Fig. 3. The variation of absolute viscosity with water cut at different total flow rates ( $\theta = 40^\circ$ ).

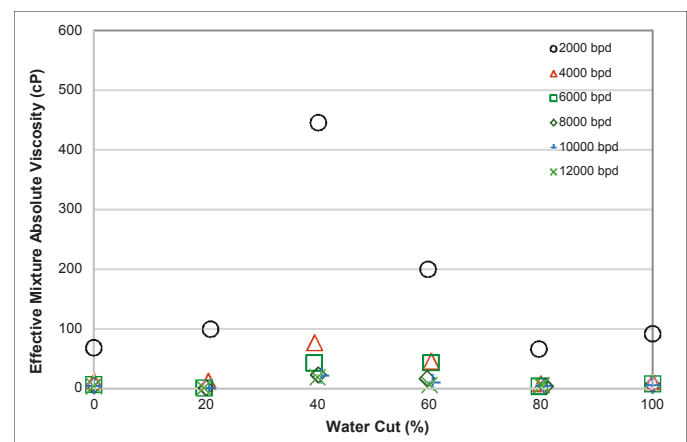


Fig. 4. The variation of absolute viscosity with water cut at different total flow rates ( $\theta = 90^\circ$ ).

maximum viscosities were about 500 cP and 450 cP, at 40° and 90° inclination angles, respectively, and occurred for a total flow rate of 2,000 bpd. At 40% water cut and 4,000 bpd, the mixture viscosity was about 82 cP, which was less than the maximum viscosity recorded at 2,000 bpd. With an increase in total flow rate, the highest mixture viscosity decreased to about 20 cP for both tests at 40° and 90° inclination angles.

These trends in viscosity variation with increasing total flow rate are similar to those observed for the tests at a 0° inclination angle, previously shown in Fig. 2. At 0% and 100% water cuts, there tends to be higher absolute viscosity values greater than that of pure oil and pure water, respectively. Although the system was flushed during the water only and oil only tests, the higher mixture viscosities observed at 0% and 100% water cuts may be attributed to some water contamination in the conduits during the oil only tests, and some oil contamination in the conduit during the water only tests.

### Effect of Inclination Angle

Figure 5 shows the variation of mixture absolute viscosity with water cut for 0°, 40°, 60°, and 90° inclination angles, for a total flow rate of 2,000 bpd. The plot shows the same trend of increasing viscosity as water cut increases up to 40%, and a decrease in viscosity as the water cut approaches 100%, as seen in plots presented previously. At 40% water cut, the result shows that the viscosity decreases from the maximum value of 500 cP at 40° to about 250 cP at 60°. For this total flow rate, there is no clear trend of viscosity variation with an inclination angle from the plot. The same observation is true for the other water cuts.

Figures 6 and 7 shows results for total flow rates of 6,000 bpd and 12,000 bpd, respectively, to cover the mid-flow and high flow rates during the test. The mixture viscosity variations with water cut are similar to those described previously, with the maximum viscosity occurring at 40% water cut. In Fig. 6, the maximum viscosity is 45 cP and occurs at a 60°

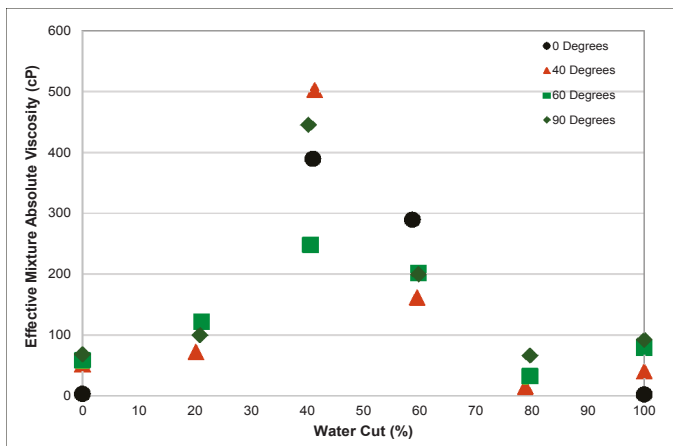


Fig. 5. The mixture of absolute viscosity vs. water cut at different inclination angles ( $Q_m = 2,000$  bpd).

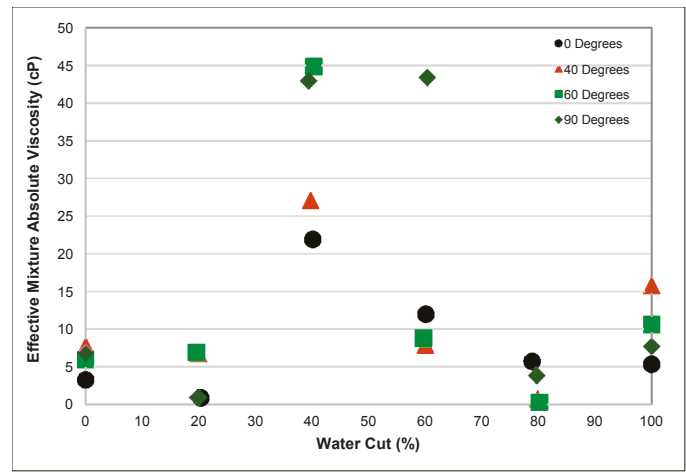


Fig. 6. The mixture of absolute viscosity vs. water cut at different inclination angles ( $Q_m = 6,000$  bpd).

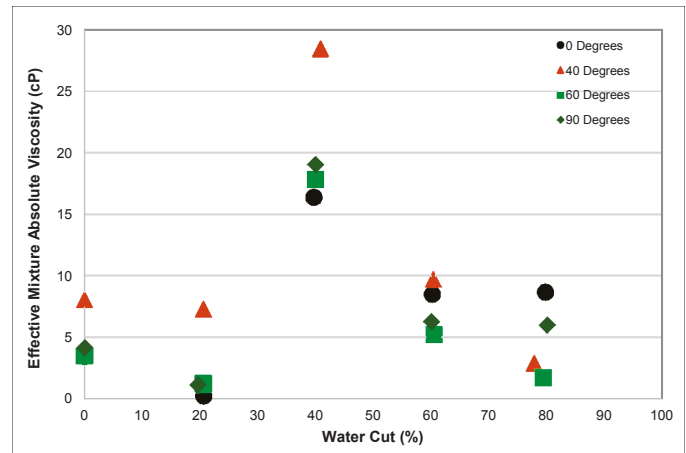


Fig. 7. The mixture of absolute viscosity vs. water cut at different inclination angles ( $Q_m = 12,000$  bpd).

inclination angle and decreases to about 22 cP for the 0° inclination angle. In Fig. 7, the maximum viscosity is about 29 cP for the 40° inclination angle and decreases to about 17 cP for the 0° inclination angle. In both Figs. 6 and 7, there is no established trend of the mixture viscosity variation with an inclination angle, similar to observations for the 2,000 bpd flow rate previously presented in Fig. 5.

The results shown in this work clearly indicate the same trend of an increase in mixture viscosity with water cut, with a maximum at 40% water cut before the mixture viscosity decreases significantly to much lower values at 100% water cut. This suggests that the inversion point for the oil-water system in this study is near the 40% to 60% water cut region. References previously cited have shown inversion points in their system at 20% and 35% water cuts. Having a single model to predict these effective absolute viscosities of the different oil-water mixtures will not be representative of a given operating condition. Therefore, measurements specific to a particular operating condition are desirable.

Viscosities as high as 500 cP have been presented in this work based on measurements from this study. During the tests, the water and oil pumps do not handle the high viscosity

oil-water mixture, since as previously mentioned, the pumps are installed on separate lines. Moreover, the oil-water separator ensures that the two liquids are segregated before being fed to each respective pump. Moreover, for field assets that have to handle oil-water mixtures in a wellbore, e.g., ESPs, having such high viscosities will be problematic for the pump. The ESP requirement to pressurize oil-water mixtures with such high viscosities as the water cut increases, and also produce the mixture to the surface will lead to ESP performance degradation, ESP motor power overload, and eventual ESP failure, resulting in expensive workover costs.

The method presented in this study is a useful method to determine the viscosity of oil-water mixtures flowing through ESPs downhole. This will aid in proper management of the ESP operation, to ensure longer equipment runlife, reduce equipment life cycle costs, and increase overall production system efficiency. This method assumes that the water cut is measured separately.

## CONCLUSIONS

The current work shows that the effective viscosity of oil-water mixtures increases substantially from 0% water cut to about 40% to 60% water cut and then decreases considerably as the water cut approaches 100%. In some cases, the effective mixture viscosity for water cuts between 40% and 60% can be up to 400 times greater than the viscosity of the mineral oil EXXSOL D80.

At the 40% water cuts, the maximum viscosities tend to decrease as the flow rate increased from about 500 cP at 2,000 bpd to about 20 cP at 12,000 bpd. This trend was consistent irrespective of the flow inclination angles studied during the test. This trend result may suggest that during field operations, it may be preferable to operate at a higher mixture flow rate to reduce the susceptibility of forming a high viscosity oil-water mixture. With regards to the effect of an inclination angle on the mixture viscosity, the maximum viscosities obtained were within the same order of magnitude for the different inclination angles. There is indistinct or negligible dependence of flow inclination on the effective mixture's absolute viscosity.

This result may suggest that changes in well deviation do not have a strong effect on the absolute viscosity of the oil-water mixture. Referring to oil field operations, there are different types of crude oils with varying physical properties depending on their compositions and operating temperatures. As water cut changes during the life of a well, the effective mixture absolute viscosity will change substantially from observations in this study. Field assets operating in conditions with such high viscosities would be prone to have performance issues, which may lead to premature failure.

Having a means to measure the absolute viscosity of oil-water mixtures therefore becomes important during production operations to ensure field assets are properly managed, and the

economic bottom line of the field operator are met. The method presented here can be a useful technique or tool to gauge the actual operating viscosities of oil field equipment, instead of using a general model that is not necessarily representative of the specific operating conditions.

## ACKNOWLEDGMENTS

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## NOMENCLATURE

- $\Delta p_t$  = total pressure drop, psi (or Pa)
- $\rho$  = fluid density, lb/ft<sup>3</sup> (or kg/m<sup>3</sup>)
- $g$  = acceleration due to gravity, ft/s<sup>2</sup> (or m/s<sup>2</sup>)
- $\theta$  = inclination angle of the conduit from the horizontal, (°)
- $V$  = average fluid velocity across the conduit, ft/s (or m/s)
- $D_h$  = hydraulic diameter of the conduit, inch (or m)
- $D_i$  = internal diameter of conduit, inch (or m)
- $D_o$  = outer diameter of conduit, inch (or m)
- $Q$  = volume flow rate, bpd (or m<sup>3</sup>/s)
- $\varepsilon$  = absolute roughness of the wetted pipe wall, ft (or m)
- $\mu$  = absolute viscosity of the fluid, cP (or Pa-s)
- $Q_m$  = mixture flow rate, bpd (or m<sup>3</sup>/s)
- $Q_o$  = oil flow rate, bpd (or m<sup>3</sup>/s)
- $Q_w$  = water flow rate, bpd (or m<sup>3</sup>/s)
- $\rho_m$  = mixture density, lb/ft<sup>3</sup> (or kg/m<sup>3</sup>)
- $\rho_o$  = oil density, lb/ft<sup>3</sup> (or kg/m<sup>3</sup>)
- $\rho_w$  = water density, lb/ft<sup>3</sup> (or kg/m<sup>3</sup>)
- $\alpha_o$  = oil cut
- $\alpha_w$  = water cut

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## BIOGRAPHIES



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# CO<sub>2</sub> Foam Rheology: Effect of Surfactant Concentration, Shear Rate and Injection Quality

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## ABSTRACT

Injecting carbon dioxide (CO<sub>2</sub>) into oil reservoirs has the potential to enhance oil recovery and sequester CO<sub>2</sub> underground. While CO<sub>2</sub> injection has been successful, a major challenge facing this technique is enhancing volumetric sweep efficiency. Some of the factors that contribute to this challenge are the low density and viscosity of injected gas relative to reservoir fluids. The use of foam is one of the most promising techniques used to increase the apparent viscosity of CO<sub>2</sub>, thereby improving volumetric sweep efficiency.

Increasing the CO<sub>2</sub> viscosity by using surfactants has the potential to mitigate some of the challenges associated with CO<sub>2</sub> injection projects. The objective of this work is to investigate the effect of various surfactants on CO<sub>2</sub> foam viscosity. Four surfactants, three commercial and one developed in-house, were used to evaluate the foam generation and rheological properties of CO<sub>2</sub> foams at high-pressure, high temperature (HPHT). Dynamic foam viscosity measurements were conducted in a special foam rheology apparatus with supercritical CO<sub>2</sub> (sc-CO<sub>2</sub>) under high-pressure (3,200 psi), high temperature (210 °F), and salinity conditions. The foam was generated by injecting sc-CO<sub>2</sub> and a surfactant at different concentrations (0.20 wt%, 0.50 wt%, and 1.00 wt%), shear rates (10 s<sup>-1</sup> to 600 s<sup>-1</sup>), and qualities (70%, 85%, and 90%).

The results indicate that all surfactants were able to generate good quality foam at HPHT. The foam viscosity increases with surfactant concentration. All foams exhibited a shear thinning behavior, with foam viscosity decreasing when increasing shear rates. In general, the highest viscosity for each surfactant was reported at the lowest shear rates. The results also showed that the foam quality has an impact on foam viscosity for some cases.

The highest foam viscosities for surfactant 2 were achieved at 85% quality; however, the quality had no significant impact on foam viscosity for surfactant 3.

## INTRODUCTION

Carbon dioxide (CO<sub>2</sub>) is a great injectant for enhanced oil recovery of light conventional oils — for environmental, technical, and economic reasons. The major advantages of CO<sub>2</sub> include lower miscibility pressures, swelling of crude oil, and

lowering its viscosity<sup>1</sup>. It has two major disadvantages: (1) An unfavorable viscosity or mobility ratio that produces inefficient oil displacement by causing fingering of the CO<sub>2</sub> owing to frontal instability, and (2) Gravity override within the reservoir due to the low density of supercritical CO<sub>2</sub> (sc-CO<sub>2</sub>)<sup>2-4</sup>.

These factors lead to poor sweep efficiency. Some of the factors that contribute to this challenge are the low density and viscosity of injected gas compared with the resident fluids in reservoirs<sup>5-7</sup>. Several methods have been tried to resolve this issue. The most common techniques are: Water alternating gas; in situ generation of foam/emulsion; and adding thickening agents to increase the CO<sub>2</sub> viscosity<sup>6, 8-12</sup>. The use of foam is one of the most promising techniques to increase the apparent viscosity of the CO<sub>2</sub>, thereby improving volumetric sweep efficiency<sup>13, 14</sup>.

Surfactants are the main chemicals used to generate and stabilize foams. Different parameters might affect foam generation and stabilization, including surfactant type and concentration, shear rate, gas volume (quality), and experimental conditions. Foam generation and stabilization at harsh reservoir conditions, such as high reservoir temperature, high salinity conditions, reaction with reservoir fluids — mainly crude oil — and surfactant adsorption to the rock minerals, are very difficult and complex<sup>15-21</sup>. The use of sc-CO<sub>2</sub> in the foam generation process is a major challenge. This is attributed to the fact that CO<sub>2</sub> has weak van der Waals forces and a lack of permanent dipole moment. Consequently, the CO<sub>2</sub> philic tail is a poor solvent for high molecular weight and polar solutes. In such a case, instability of foam can occur either in the form of flocculation or coalescence of foam bubbles. Based on the work that has been accomplished in this area, only a few surfactants can stabilize CO<sub>2</sub> brine foam/emulsion<sup>22-24</sup>.

The objective of this work is to investigate the effect of various surfactants on CO<sub>2</sub> foam rheology. Four surfactants, including commercial and in-house developed, were used to evaluate the foam generation and rheological properties of CO<sub>2</sub> foams at high-pressure, high temperature (HPHT), and salinity conditions. This work is a preliminary step to select potential surfactants for foam generation as a technique to improve the volumetric sweep efficiency during CO<sub>2</sub> injection.

Surfactant	Commercial Name
Surfactant 1	Ammonyx® LMDO
Surfactant 2	Petrostep® SB
Surfactant 3	Foaming agent provided by local vendor
Surfactant 4	Nano-surfactant

Table 1. List of surfactants

Salt	Concentration (mg/L)
NaCl	41,041.45
CaCl <sub>2</sub> ·2H <sub>2</sub> O	2,384.27
MgCl <sub>2</sub> ·6H <sub>2</sub> O	17,644.88
Na <sub>2</sub> SO <sub>4</sub>	6,343.19
NaHCO <sub>3</sub>	165.22

Table 2. Brine composition used

## MATERIALS

The commercially available 30 wt% active blend of lauramidopropylamine oxide and myristamidopropylamine oxide surfactants in water (Ammonyx® LMDO) and the 43 wt% active cocoamidopropyl hydroxysultaine surfactant in water (Petrostep® SB) used in this study were from the Stepan Company (Northfield, IL), and another commercial foaming agent was provided by a local vendor. The last surfactant formulation described in this work was developed in-house.

Table 1 lists the surfactants with their commercial names used in this study. The water used in this study was field injection water with a total dissolved solids content of 57,000 ppm, a density of 1.01 g/mL, and a viscosity of 0.291 centipoise (cP), both values are at 90 °C. The brine was prepared by dissolving various types of salts in deionized water. The details of the brine composition used are provided in Table 2. The gas used for foam generation is CO<sub>2</sub> with 99.5% purity.

## METHODOLOGY

Measured amounts of as-supplied surfactant stock solution were directly dissolved in calculated amounts of high salinity water to prepare — 0.20 wt%, 0.50 wt%, and 1.00 wt% — active surfactant solutions. Rheology experimentations were designed and performed on a custom-made HPHT foam loop rheometer, Fig. 1. This instrument has a visualization sapphire window cell and a capillary steel tube loop to measure rheology under dynamic conditions. Foam studies were performed with sc-CO<sub>2</sub>

under high-pressure (3,200 psi), high temperature, (210 °F), and salinity conditions. Shear rates applied to measure foam viscosity ranged from 10-600 s<sup>-1</sup> and volume (quality) of sc-CO<sub>2</sub> used for different measurements was 70%, 85%, and 90%.

The rheometer was first calibrated using Newtonian fluids with known values. The procedure involved placing the foaming agent — surfactant in high salinity water — and allowed to equilibrate in the cell. The sc-CO<sub>2</sub> is then introduced and equilibrates until the desired temperature and pressure is reached. The mixture was circulated in the capillary loop to ensure mixing and formation of the foam. Sample viscosities were then measured at different shear rates. The quality parameters of the foam was calculated from the volume of gas to the foaming agent ratio. A similar procedure was repeated for all samples reported in this study.

When studying fluid rheological properties, it is important to characterize shear stress ( $\tau$ ) and shear rate ( $\dot{\gamma}$ ) to estimate the fluid's apparent viscosity,  $\mu_{apparent}$ . Foam is classified as non-Newtonian fluid whose apparent viscosity is shear rate dependent. The apparent viscosity of the generated foam was measured as follows:

$$\mu_{apparent} = \frac{\tau}{\dot{\gamma}} \quad (1)$$

$$\tau = \frac{D \Delta P}{4L} \quad (2)$$

$$\dot{\gamma} = \frac{8V}{D} \quad (3)$$

where  $D$  is the tube diameter,  $\Delta P$  is the differential pressure across the foam loop,  $L$  is the tube length, and  $V$  is the velocity.

## RESULTS AND DISCUSSION

As previously mentioned, this study examines the impact of surfactant concentration, foam quality and shear rate on the viscosity of generated foam at HPHTs. The results indicate that

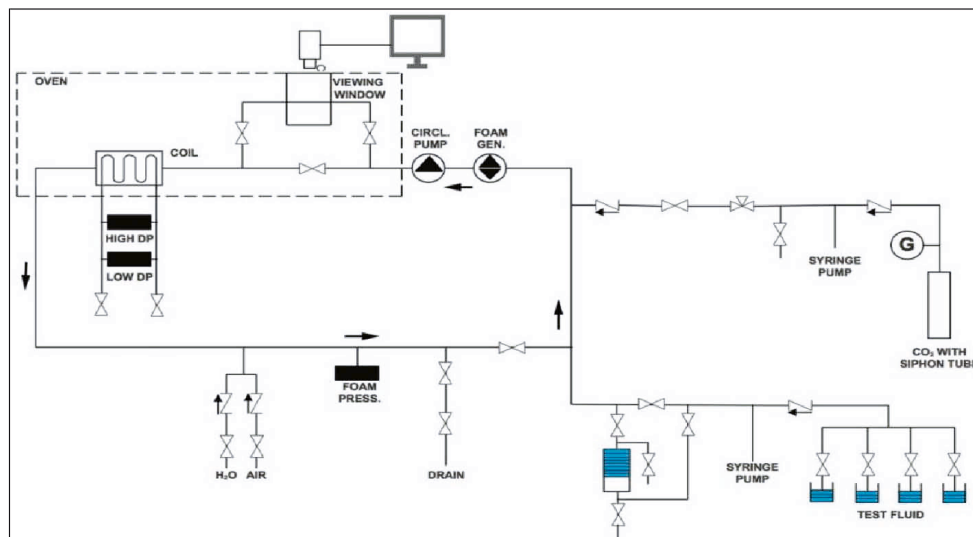


Fig. 1. Schematic of the custom-made HPHT foam loop rheometer.



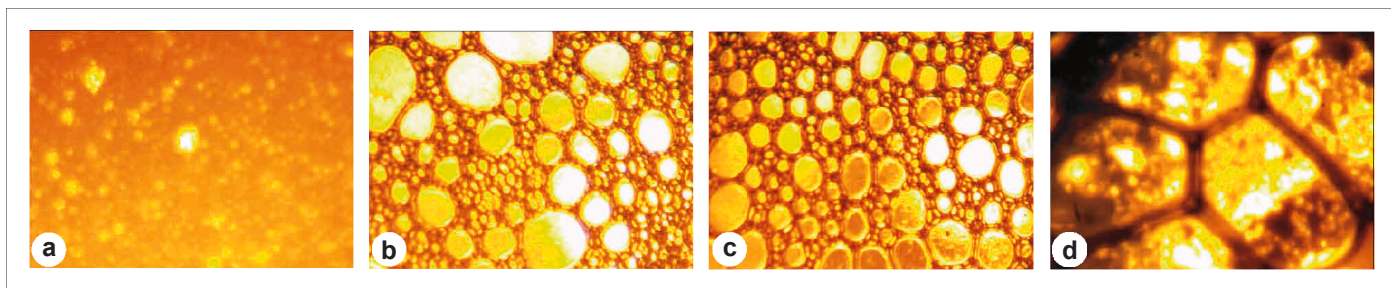


Fig. 2. Foam generated at HPHT: (a) surfactant 1, (b) surfactant 2, (c) surfactant 3, and (d) surfactant 4.

all four surfactants were able to generate foams at experimental conditions, Figs. 2a to 2d. The foam viscosity increases with surfactant concentration. All foams exhibited shear thinning behavior, whereas the foam viscosity decreases with increasing shear rates. The results also showed that the foam quality has an impact on the foam viscosity for surfactant 2, where the highest foam viscosities were achieved at 85% quality. More details about the effect of each parameter on the viscosity of foam will be presented separately.

### Foam Texture

Foam texture is an important parameter for determining foam strength and viscosity. Foam texture, also known as bubble

density, is defined as bubble size or the number of lamellae per unit volume. There is an inverse relationship between bubble density and bubble size. The foam's apparent viscosity is strongly dependent on foam texture. Studies found that smaller bubbles result in higher apparent viscosity of foam<sup>13, 14, 25</sup>. Figures 3a and 3b show the foam bubbles for surfactant 2 and surfactant 4 generated at 0.20 wt% concentration, 70% quality, and 30 s<sup>-1</sup> shear rate. As shown in Fig. 3a, foam bubbles are smaller for surfactant 2 than for surfactant 4. Consequently, the apparent viscosity measured for surfactant 2 was higher than that for surfactant 4 at the same conditions, 18.45 cP and 6.50 cP, respectively.

Also, a comparison was made for surfactant 2 and surfactant 3 at 0.50 wt% concentration, 90% quality, and 10 s<sup>-1</sup> shear rate, Figs. 4a and 4b, respectively. Surfactant 3, Fig. 4b,

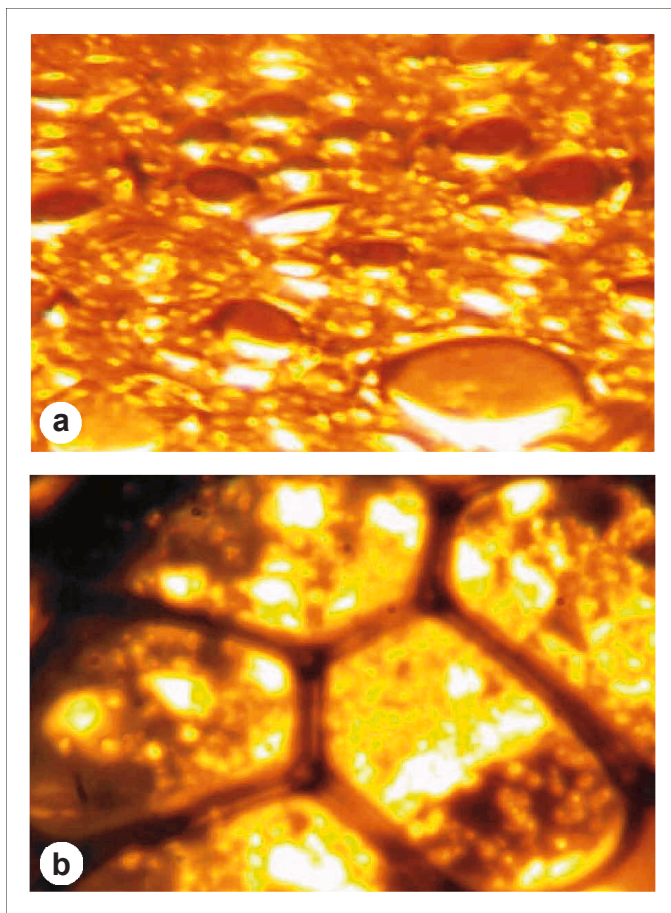


Fig. 3. Foam generated at 0.20 wt% concentration, 70% quality, and 30 s<sup>-1</sup> shear rate: (a) surfactant 2, and (b) surfactant 4.

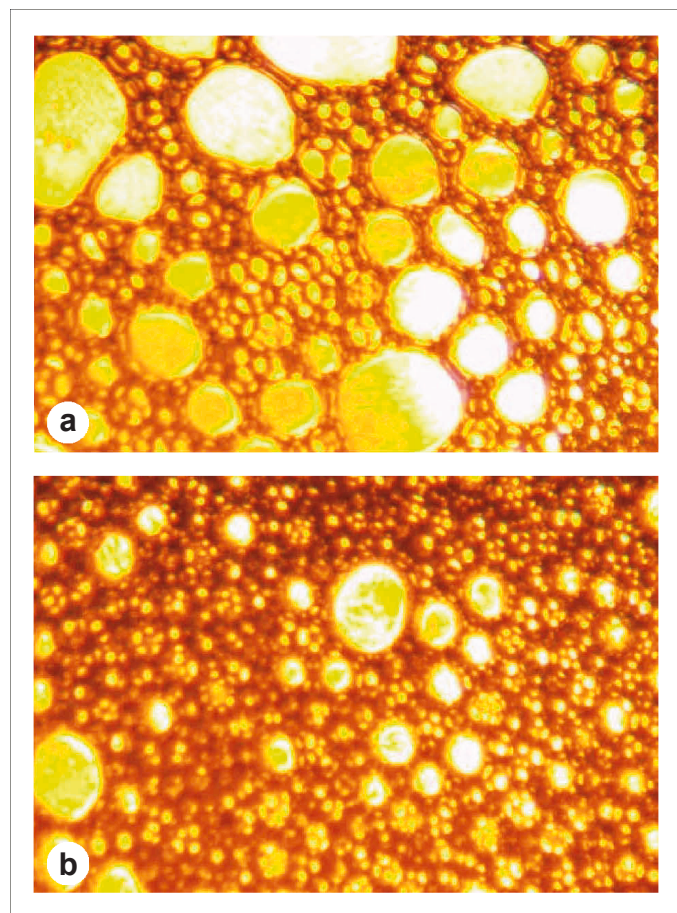


Fig. 4. Foam generated at 0.50 wt% concentration, 90% quality, and 10 s<sup>-1</sup> shear rate: (a) surfactant 2, and (b) surfactant 3.

generated foam with relatively smaller bubbles than that of surfactant 2, Fig. 4a. The measured apparent viscosity for surfactant 2 was 15 cP, while for surfactant 3, it was 33 cP.

### Effect of Concentration

The effect of surfactant concentration on foam viscosity was evaluated for all four surfactants. The results clearly indicate that the concentration of surfactant is critical to generate viscous foam. For surfactant 1, the effect of surfactant concentration was evaluated at 0.20 wt% and 0.50 wt%, and at different shear rates. As shown in Fig. 5, the increase of surfactant concentration from 0.20 wt% to 0.50 wt% produced at least seven times higher viscosity foam. This magnitude becomes higher as the shear rate increases. Similarly, the effect of the surfactant concentration was evaluated at 0.20 wt% and 0.50 wt%, and at different shear rates for surfactant 2. As shown in Fig. 6, the viscosity doubles as the surfactant concentration increases from

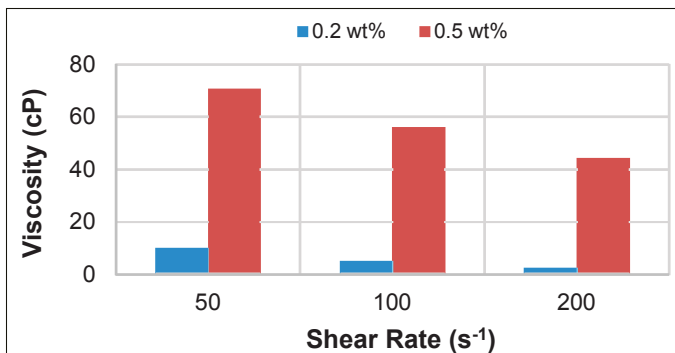


Fig. 5. The effect of surfactant 1 concentration on foam viscosity.

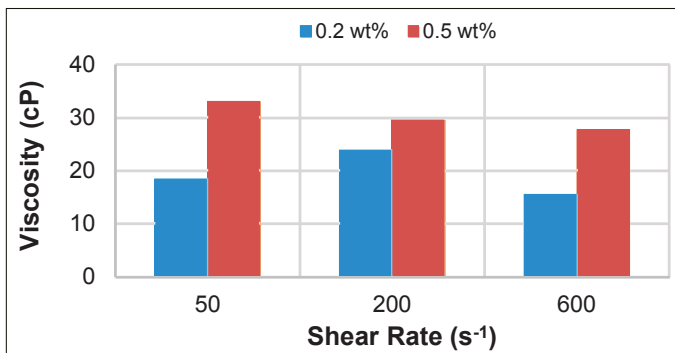


Fig. 6. The effect of surfactant 2 concentration on foam viscosity.

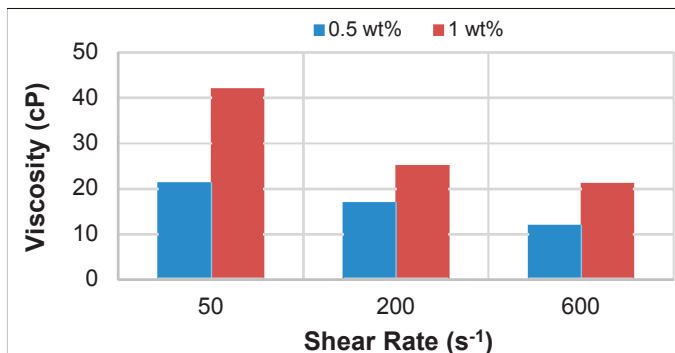


Fig. 7. The effect of surfactant 3 concentration on foam viscosity.

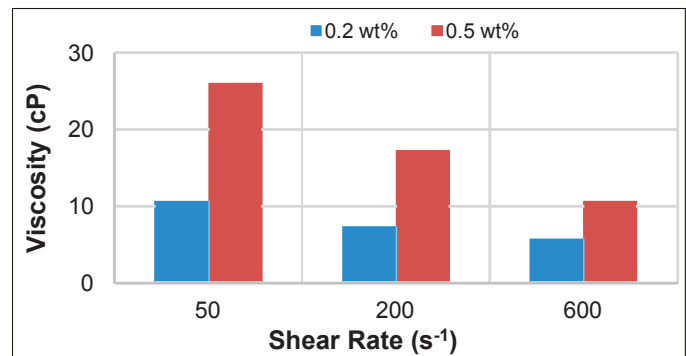


Fig. 8. The effect of surfactant 4 concentration on foam viscosity.

0.20 wt% to 0.50 wt%.

For surfactant 3, the effect of the surfactant concentration was studied using 0.50 wt% and 1.00 wt% samples. Similar to the previous surfactants, the results showed that as the surfactant concentration increases, the foam viscosity increases, Fig. 7.

The same behavior was reported for surfactant 4, with the surfactant concentration and viscosity being directly proportional. This behavior is depicted in Fig. 8. Increasing the surfactant concentration enhances the formation of micelle at the CO<sub>2</sub> brine interface, reduces the interfacial tension, and enhances the foam generation process.

### Effect of Quality

In general, the volume of injected gas to the total volume of injected fluids (quality) is a very important parameter influencing the foam generation and rheology. If the quality is too low, gas droplets are spherical and dispersed. In such cases, the foam will be weak and the viscosity will be very close to that of the foaming agent. Likewise, if the quality is too high, the aqueous film (lamellae) will be very thin and easy to collapse; or there might be no sufficient volume of foaming agent to form lamellae. As a result, the viscosity will be similar to that of the injected gas. The definition of low and high quality depends on the selected material and experimental conditions.

The effect of gas volume on the foam viscosity was evaluated for surfactant 2 and surfactant 3. The results showed that the injection quality is a critical parameter for foam generation for some cases, and therefore, determines the viscosity of the

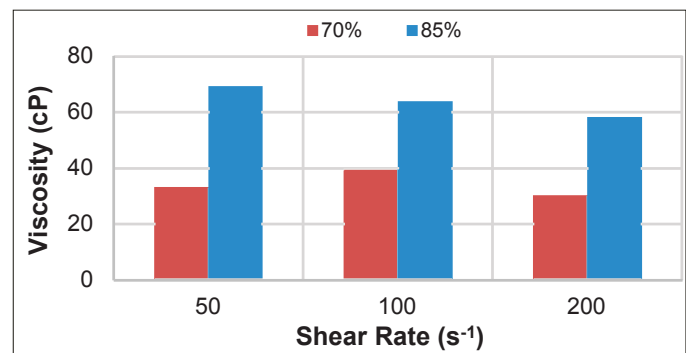


Fig. 9. The effect of gas volume on the foam viscosity for surfactant 2.

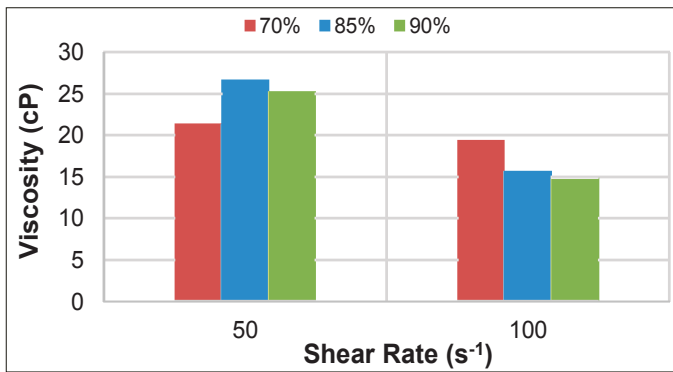


Fig. 10. The effect of gas volume on the foam viscosity for surfactant 3.

generated foam. For surfactant 2, the effect of quality was conducted at two qualities: 70%, and 85%. The results showed that the highest foam viscosities were produced when the foam quality was 85%. The tests were repeated at different shear rates, and all results confirmed this conclusion. This is, as mentioned earlier, due to either the lack of foaming agent or the weak foam generated, which might break down easily. Figure 9 shows the results of this case.

The effect of quality on the foam viscosity was also evaluated at three qualities: 70%, 85%, and 90% for surfactant 3. The results, as plotted in Fig. 10, showed that quality had no significant impact on the foam viscosity. As mentioned earlier, the impact of quality on the foam rheology is material and experimental conditions dependent. The results reported for the two tested materials, surfactant 2 and surfactant 3, support this hypothesis.

### Effect of Shear Rate

Foam is classified as a non-Newtonian fluid, whose apparent viscosity is shear rate dependent. Based on the foaming agent and shear rates, foam can exhibit either a shear thickening or a shear thinning behavior. In this study, the role of the shear rate on foam strength was examined by measuring the foam viscosity at various conditions, different concentrations and qualities, for all listed surfactants. Even though the effect of shear rate on foam viscosity was previously seen in Figs. 5 to 10, this section will present the effect of shear rate for specific cases. In general, the results of all tested surfactants exhibited a shear thinning

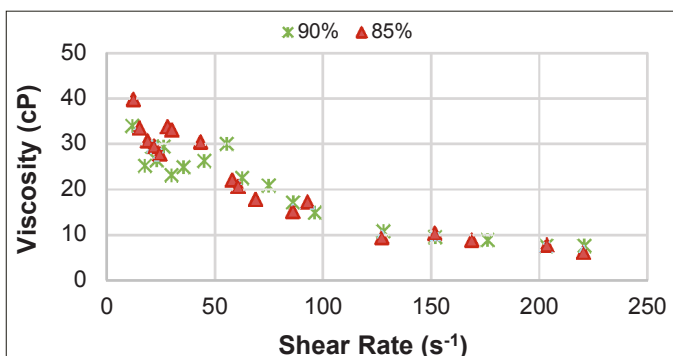


Fig. 11. The effect of shear rates on the foam's apparent viscosity for surfactant 3 at 0.5 wt% concentration, and at 85% and 90% quality.

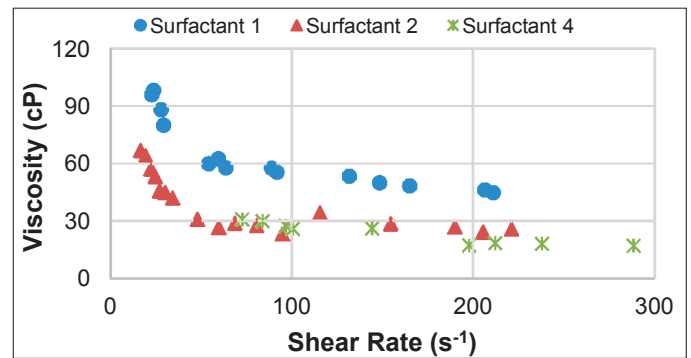


Fig. 12. The effect of shear rates on the foam's apparent viscosity for surfactant 1, surfactant 2, and surfactant 4.

behavior since their viscosity values decrease as shear rates increase. Figure 11 shows the effect of shear rates on the foam's apparent viscosity for surfactant 3 at 0.5 wt% concentration and at 85% and 90% quality.

The effect of shear rates on the foam's apparent viscosity for surfactants 1, 2, and 4, is depicted in Fig. 12. All cases exhibited the same behavior, as the shear rate increases, the foam's apparent viscosity decreases.

The viscosity of brine and CO<sub>2</sub> at experimental conditions, 3,200 psi, and 100 °C are 0.218 cP and 0.041 cP, respectively. Based on viscosity measurements, the four surfactants at all scenarios were able to generate foams with a higher viscosity than that of CO<sub>2</sub> and water.

### CONCLUSIONS

Four surfactants, developed commercially and in-house, were used to evaluate the foam generation and rheological properties of CO<sub>2</sub> foams at HPHT, and salinity conditions. Dynamic foam viscosity measurements were conducted in a special foam rheology apparatus with sc-CO<sub>2</sub> under high-pressure (3,200 psi), high temperature (210 °F), and salinity conditions. The foam was generated by injecting sc-CO<sub>2</sub> and surfactant at different concentrations (0.20 wt%, 0.50 wt%, and 1.00 wt%), shear rates (10 s<sup>-1</sup> to 600 s<sup>-1</sup>), and qualities (70%, 85%, and 90%).

Based on the foam rheology tests:

1. The results indicated that all four surfactants were able to generate foams at the tested conditions.
2. The foam viscosity is strongly dependent on the experimental parameters, including the surfactant concentration, the shear rate, and to some extent, the quality.
3. The foam viscosity increases with surfactant concentration. This effect was very obvious with all tested surfactants. For example, the increase of surfactant concentration from 0.20 wt% to 0.50 wt%, for surfactant 1, produced viscosity foam that was at least seven times higher.
4. The results showed that the injection quality is a crucial parameter for foam generation for some cases, and therefore, the viscosity of generated foam. For surfactant 2, the



highest viscosities were reported at 85% quality and the lowest at 90% quality. This is not the case for surfactant 3, for which the quality had no significant impact on the foam's viscosity.

5. The results also found that shear rate had an inverse relationship with the foam viscosity.
6. The four surfactants, at various conditions, were able to increase the CO<sub>2</sub> viscosity 25 to 2,000 fold.

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## BIOGRAPHIES



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# Detection of Signs Leading to Stuck Pipe Incidents and the Way toward Automation

Abrar A. Alshaikh, Mohammed K. Al-Bassam, Salem H. Al-Gharbi, and Dr. Abdullah S. Al-Yami

## ABSTRACT

The earlier a stuck pipe incident is predicted and mitigated, the higher the chance of success in freeing the pipe or avoiding severe sticking. Time is crucial in such cases as an improper reaction to a stuck pipe incident can easily make it worse. In this work, a novel and practical model was developed using real-time drilling data to automatically detect leading signs of stuck pipe during drilling operations and to communicate the observations and alerts — sufficiently ahead of time — to the rig crew for avoidance, or to initiate remediation actions.

The model uses key drilling parameters to detect abnormal trends that are identified as leading signs to stuck pipe. The parameters and patterns used in building the system were identified from published literature and historical data, and reports of stuck pipe incidents. The model is designed to be implemented in the real-time drilling data portal to provide an alarm system for all oil and gas rigs based on the observed abnormalities. The alarm is to be populated in the real-time environment and communicated to the rig crew in a timely manner to ensure optimal results, giving them more time to prevent or remediate a potential stuck pipe incident.

Testing the model on several wells showed promising results as anomalies were detected early in time before the actual stuck pipe incidents were reported. It further facilitated a better understanding of the underlying physics principles and provided awareness of stuck pipe occurrence. It improved monitoring and interpreting the drilling data streams. Beside such pipe signs, the model helped to detect signs of other impeding problems in the downhole conditions of the wellbore, the drilling equipment, and the sensors.

The model exceptionally uses the robustness of data along with the physics-based analysis of stuck pipe. This hybrid model has shown effective detection of the signs observed by experts ahead of time and has helped to provide enhanced stuck pipe prediction and risk assessment.

## INTRODUCTION

Stuck pipe occurs routinely in drilling operations with various levels of severity due to the combined effect of reservoir properties, engineering design factors, and rig crew intervention. These

factors include and are not limited to: formation lithology, pore pressure, well profile, drilling mud properties, borehole size, bottom-hole assembly (BHA) configuration, still pipe time, and rig crew experience. Stuck pipe is a typical unscheduled event during drilling operations, but it is especially problematic as it accounts for at least 25% of the nonproductive time, which is equivalent to an annual cost of 2 rig years<sup>1</sup>. This cost would be even more crucial when the drilling operations are carried out offshore. In addition to lost time and the rig daily rate, stuck pipe incidents often come with remedial associated costs such as lost tools, fishing costs, and/or sidetracking costs. Each of which comes with several cost categories, as in the case of sidetracking where the expenditures are associated with casing, cementing, drilling mud, logging, site preparations, and so on<sup>2</sup>.

When a pipe is stuck, the mechanism and cause of sticking need to be identified to execute the corresponding freeing procedures and remediation measures. Freeing the drillstring can take less than an hour in minor cases, and it can last days in severe sticking cases — if freed at all. The sooner the stuck pipe mechanism of the incident is identified, the faster the correct response can be taken, and the higher the chance of freeing the pipe<sup>3</sup>. In fact, 50% of stuck pipe cases become free within 4 hours, while less than 10% become free after 4 hours, Fig. 1<sup>4</sup>. If this statistic tells us something, it is the critical influence of time in the freeing procedure. In a worst-case scenario, when freeing the pipe becomes unsuccessful, the drilling engineer needs to

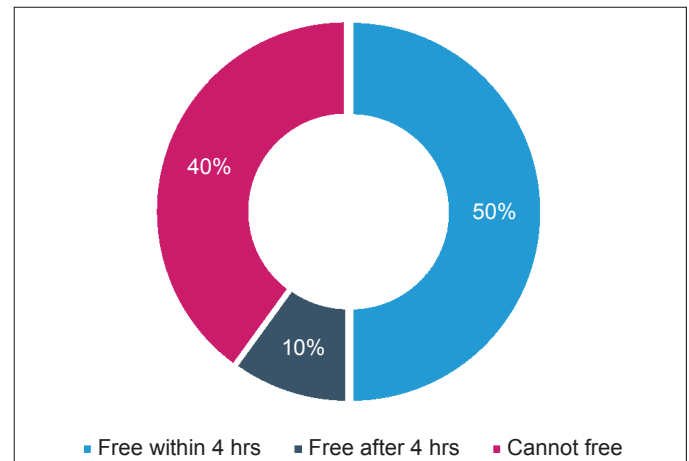


Fig. 1. Time is crucial to stuck pipe remediation, as less than 10% of stuck pipes are freed after 4 hours<sup>4</sup>.

consider an alternative plan of action and proceed with a side-tracking operation, adding additional costs to the drilling plan.

By understanding the mechanisms of sticking and their leading signs, one can also predict the sticking ahead of time according to the signs and trends produced during the drilling operations. This type of prediction, if done effectively, can give the rig crew more chance to avoid serious stuck pipe incidents. In this article, the mechanisms of stuck pipe, the conventional practices and techniques of preventing, diagnosing, and remediating such incidents, the identified leading signs and symptoms of stuck pipe, and the previously published work in the area of predicting stuck pipe occurrences are reviewed. A model for real-time automated detection of abnormalities in the drilling data is also presented as an approach to predict stuck pipe incidents. The results of the model's validation tests are presented and discussed from both the data and physics perspectives.

### STUCK PIPE MECHANISMS, PREVENTION, AND REMEDIATION

The drillstring is considered stuck when it cannot be retrieved from the wellbore, despite the ability or inability to lower it downhole, rotate it, or to circulate. In other words, as long as the drillstring cannot be pulled out of the hole using the maximum allowable tensile strength of the drillstring, it is considered stuck. This is because of the different types of sticking, e.g., in case of differential sticking, circulation is usually not interrupted, and in case of key seating, typically the down movement of the pipe remains possible during the incident<sup>4</sup>. That being so, stuck pipe incidents are usually classified according to their sticking mechanism, i.e., the force or the means that prevents pulling the drillstring out of the hole, to three broad categories. These are: (1) pack off and bridging, (2) wellbore geometry, and (3) differential sticking.

Mechanical sticking, due to either pack off, bridging, or

wellbore geometry, is responsible for almost 68% to 70% of the stuck pipe incidents while the remaining 30% to 32% is accounted for by differential sticking<sup>1</sup>. It is very common to have a stuck pipe after loss circulation during drilling through a lost zone as the drilling fluid fails to transport the cuttings off the bottom, causing pack off. It is also common for the pipe to

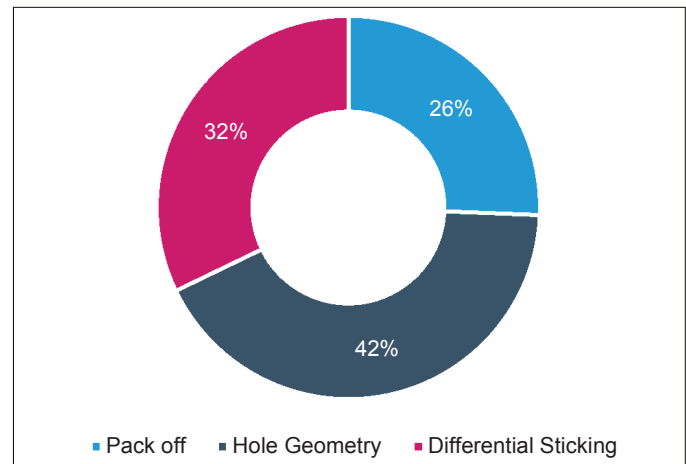


Fig. 2. The three most common stuck pipe incidents by type of sticking<sup>4</sup>.

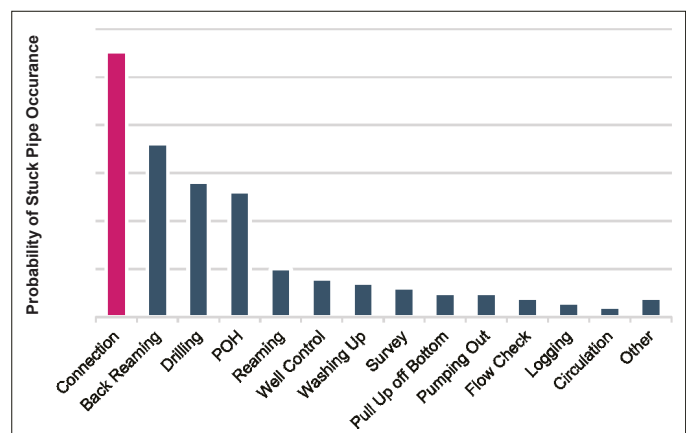


Fig. 3. A short list of the most common activities prior to stuck pipe incidents.

Mechanism		Causes	
Mechanical sticking	Pack off and bridging	Poor hole cleaning	
		Wellbore instability	Chemically stressed shale
			Mechanically stressed shale
			Unconsolidated sands
			Junk in the hole
	Fractures and faults		
	Dogleg	Keyseats	
		Stiff assembly	
		Micro-dogleg	
	Wellbore geometry	Ledges	
Squeezing formation			
Undergauge hole			
Differential sticking		Differential pressure	

Table 1. A summary of the different mechanisms and causes of stuck pipe<sup>4</sup>

get stuck after making a connection, right when the drillstring starts to move after some still time. Figures 2<sup>4</sup> and 3 show the most common mechanism of stuck pipe, and the most common drilling activities prior to sticking. Table 1 presents a summary of the different stuck pipe types and causes<sup>4</sup>. That being said, it is good to keep in mind that some stuck pipe incidents occur due to a combination of forces and factors, and that the incident can start with a specific mechanism of sticking and lead to another mechanism with time.

The first actions upon becoming stuck are the most critical. Even if the incident starts with the possibilities of limited movement or rotation, it degrades with time to impossible pipe movement in any direction. This is another reason why time is critical in such incidents, besides the cost of lost time<sup>4</sup>. Therefore, it is important to correctly diagnose and report the stuck pipe incident to ensure correct remedial actions are put in the right place and time. The actions taken based on the initial diagnosis can be the deciding factor between the ability to free the pipe or losing the pipe and opting for a sidetrack, or abandonment. Wrong initial diagnosis can easily lead to the situation getting out of hand and eventually losing the string in the hole. Therefore, it is of a great importance to know the different mechanisms of pipe sticking, the leading symptoms, and how to diagnose each type of sticking. In this section, the mechanisms of stuck pipe are briefly explained, and the prevention and remediation methods commonly used for each type of sticking are presented.

### Pack Off and Bridging

Hole pack off and bridging occur when the wellbore around the drillstring is plugged with debris or when a portion of the wellbore wall collapses around the drillstring, preventing the pipe from movement, and restricting or preventing circulation. They are said to be the most problematic of the other sticking mechanisms and have the lowest chance of freeing the pipe after sticking. The main cause of hole pack off or bridging is inadequate hole cleaning, that is when the cuttings, cement blocks, and/or junk are not properly transported out of the hole, and so they settle and build on the wellbore causing compaction around the drillstring.

Bridging refers to the case when large pieces of debris bridge and make the pipe stick, while pack off refers to the case when smaller debris makes the pipe stick by plugging the annular clearance between the drillstring and the wellbore. Hole cleaning is more critical and challenging in highly deviated or horizontal wells than in vertical wells as more debris tends to fall and accumulate at the low side of the hole, making it harder to clean. Therefore, in high-angle holes, more parameters need to be taken into consideration for maintaining an effective hole cleaning operation<sup>4,5</sup>.

The other potential cause of pack off is wellbore instability, which refers to formation failure causing caving or collapse of the wellbore. If there is a chance to free a pipe stuck due to a

wellbore collapse, sufficient hole cleaning needs to be done to clean the resulting debris out of the well. Wellbore instability imposes the most severe cases of stuck pipe where the drilling engineer would opt for fishing or sidetracking. It can be due to chemically or mechanically stressed shale, unconsolidated sands, or fractured and faulted formations. Wellbore stability is also affected by certain factors, including rock strength, stress anisotropy, mud density, mud filtrate, well path, and wellbore geometry. Wellbore geometry will be further discussed in the next section. Figures 4 and 5 illustrate examples of pack off and bridging due to different reasons.

As hole pack off is strongly linked to poor hole cleaning, preventing hole pack off is best achieved through efficient hole cleaning, which is done by maintaining the following measures:

- Have good mud rheology, especially plastic viscosity, yield point and gel strength.
- Ensure sufficient mud flow rate and hydraulics to maintain the required annular velocity (AV) to carry cuttings to the surface.

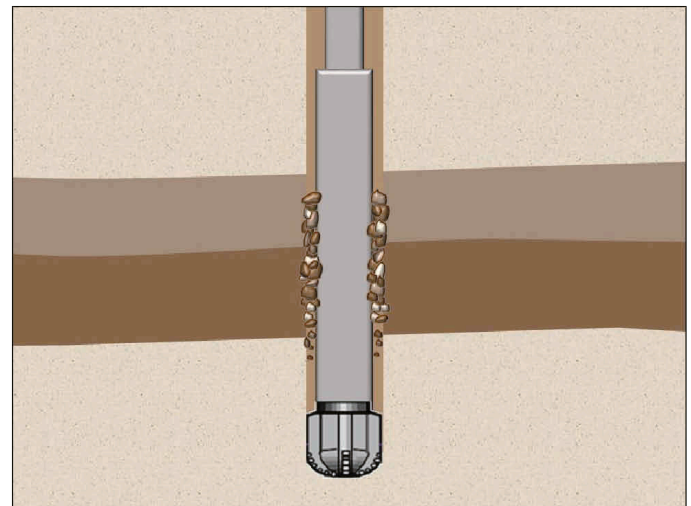


Fig. 4. An illustration of a stuck drillstring due to poor hole cleaning causing hole pack off.

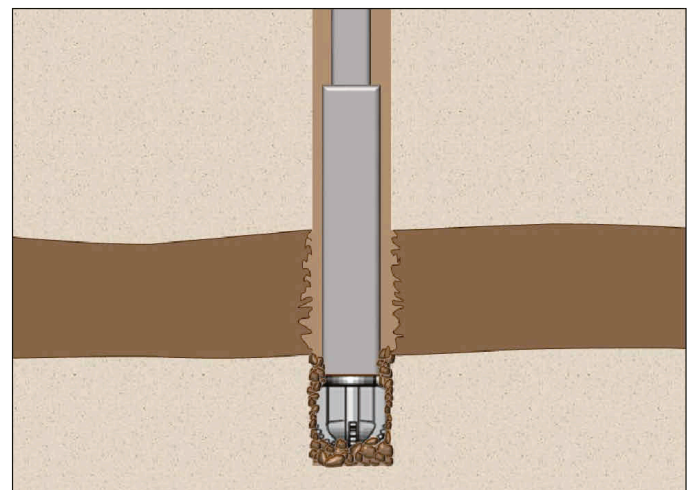


Fig. 5. An illustration of a stuck bit due to wellbore collapse and inadequate hole cleaning.



- Ensure reciprocating and rotating of the drillpipe while circulating the hole clean.
- Ensure eccentricity of the pipe, making sure that the pipe is placed in the center of the wellbore to ensure having similar AVs around the drillstring.
- Control the rate of penetration to ensure that the drilling process is not creating more cutting and solids than the mud system can carry and dispose of.
- Plan regular wiper trips as they clean the hole, wipe swelling clays, and ream problematic sections.

An important indicator of the efficiency of hole cleaning is the carrying capacity index (CCI), which was developed by Robinson and Morgan (2004)<sup>6</sup> and is calculated using the following equation:

$$CCI = \frac{K+AV+MW}{400,000} \quad (1)$$

where  $AV$  is the annular velocity in ft/min,  $MW$  is the mud weight in ppg, and  $K$  is the consistency index calculated using the following equation:

$$K = (511)^{1-n}(PV + YP) \quad (2)$$

where  $PV$  and  $YP$  are the plastic viscosity and the yield point in the Bingham Plastic model, respectively, and  $n$  is the power law index defined by the following equation:

$$n = 3.22 \log \left( \frac{2PV+YP}{PV+YP} \right) \quad (3)$$

Robinson and Morgan (2004)<sup>6</sup> concluded that the best hole cleaning is observed when the  $CCI = 1$  and poor hole cleaning is observed when the  $CCI = 0.1$ .

As for remediation hole pack off, certain steps can be considered to free the pipe:

- Attempt first to ensure good mud circulation, and regain circulation in case of losses.
- Apply downward force until circulation starts.
- Attempt to rotate the drillstring.
- In case of high inclination wells, spotting a low viscous followed by a weighted pill. The low viscosity pill will disturb the flow across the cuttings bed and then the weighted pill will carry the cuttings to the surface.
- In case of low inclination wells, only the use of a weighted pill will be needed to carry the cuttings to the surface.

## Wellbore Geometry

The second category of stuck pipe to be discussed involves wellbore geometry. This category includes the cases where sticking

happens as a result of a conflict between the wellbore shape and the BHA configuration. Specifically, it occurs when the BHA is moved up or down into the area of the wellbore with the misconfigured shape. This can happen due to several reasons, which Mitchell (2011)<sup>4</sup> has broken down into four categories. These are: (1) doglegs, (2) ledges, (3) undergauge holes, and (4) squeezing formations; such as salts, marls, and plastic shales.

Doglegs represent the majority of wellbore geometry sticking, as they can lead to further sticking problems such as keyseats, ledges, or drillstring failure due to high torque and side load. They can also lead to trouble related to cementing, running casing, logging, and even production equipment failure. It is worthwhile to note that doglegs also increase the risk of other types of sticking, be it differential or pack off. Figure 6 illustrates how a keyseat can be cut into a dogleg. Several keyseats resulted from high dogleg severity, high pipe tension and rotation, and long rotating time.

In his book, Mitchell (2011)<sup>4</sup> also points out another type of stuck pipe, which is “stiff assembly sticking.” It usually occurs while drilling directional wells, Fig. 7. In case of a severe

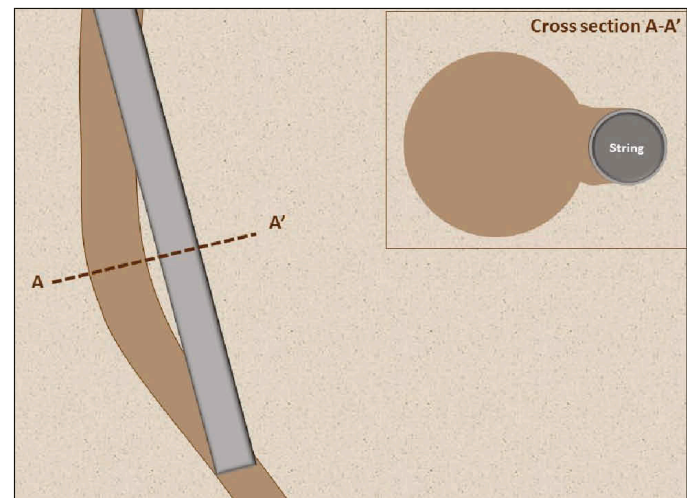


Fig. 6. An illustration of how a keyseat cuts into a dogleg causing a stuck drillstring.

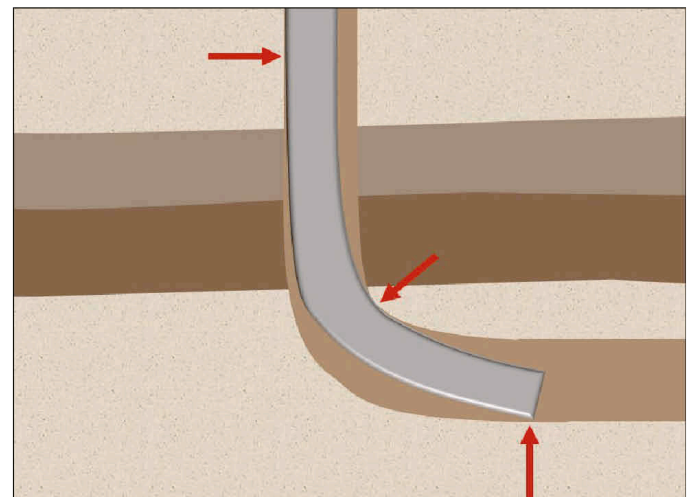


Fig. 7. An illustration of side loads induced by forcing the assembly into the dogleg, leading to the drillstring getting stuck.

dogleg, the BHA used in holding the built angle that can perhaps be forced down into the dogleg, inducing high side loads, and leading to the assembly getting stuck and not able to be retrieved. This particularly happens if the assembly is more flexible in compression than in tension. With proper design of the stiff assemblies run downhole, and with a careful consideration of the dogleg sections of the borehole, this type of sticking can be limited.

A wellbore geometry stuck pipe can usually be prevented if these certain procedures are followed:

- Sharp doglegs should be avoided. If they are suspected while drilling, a reaming trip should be considered to eliminate the keyseat. If they are suspected while tripping, a keyseat wiper can be added to the drillstring and plan for a short trip to wipe out the keyseat.
- Drilling through salt formations should be done with extra care, if it cannot be avoided at all. In that case, it should be drilled with high MW, as much as it is allowed by the pressure gradients.
- The BHA needs to be positioned carefully and stabilizers should be used while tripping across undergauge sections.

Several methods to free stuck pipe due to wellbore geometry include:

- Jarring the pipe in the opposite direction in which the pipe was moving before it got stuck.
- If the pipe was not freed, pumping a spotting lubricant agent might help reduce the friction between the wellbore and the stuck part. If the stuck pipe is in a carbonate formation, pumping acid pills may assist in dissolving the rock around the BHA.
- If the stuck pipe is in a salt formation, a freshwater pill can be pumped to dissolve the salt across the stuck part.

### Differential Pressure Sticking

The third category of stuck pipe is differential pressure pipe sticking. In this type of sticking, the drillstring is held against the wall of the wellbore due to forces developed across a permeable zone. These forces are mainly due to the difference between the hydrostatic and pore pressures. This force presses the drillstring to get embedded in the mud cake. This is especially critical in permeable formations with depleted reservoir pressure; since it imposes more room for higher differential pressure and thick mud cake development. This force gets even stronger as the filtrate escapes the mud cake into the formation allowing the pressure within the mud cake to decline.

Additional forces that act against the pipe movement are then developed between the fine solids of the filter cake and the

pipe, which is the adhesion force. The more filtrate that escapes into the formation, the more the cake shrinks. As a result, the contact area, and therefore the friction forces between the steel of the pipe and the solids increase, adding more resistance to the pipe movement<sup>7-9</sup>. Figures 8a and 8b illustrate two views of differential sticking of the BHA across a permeable formation showing the embedment in the mud cake.

Differential sticking can usually be prevented by taking certain measures, such as:

- Minimize and maintain the overbalance circulating mud pressure, including equivalent circulating density. Extra caution should be taken not to go underbalance and risk having an influx.
- The use of spiral drill collars minimizes the contact area between the BHA and the wellbore. Using small drillstrings and having a large hole size will result in less wellbore contact.
- Always minimize the time of static pipe during connections and taking surveys.
- Maintain a low value of fluid loss and avoid having thick filter cake through permeable zones. A thick filter cake will cause a reduction in the clearance between

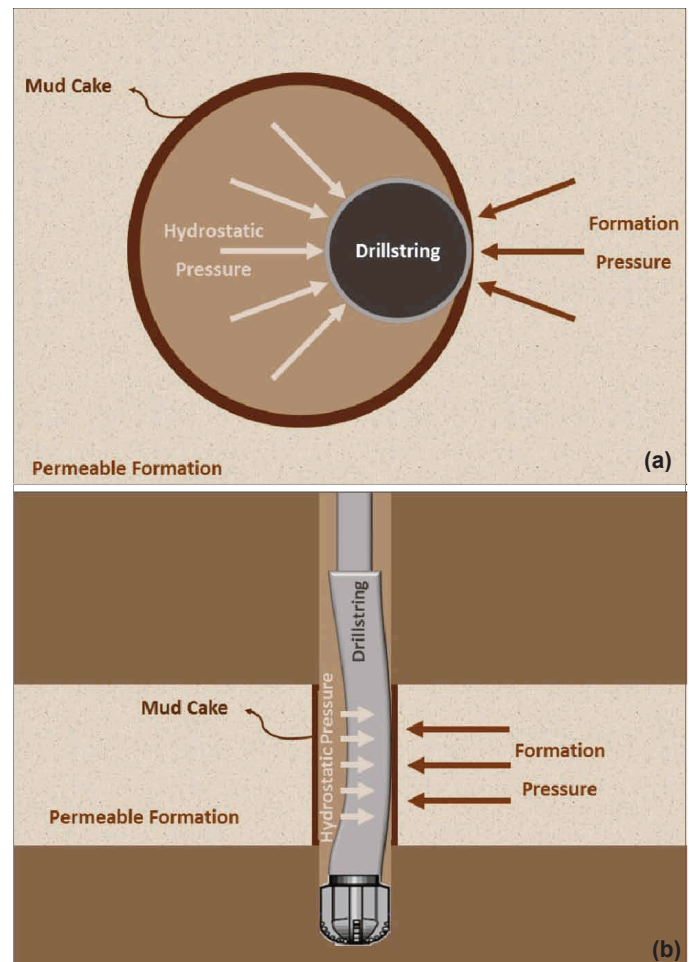


Fig. 8. Two separate views of differential pressure sticking of the BHA and the embedment of the drillstring in the mud cake across a permeable formation.

the wellbore and the BHA and will lead to differential sticking.

- Keep circulating to remove high solids from the mud to minimize the thickness of the filter cake. The filter cake is recommended to be thin, hard and impermeable.

Conventionally, a differential stuck pipe can be recovered following a few basic points<sup>4, 10</sup>:

- The first action is to increase the flow rate and apply maximum torque. The high mud flow rate will help to remove the filter cake from the BHA.
- The pipe should be jarred down. If not able to jar the pipe, the pipe should be slumped down. In differential sticking, the pipe should not be jarred up or pulled up because this will only increase the contact area between the filter cake and the BHA.
- If the above action did not succeed, then the reduction of MW should be considered to reduce the overbalance causing the differential sticking. Extra caution should be taken when reducing the MW so as to not get a kick, which could lead to a dangerous blowout.
- If the reduction of MW is not successful, or too dangerous to attempt, then spotting fluids to reduce the friction between the filter cake and the BHA should be considered. This may also be used simultaneously with the reduction of MW.

## STUCK PIPE PREDICTION

Throughout the last few decades, following the best practices for stuck pipe avoidance has proven to be very effective in reducing stuck pipe incidents. Several major oil and gas companies have adopted initiatives for preventing stuck pipe, formed task forces to mitigate this problem, and have reached the same conclusion. Results of their investigations indicate that focusing effort on engineering an operational training; ensuring adequate hole cleaning, ensuring use of optimal BHA and fluid designs, and following best remediation practices, have shown significant improvement in reducing stuck pipe incidents. Despite such improvements, stuck pipes continues to be a leading cause of nonproductive time and a major expense during drilling operations today<sup>1, 11</sup>.

Two potential solutions to minimize stuck pipe incidents are either of a drilling fluids approach, or of a drilling automation approach. In the first approach, which was presented in the previous section, the options are to optimize your drilling processes proactively such as by improving hole cleaning efficiency, controlling mud cake, and reducing loss circulation by optimizing the drilling fluids. The automation approach, however, is consistent of the hardware part; i.e., the sensors, and the software part; e.g., the algorithms. This approach, when very well

developed and utilized, can become very accurate and robust in preventing or mitigating stuck pipe incidents.

Many studies published in the literature have utilized data based on statistical analysis techniques, with a goal for tracking stuck pipe probability. One of the earliest works is by Hemphkins et al. (1987)<sup>12</sup>, which uses the discriminant analysis technique to classify the wells statistically, into mechanical, differential, or not stuck wells. Several other studies followed Hemphkins' work, basing their work on the multivariate discriminant analysis method and improving on it<sup>13-15</sup>. Subsequent work has presented several other techniques such as artificial neural network (ANN)<sup>16, 17</sup>, the adaptive neuro fuzzy inference system<sup>18, 19</sup>, and support vector regression<sup>3, 20</sup> to build similar stuck pipe classifiers or give stuck pipe probabilities using a large set of drilling data as an input.

Another approach using the combination of automation and human knowledge in mitigating drilling problems has been presented by Sadlier et al. (2013)<sup>21</sup> and Ferreira et al. (2015)<sup>22</sup>. The model uses pattern recognition incorporated in an automated decision support tool. This tool provides real-time case-based reasoning to assess the risk and mitigate stuck pipe incidents in collaboration with an expert. The tool uses case-based reasoning to match the real-time patterns with historical analogous cases where the same problem occurred. This allows providing automated recommendations for corrective actions based on the recognized patterns and the historical match. The experts are to collaborate in a timely manner with the decision support tool to provide guidance in mitigating the problem.

The third approach published in the literature uses analytical models, such as torque and drag, or hydraulics models, in identifying potential drilling problems. These models are usually based on the initial well plan, and the resulted predictions from the model are used during drilling operations for comparison with the actual parameters. In 2016, Salminen et al. (2017)<sup>23</sup> have presented a methodology using the same analytical model, but with improved reliability by including more parameters as factors in assessing stuck pipe risk. They have also incorporated this with the detection of specific patterns in the data that were identified as leading indicators of stuck pipe from historical cases.

## METHODOLOGY

Careful monitoring of drilling and tripping trends is crucial to a successful drilling operation. The approach discussed in this article focuses on real-time detection of leading signs of stuck pipe incidents using the combination of pattern recognition in the drilling data and the physics of stuck pipe presented earlier. This integration is meant to ensure the reliability of the automated detective model. The drilling data and the trends of abnormalities implemented in the model were identified based on analysis of historical data of stuck pipe cases as well as the expert's knowledge in the underlying principles for each type of stuck pipe. The model is designed to be implemented in the real-time drilling data environment to provide an alarm system



for all oil and gas rigs based on the observed abnormalities. The alarm is to be communicated to the rig crew in a timely manner to ensure optimal results, giving them more time to prevent or remediate a potential stuck pipe incident.

From the analysis of historical cases, it was seen that there is not a single pattern in a single parameter indicating all of the stuck pipe incidents. There are, though, different trends that show for different cases, but not all of them. The main factors that are thought to cause this is the mechanism of sticking and the type of operation held prior to getting stuck. Therefore, the decision was to rely on the certain parameters and behaviors that appear to be indicative of most stuck pipe incidents, taking into consideration the drilling operation type. The parameters used as inputs for the model included flow-in rate, weight on bit, rotary speed, standpipe pressure, hookload, hook height, bit depth, hole depth, torque, and time. The inputs were included on different sub-models. The tests presented in this article reflect the results of only one of the sub-models, which uses standpipe pressure, flow-in rate, rotary speed, time, hole depth, and bit depth.

In the context of machine learning, the model examines the real-time streams of the key drilling parameters to recognize the installed patterns that give meaningful observations. The engine consists of algorithms that use rule-based structures to identify the elements of abnormalities in the streams. These elements can be either simple; consisting of a single pattern in a single parameter, or complex; consisting of a combination of patterns that are either trending in a single parameter stream or more than one stream. Complex elements — or trends — could be signs or symptoms indicating a potential for more severe events. The elements that satisfy the rules of the algorithms are presented as alarming events to the end-user. The elements can recognize erratic behaviors, cyclic increase or decrease, gradual increase or decrease, or a combination of these behaviors for different parameters.

The engine was examined across several historical cases of stuck pipe before implementation and testing in a real-time environment. In the next section, the results of implementation of the model on two cases are presented and discussed.

## RESULTS

**Case 1:** A slight pack off was observed and the BHA got stuck while curing losses. After multiple attempts to free the drillstring with working it downwards, jarring, and spotting fluid pills, a decision was made to cut the drillstring free, and side-track to resume drilling operations.

The predictive engine developed was run on the same well, and it was able to detect leading signs 2½ hours before any abnormalities were reported or observed by the rig crew or the monitoring engineers. The engine detected the abnormal decrease in the standpipe pressure followed by an increase during the constant flow of mud from the pump. The observation by the model is shown in red, as one of the signs detected

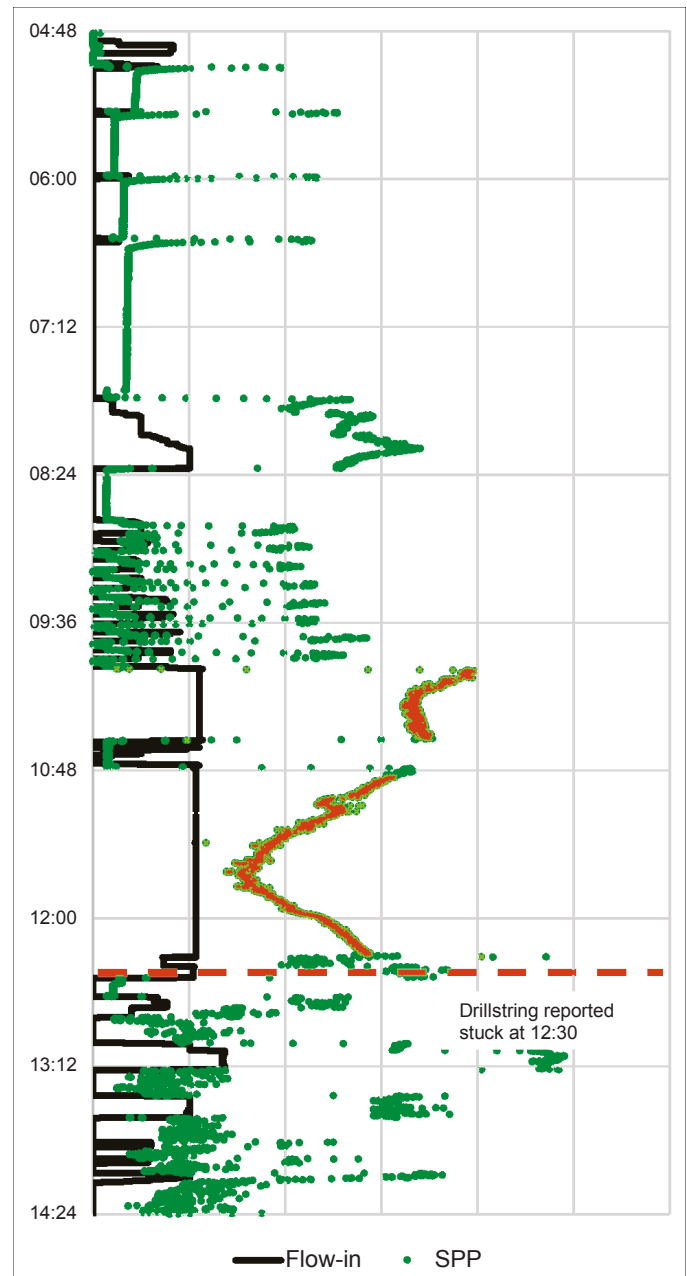


Fig. 9. The results of case 1 with the model's observed abnormalities marked in red.

by the engine in the standpipe pressure's real-time data stream, Fig. 9.

**Case 2:** While washing and reaming up prior to connection, increased overpull was observed while picking up the pipe. The rotation of the pipe was restricted, as well as circulation, as noticed on the circulating pressure gauge. Prior to that, dynamic losses were experienced during rotary drilling, and restrictions were observed while running in the hole. Given the symptoms, the sticking was likely due to pack off in the well-bore after loss circulation. Stuck pipe incidents due to pack off are common after loss circulation incidents, as the drilling mud fails to transport the cuttings induced by the lost zone while drilling<sup>24</sup>.

Running on the same well, the model was able to detect

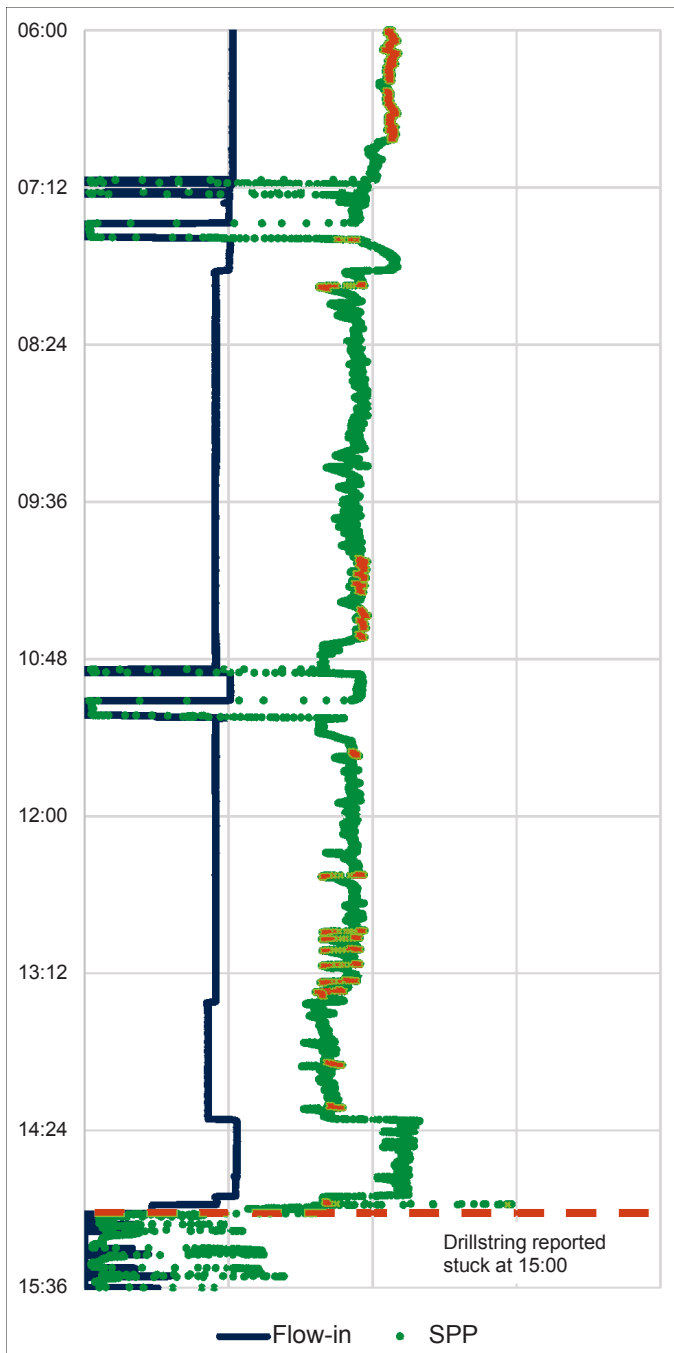


Fig. 10. The results of case 2 with the model's observed abnormalities marked in red.

leading signs 5 hours before a stuck pipe incident was identified and reported. The frequency of the alarming abnormalities increased over time until the sticking was observed by the rig crew. Figure 10 shows the monitored parameters, with the abnormalities observed by the model marked in red.

## CONCLUSIONS AND FURTHER STEPS

1. The detection model facilitates a better understanding of the underlying physics principles, and provides improved situational awareness of stuck pipe incidents. It helps to better utilize, monitor and interpret the real-time drilling data streams.

2. The elements detecting abnormalities in the drilling data streams may not necessarily signal a stuck pipe, nevertheless, it may indicate impending problems whether in the conditions of the wellbore, the drilling equipment, or the sensors.
3. In the context of data quality, the accuracy of the data is far from consistent and that is mainly due to factors related to the sensor types and the sensor calibration used as sources to acquire the different drilling data points. Another factor is the nature of the properties' acquisition, derivation, and measurement. The source of "errors" building up cause major effects throughout the process of collection up to interpretation. The negative effect of this issue on the results of the model is better minimized by the use of improved sensors with optimized calibration methods.
4. To ensure more robustness and reliability, the configuration of the model is to be optimized to ensure high functionality with different sources of data and ranges of accuracy through the use of an adapting criteria set in the algorithms.

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## BIOGRAPHIES



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# A New NMR-based Height Saturation Model of a Low Permeability Carbonate Reservoir

Dr. Ahmad M. Al-Harbi, Dr. Gabor G. Hursan, Dr. Hyung T. Kwak, and Jun Gao

## ABSTRACT

Formation evaluation studies suggest that high in the hydrocarbon column, the resistivity logs can precisely quantify fluid saturation due to the large contrast in the resistivities of hydrocarbon-bearing and water-bearing formations. In the transition zone where water and oil reside in more or less equal volumes, the determination of hydrocarbon saturation by resistivity value becomes challenging. Some of these intervals exhibit low resistivity pay (LRP) characteristics where resistivity-based log analysis predicts high water saturation, yet they can produce little or no water cut.

Conventional log-based saturation and rock quality evaluation in a low permeability carbonate reservoir is difficult due to the lack of the input measurement sensitivity to pore size and the amount of pore filling fluids. Pore size information provided by nuclear magnetic resonance (NMR) logs from this LRP provides good sensitivity, but it needs to be calibrated for quantitative use. The objective of this study is to determine a height-based bulk volume irreducible (HBVI) cutoff to distinguish and quantify the amounts of reservoir fluids across a wellbore using NMR logs.

The procedure consists of a two-part workflow. The first part describes the acquisition of a database that includes high-quality laboratory NMR and capillary pressure measurements to determine the pore aspect ratio and the effect of temperature on the formation's NMR properties using core samples from the target reservoir. These measurements are then used to underpin the mathematical description of the HBVI cutoff as a function of displacement pressure that is translated to a height above the free water level. The second part of the workflow is a well log processing scheme where the new formula is implemented to calculate a continuous fluid saturation profile across the well using NMR logs.

The laboratory measurements suggest a good agreement between the capillary pressure and NMR  $T_2$  measurements. Both data sets indicate a well sorted pore size distribution. The  $T_2$  relaxation time increases with temperature, which is then considered in the downhole implementation of the HBVI model. The NMR-based saturation log is consistent with wireline formation test observations and mercury injection capillary pressure (MICP) based saturation height modeling results

in a LRP reservoir.

The results of this study suggest that the laboratory calibration and NMR log processing workflows described herein provide a viable alternative for the calculation of fluid saturations in complex reservoirs where the conventional log-based saturation evaluation faces uncertainties.

## INTRODUCTION

Formation evaluation studies suggest that high in the hydrocarbon column, the distribution of fluids in the pore network yields a simple and straightforward correlation between formation resistivity fluid saturation as described first by Archie's breakthrough article in 1942<sup>1</sup>. In the transition zone, where the amounts of oil and water become comparable, the relationship between resistivity and saturation is less accurate<sup>2</sup>. In certain formations, the water phase forms electrical shortcuts that lead to low resistivity in formations that still contain significant volumes of producible hydrocarbons<sup>2</sup>. Such a pay interval is known as low resistivity pay (LRP). The issue of LRP is evident in some sandstones due to mainly shaliness<sup>3,4</sup> and in carbonates due to mainly microporosity<sup>5-9</sup>.

Microporous carbonates may contain large amounts of connate water, yet produce dry or nearly dry oil. The resistivity contrast between these pay zones and water-bearing formations becomes small<sup>10</sup>. The resulting loss of sensitivity in conventional log-based saturation evaluation poses risks to reservoir development in these formations at or near the transition zone and warrants alternative solutions, one of which is discussed in this article.

Nuclear magnetic resonance (NMR) tools uniquely measure the amount of fluids within a porous rock and characterizes the strength of their interaction with the pore surface. Downhole NMR logging enabled new reservoir description techniques for porosity and rock quality analysis<sup>11</sup>. One of these techniques is the determination of irreducible water saturation using an NMR cutoff that is obtained by laboratory desaturation of core samples with a single desaturation pressure representing maximum reservoir height. The advantage of this technique is that the NMR cutoff<sup>12</sup> usually remains consistent within major lithology types while it is independent of formation resistivity properties.

Motivated by a good agreement between NMR  $T_2$  distribution logs and mercury injection capillary pressure (MICP) pore throat distributions in multiple cored wells from a low permeability carbonate reservoir, the current study extends the NMR cutoff approach to a multitude of displacement pressures covering a wide range that includes the transition zone in addition to the irreducible condition. Combined with fluid displacement pressure in a given well, the height-based NMR cutoff can be conveniently used for the calculation of water saturation. The practical advantages of the technique reported herein are summarized as:

1. It is independent of formation resistivity.
2. It is easily implemented within the existing NMR interpretation software.
3. The method works in horizontal and vertical wells without any modification.

This article describes the laboratory procedures to acquire supporting data for the height-based cutoff method and the results of said analysis for 15 microporous samples that underpins the mathematical model of the height-based NMR  $T_2$  cutoff. The final section discusses the results of the new procedure applied on NMR well log data.

## METHOD AND PROCEDURE

### Material

Fifteen 1.5" diameter core plug samples from a low permeability carbonate reservoir were prepared for the tests. All of the 1.5" core plugs were cut in half creating 30 plugs, in which nine halves were used in the MICP study while the other nine halves were used in the height saturation modeling study. Synthetic water related to the depth's interval used for the investigation — 206,056 mg/L total dissolved solids — was prepared based on the detailed water composition presented in Table 1. The brine was filtered through a 0.45 micron filter for test use.

Salt	Concentration (mg/L)
Sodium Chloride (NaCl)	187,667
Calcium Chloride (CaCl <sub>2</sub> ·2H <sub>2</sub> O)	13,293
Magnesium Chloride (MgCl <sub>2</sub> ·6H <sub>2</sub> O)	3,562
Potassium Chloride (KCl)	550
Sodium Bicarbonate (NaHCO <sub>3</sub> )	2,236
Sodium Sulfate (Na <sub>2</sub> SO <sub>4</sub> )	2,675

Table 1. Salt concentration of the water used to prepare synthetic brine

## Magnetic Resonance Imaging (MRI) based Capillary Pressure

The main objective of this study is to confirm the apparent relationship of pore size information provided by NMR and capillary pressure, and to develop a model linking capillary-bound water volume and capillary pressure, resulting in a height-based saturation model.

To confirm the relationship of pore size information from the NMR and capillary pressure, accurate capillary pressure curves are required for each sample. Capillary pressure is typically measured in the laboratory by using mercury injection, porous plate, or centrifugation techniques<sup>13</sup>. The porous plate method is considered the most direct and accurate method. This method takes a long time since each capillary pressure point requires an equilibrium time that can take weeks or months<sup>14</sup>. The mercury injection method is fast and can reach very high capillary pressures. The method is destructive and uses a non-representative fluid (mercury).

A common compromise between porous plate and mercury injection is centrifugation<sup>15</sup>. This method uses reservoir fluids and decreases the equilibrium time by using high centrifugal forces. The inlet saturation must be computed using an approximate solution that is known to cause errors<sup>16</sup>.

A more recent method<sup>14</sup> for measuring capillary pressure employing a centrifuge and a new quantitative magnetic resonance imaging (MRI) method for measuring fluid saturation were demonstrated to work for different rock systems. The capillary pressure is calculated from the Hassler and Brunner equation (Eqn. 1) at each radial position in the rock:

$$P_c(r) = \frac{1}{2} \Delta \rho \omega^2 (r_2^2 - r^2) \quad (1)$$

where  $\Delta \rho$  is the density difference between wetting and non-wetting fluid.  $\omega$  is the rotational speed around the rotational axis,  $r_2$  and  $r$  are the distance from the center of the rotational axis, Fig. 1.

The calculated capillary pressure together with the saturation, as measured by MRI at each position, directly produces a capillary pressure curve<sup>14</sup>. Figure 2 shows a typical example of the MRI capillary pressure curve.

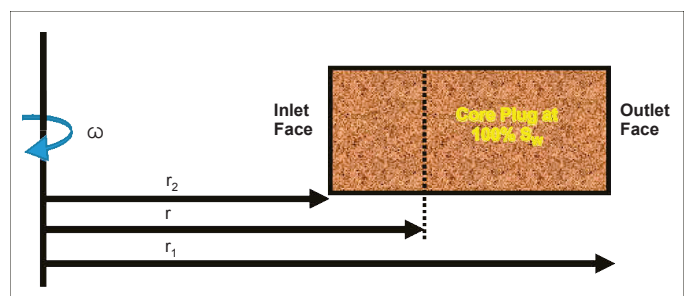


Fig. 1. Schematic diagram of a core plug sample spinning in a centrifuge.



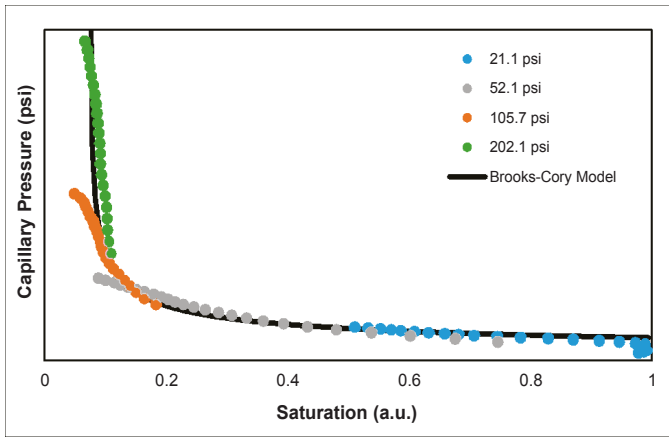


Fig. 2. A typical example of the MRI capillary pressure curve.

## Height-based Saturation Modeling

**Marschall's Height-based Saturation Model.** Marschall (2000)<sup>17</sup> developed a new method to determine capillary bound fluid saturations at multiple capillary conditions, which he referred to as height-based bulk volume irreducible (HBVI). His method showed that by plotting experimental data on a log-log scale,  $T_2$  cutoff was inversely proportional to air-brine  $P_C$ , and the data was nicely fitted with a power function. The correlation was based on the  $T_2$  cutoff values derived from  $S_{wi}$  via mercury injection and a full-curve and single-point centrifuge  $P_C$ .

Following Marschall's method, a correlation between  $T_2$  cutoff and  $P_C$  was constructed for nine samples (S1, S2, S3, S5, S6, S7, S8, S9, and S12) using data from a MICP  $P_C$  curve and a MRI-based  $P_C$  curve value spanning over approximately one order of magnitude, Fig. 3.

Even though our data was fitted nicely with a power function —  $R^2$  between 0.81 and 0.95 — the figure clearly shows that a linear relationship cannot perfectly describe the data. Therefore, a new model is required to accurately describe the relationship between the  $T_2$  cutoff and the  $P_C$  for the transition region (< 100 ft above the free water level) at this well.

**NMR-based Height Saturation (NBHS) Model.** This section describes the development of a new NMR-based height

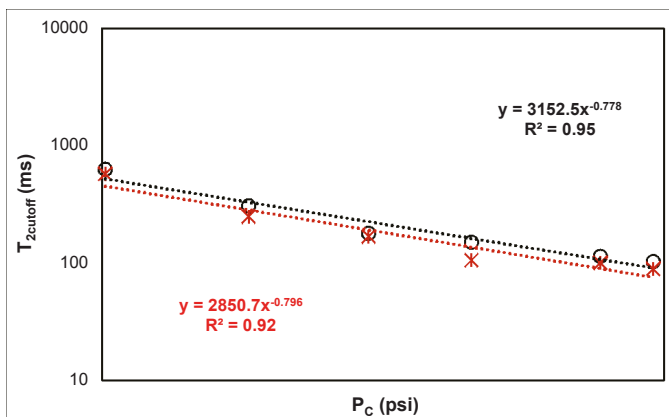


Fig. 3. The relationship between  $P_C$  and  $T_2$  cutoff obtained using a MICP  $P_C$  curve (black) and a MRI-based  $P_C$  curve (red).

saturation (NBHS) model specific for the LRP zones in this reservoir. The NBHS model was derived by integrating NMR/ MRI and centrifugation techniques. This allows NMR data to be used to determine the capillary bound fluid saturations at multiple capillary conditions, which will improve the determinations of hydrocarbon pore volume.

The  $T_2$  distributions displayed in Fig. 4 show that for each  $P_C$  imposed, there is a consistent decrease in the  $T_2$  distribution time components. This demonstrates that the  $T_2$  cutoff is inversely proportional to  $P_C$ <sup>17</sup>.

Figure 4 also shows that as the  $T_2$  cutoff decreases, the cumulative porosity, i.e., capillary bound fluid saturations, decreases. Knowing the relationship that ties the  $T_2$  cutoff to capillary pressure and capillary bound fluid saturation, a height-based saturation model could be constructed based on sound assumptions.

The Brooks-Corey model in the following form relates capillary pressure and saturation as:

$$P_C = P_e \left( \frac{S_w - S_{wi}}{1 - S_{wi}} \right)^{-1/\lambda} \quad (2)$$

where  $S_w$  is water saturation at the corresponding  $P_C$ , and  $S_{wi}$  is the irreducible water saturation,  $P_e$  is the entry capillary pressure, and  $\lambda$  the pore size distribution index.

Solving for the saturation, the model could be written as:

$$S_w = (1 - S_{wi}) \left( \frac{P_C}{P_e} \right)^{-\lambda} + S_{wi} \quad (3)$$

For a fully water saturated rock, as  $T_2$  cutoff decreases due to an increase in displacement pressure, i.e., capillary pressure, the non-movable water saturation decreases. Data from the full curve NMR-based  $P_C$  for samples 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, and 12, shows that the  $T_2$  cutoff is linearly proportional to the non-movable water saturation, Fig. 5.

Therefore, the saturation terms in Eqn. 3 could be replaced with  $T_2$  terms as follows:

- $S_w$  is replaced with the  $T_2$  cutoff.
- $(1 - S_{wi})$  is replaced with  $(T_{2max} - T_{2min})$  where  $T_{2max}$  and

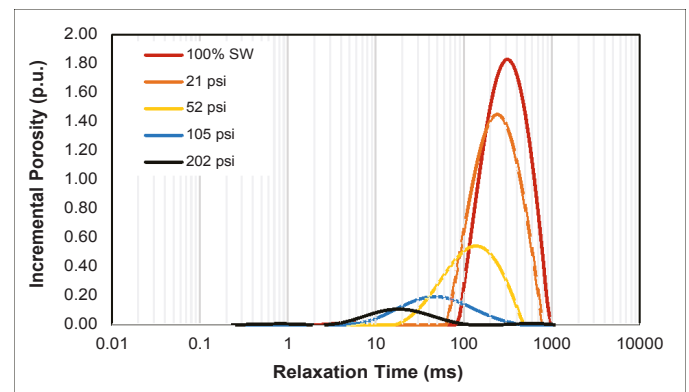


Fig. 4. Relationship between the imposed  $P_C$  and the shift in the  $T_2$  distribution for S5 at  $P_C = 0$  psi (red), at  $P_C = 21.1$  psi (green), at  $P_C = 52.1$  psi (orange), at  $P_C = 105.7$  psi (blue), and at  $P_C = 202.1$  psi (black).

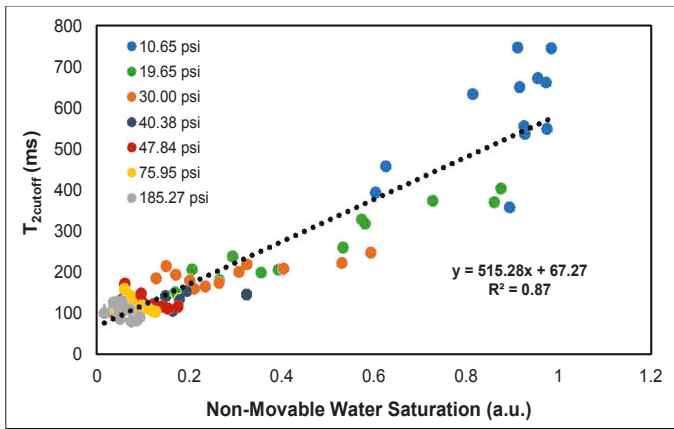


Fig. 5. The relationship between the  $T_2$  cutoff and non-movable water saturation.

$T_{2min}$  are defined in Fig. 6, using S11 as an example.

- $S_{wi}$  is replaced with  $T_{2min}$ .

For the studied samples, it is assumed that any incremental porosity with  $T_2$  relaxation time less than 10 mSec, Fig. 6, will not be produced for an air-brine  $P_c$  range up to  $\sim 200$  psi.

Therefore, Eqn. 3 takes the following form:

$$T_{2cutoff} = (T_{2max} - T_{2min}) \left(\frac{P_c}{P_e}\right)^{-\lambda} + T_{2min} \quad (4)$$

By substituting the following relationship between  $P_c$  and the height above the free water level ( $h$ ):

$$h = \frac{144P_c}{\Delta\rho} \quad (5)$$

where  $\Delta\rho$  is the density difference between the wetting and nonwetting phase, so Eqn. 4 then becomes:

$$T_{2cutoff} = (T_{2max} - T_{2min}) \left(\frac{h}{h_e}\right)^{-\lambda} + T_{2min} \quad (6)$$

where  $h_e$  is the height above the free water level corresponding to the capillary entry pressure.

To generate a height-based saturation curve, Eqn. 6 can be used to fit a full curve of  $P_c$  (or  $h$ )

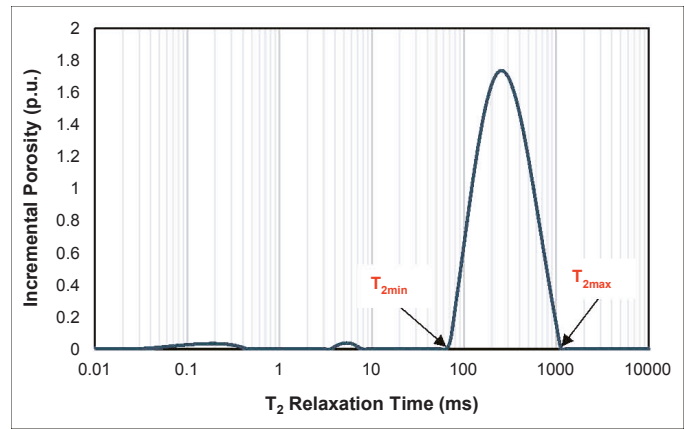


Fig. 6. NMR  $T_2$  distribution of S11 at 100%  $S_w$ .

vs.  $T_2$  cutoff. To generate the  $T_2$  cutoff curve, the workflow in Fig. 7 is followed. The model error was calculated and then minimized to find the optimal solution (fit) using the “log  $S_w$  least squared fit” function given by:

$$Error = \sum (\log(T_{2cutoff-measured}) - \log(T_{2cutoff-calculated}))^2 \quad (7)$$

The reason for selecting this error function is because for capillary pressure like the curve data, the data is nonlinear and is exponential in nature.

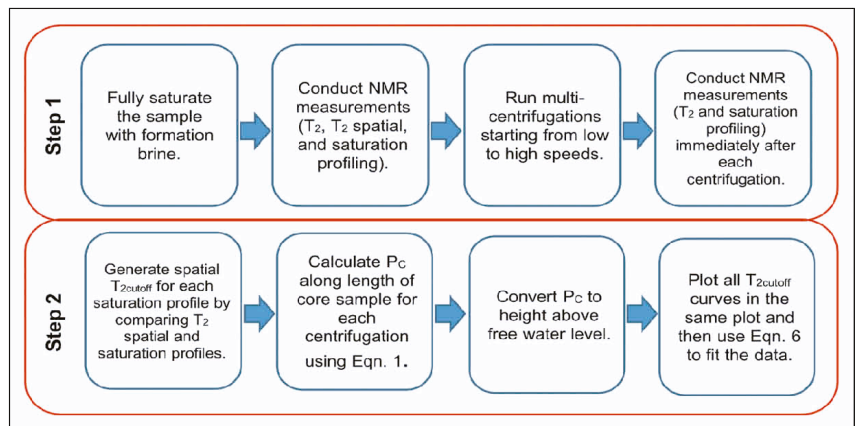


Fig. 7. Steps followed to generate a height-based saturation curve.

NMR Parameter	Saturation Profile	$T_2$ by CPMG <sup>1</sup> Sequence	Spatial $T_2$ by SE-SPI <sup>2</sup> Sequence
Recycling Delay (s)	7,500	7,500	7,500
Echo Delay ( $\mu$ s)	—	59	59
Total Number of Echo Train	—	42,373	42,369
Number of Scan	16	16	16
Field of View (cm)	6	—	6
Number of Steps	—	—	64
Maximum Gradient Strength (gauss/cm)	70	—	70

(1) CPMG: Carr-Purcell-Meiboom-Gill

(2) SE-SPI: Spin-Echo Single Point Imaging

Table 2. Important parameters used for all NMR/MRI measurements using the 2 MHz NMR instrument

## Centrifuge Displacement and NMR/MRI Measurements

A centrifuge system, from CoreLab, was used in this study for air-brine displacement tests. The NMR measurements before and after using the centrifuge were conducted using the 2 MHz GeoSpec Oxford Geospec2 with 1D gradient. Table 2 lists important parameters used for all NMR/MRI measurements.

The general procedure for an air-water displacement test using the centrifuge and NMR measurements is as follows:

1. Protect the core plug's integrity by using heat shrink tubes.
2. Saturate the selected core plugs with connate water under vacuum and then apply 2,000 psi pressure to make sure the core samples are fully saturated with connate water.
3. Conduct NMR base measurements ( $T_2$ , spatial  $T_2$ , and saturation profile) at room temperature.
4. Centrifuge the core sample at room temperature and desired desaturation pressure for 6 hours.
5. Conduct NMR measurements ( $T_2$  and saturation profile) at room temperature.

## Temperature Effect on NMR $T_2$ Relaxation

It is known that reliable, in situ nuclear spin relaxation measurements must be calibrated with laboratory experiments performed on core plugs. The laboratory data are usually collected at room temperature as is the case in this study, whereas reservoir temperatures can be as high as 100 °C. Previous studies of the temperature dependence of NMR relaxation of water in natural rocks showed either a weak and negligible effect<sup>18</sup> or an anomalous temperature dependence<sup>19,20</sup>. The temperature dependence of the NMR  $T_2$  relaxation should therefore be investigated for the core plug samples of this study. Three core plug samples (S13, S14, and S15) were selected for this study.

The main procedure for the temperature dependence test is as follows:

1. Clean and dry the core plug sample.
2. Take the dry weight of the core plug sample.
3. Saturate the selected core plug samples with connate water under vacuum conditions and then apply pressure of 2,000 psi to make sure the core samples are fully saturated with connate water.
4. Seal the core plug sample with a heating shrink tube and Teflon solid disks to prevent fluid losses during handling and testing.
5. Submerge the core plug sample in a sealed bottle filled with synthetic formation brine.
6. Place the bottle with the sample inside the incubator. Set the temperature of the incubator at 25 °C for 8 hours.
7. Take out the sample and immediately conduct a NMR  $T_2$

measurement.

8. Place the bottle with the sample inside the incubator. Raise the temperature of the incubator to 95 °C for 8 hours.
9. Take out the sample and immediately conduct a NMR  $T_2$  measurement.

## RESULTS AND DISCUSSIONS

### NMR $T_2$ and Spatial $T_2$ Measurements at 100% $S_w$

Figure 8 shows the NMR  $T_2$  distribution of all samples used in this study. The figure also shows that the selected samples have in general uniform and narrow pore size distributions. The NMR

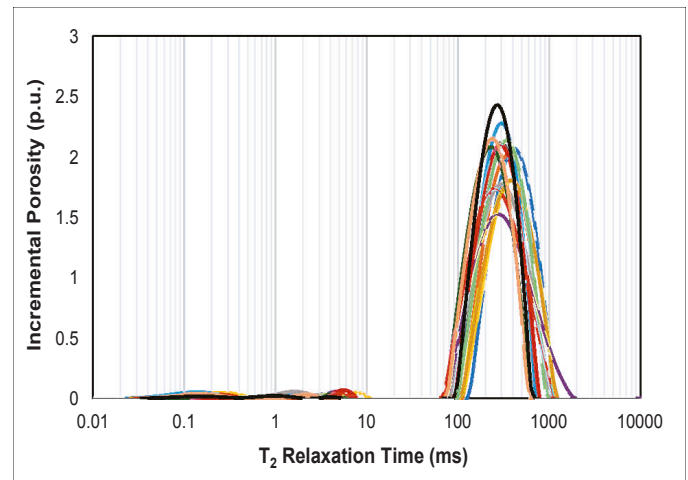


Fig. 8. NMR  $T_2$  distributions of the samples used in this study.

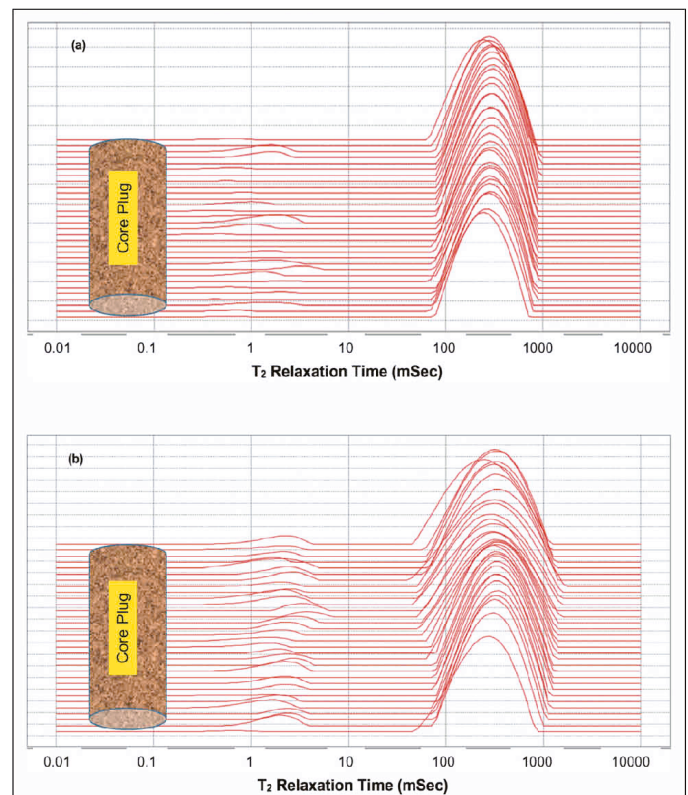


Fig. 9. Spatial  $T_2$  distributions along the length of S7 (a), and S8 (b).



porosity is in good agreement with routine helium porosity.

The results from the NMR  $T_2$  spatial showed that the majority of the selected samples have uniform pore size distribution along the length of the core samples, similar to S7 in Fig. 9a. S8, on the other hand, showed nonuniform  $T_2$  distribution, i.e., pore size distribution, Fig. 9b. In addition, the profiles at 100%  $S_w$  showed that the majority of the samples have uniform porosity along the length of the core samples — similar to S7 in Fig. 9a — except for S2, S3, S6, S7, and S11, which displayed spatial porosity nonuniformity similar to S8 in Fig. 9b.

Figure 10 shows the MRI measured profiles at 100%  $S_w$  for S7 and S8.

### Temperature Effect on NMR $T_2$ Relaxation

Figures 11a, 11b, and 11c, and Table 3 show the results from the temperature effect on the NMR  $T_2$  relaxation for the three core plug samples — S13, S14, and S15 — that were fully saturated with synthetic formation brine. NMR  $T_2$  relaxation measured at 25 °C was compared against the NMR  $T_2$  relaxation measured at 95 °C. The figures clearly show that the NMR  $T_2$  relaxation of the samples will experience a shift toward the longer  $T_2$  relaxation times under reservoir temperature (95 °C). The percentage change in the logarithmic mean of  $T_2$  was used to adjust the  $T_2$  cutoff values measured at a lab temperature of 25 °C. The average percentage change in the logarithmic mean of the  $T_2$  (25 °C vs. 95 °C) of the three samples is 54.93%.

### MRI-based Capillary Pressure

Table 4 presents the fitting parameters of the Brooks-Corey capillary pressure model (Eqn. 2) for S1 to S12. The fitting of capillary pressure data was performed by using GIT software.

The equivalent air-brine capillary pressure from the MICP was consistent with the MRI-based capillary pressure, Fig. 12. The MRI-based capillary pressure method seems to undercall the capillary pressure for the saturation region above irreducible saturation. There are a few possible explanations for this behavior in the studied samples:

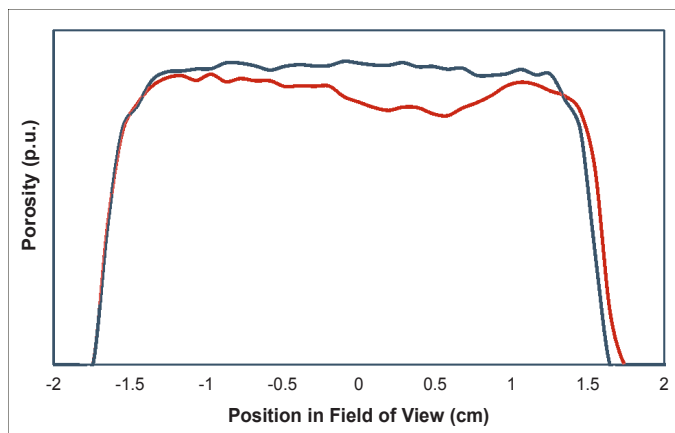


Fig. 10. MRI measured profiles for S7 (black) and S8 (red) at 100%  $S_w$ .

1. MICP was conducted on the sister plugs of the samples used for the NMR study. Therefore, the sister plug samples could have some discrepancy in both rock properties and rock homogeneity.
2. The MRI-based capillary pressure method utilizes centrifugation to initiate saturation profiles at different desaturation pressures. The capillary pressure measurements using

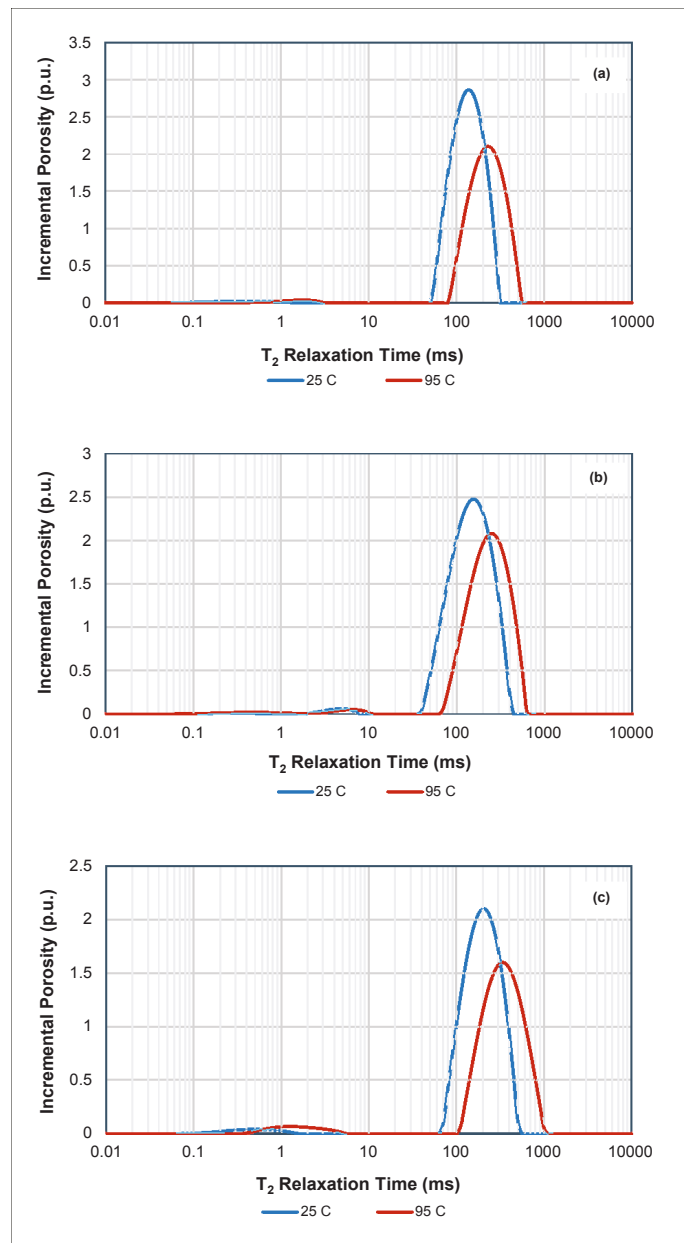


Fig. 11. Temperature effect on NMR  $T_2$  distribution for S13 (a), S14 (b), and S15 (c).

Sample No.	$T_2$ Log Mean (mSec)		Percentage Change in $T_2$ Log Mean (mSec)
	25 °C	95 °C	
13	167.61	254.46	51.82
14	131.45	196.72	49.65
15	123.33	201.42	63.31

Table 3. Results from the temperature effect on NMR  $T_2$  relaxation

Sample No.	$S_{wi}$ (a.u.)	$P_e$ (psi)	$\lambda$	Error
1	0.05	9.44	1.97	$4.42 \times 10^{-5}$
2	0.03	5.92	1.45	$8.32 \times 10^{-5}$
3	0.01	10.81	1.75	$7.7 \times 10^{-5}$
4	0.05	10.57	1.74	$9.9 \times 10^{-6}$
5	0.04	12.04	1.59	$4.64 \times 10^{-6}$
6	0.06	7.67	1.78	$4.64 \times 10^{-5}$
7	0.07	10.12	1.94	$3.59 \times 10^{-5}$
8	0.03	9.79	1.10	$2.07 \times 10^{-5}$
9	0.07	13.72	2.26	$2.22 \times 10^{-5}$
10	0.08	18.85	2.02	0.13
11	0.03	12.53	1.33	$5.14 \times 10^{-7}$
12	0.09	21.76	2.18	0.02

Table 4. Results from fitting the Brooks-Corey capillary pressure model to the experimental data for the selected samples

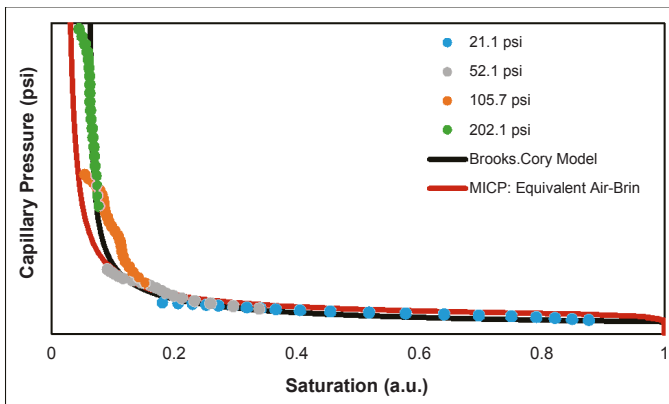


Fig. 12. The MRI-based air-brine capillary pressure vs. the equivalent air-brine  $P_c$  from the MICP.

centrifugation is based on the assumption that the capillary pressure is zero ( $S_w = 100\%$ ) at the far end of the core sample from the center of the centrifugation. This assumption usually cannot be satisfied in practice. There are some other measures that can be applied during centrifugation to minimize the experimental error from not satisfying the zero capillary pressure condition. The most appropriate of these measures is the use of a Teflon disk at the bottom of the sample, which was applied in this study.

- MICP uses a standard mercury air contact angle of  $480^\circ$  that was obtained on a smooth standard rock's surface. In reality, the pore surface of our samples is not smooth, and could be different from one sample to another. Therefore, the use of the standard mercury air contact angle could be a source of error causing the aforementioned discrepancy between the two capillary pressure measurement methods.

Most of the samples showed a mismatch of the capillary pressure curves near the region of irreducible saturation. This is caused by our sample's integrity condition, which mandates the use of maximum centrifuge speed of about 6,500 rpm ( $\sim 200$  psi) to avoid damaging the core sample. Therefore, for some

samples, the irreducible saturation was not reached. Another reason for this mismatch could be the result of using a sister plug as previously mentioned.

For each saturation profile the capillary pressure was computed using the Hassler and Brunner equation at each point and plotted with the saturation percent to create a capillary pressure curve. Figure 13 shows the MRI measured profiles for S7 before and after centrifugation at a different  $P_c$ . The saturation profiles acquired at different centrifuge speeds were plotted on the same curve to expand the range and the resolution of the capillary pressure curve. Fluid redistribution was noticed in some samples for the saturation profiles acquired at the highest desaturation pressures, marked by green and orange curves in Fig. 13. Figure 13 also shows that a fluid redistribution took place at a position in the field of view of 1.5 cm. This could contribute to the mismatch between the capillary pressures obtained by MRI and MICP for the irreducible saturation region.

In summary, since the MRI-based capillary pressure method is reasonably comparable to the MICP method, we can now proceed to construct the NBHS model for our samples.

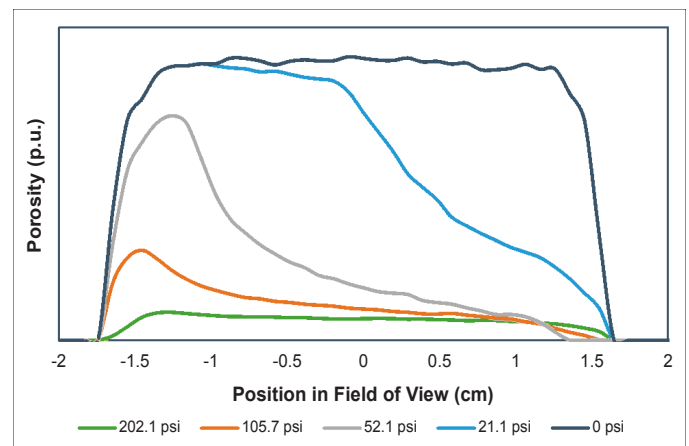


Fig. 13. MRI measured profiles for S7 before and after centrifugation at a different  $P_c$ .

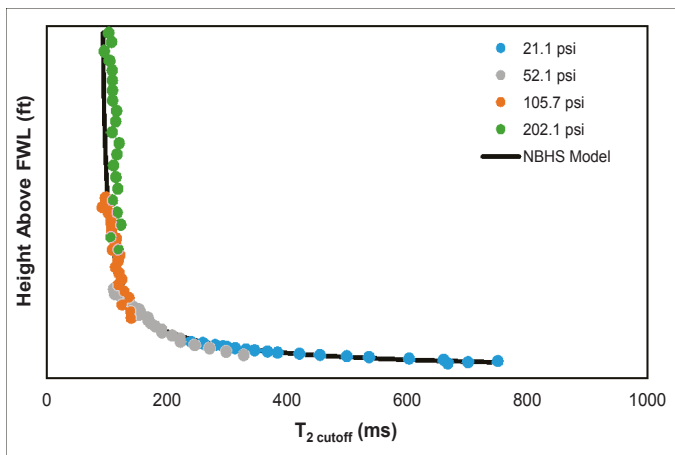


Fig. 14. The NBHS model fit to the experimental data.

### The NBHS Model

The NBHS model was derived by integrating NMR, MRI and centrifugation techniques as previously explained. This allowed the NMR data to be used to determine the capillary bound fluid saturations at multiple elevations from the free water level.

To fit the experimental data with the NBHS model, air-water  $P_c$  was converted to the reservoir height ( $h$ ) above the free water level using Eqn. 8:

$$h = P_{Ca-w} \times \frac{\sigma_{o-w}}{\sigma_{a-w}} \times \frac{144 \cos \theta}{\Delta \rho_{o-w}} \quad (8)$$

where  $\sigma_{o-w}$  is the interfacial tension between the oil and water at reservoir conditions (38.5 dyn/cm),  $\sigma_{a-w}$  is the interfacial tension between the air and brine at laboratory conditions (73 dyn/cm),  $\theta$  is the oil-water contact angle at reservoir conditions (71°), and  $\Delta \rho_{o-w}$  is the density difference between oil (41.52 lb/ft<sup>3</sup>) and water (65.86 lb/ft<sup>3</sup>) at reservoir conditions.

Figure 14 shows the NBHS model fit to the experimental data for one sample, and that the NBHS model was able to precisely model the changes in  $T_2$  cutoff with the height above the

free water level. The  $h_c$  in Table 5 varies from 4.65 ft (S2) to 15.11 ft (S12), while  $\lambda$  varies from 1.42 (S8) to 2.06 (S6). The model fit error rate varies between 0.02 (S4) and 0.36 (S2), and is found in most cases to increase with heterogeneity — spatial porosity as depicted by the saturation profile at initial saturation — of the sample.

### LOG EXAMPLE

Figure 15 shows the application of the height-based variable cutoff model on NMR logs acquired from the studied well

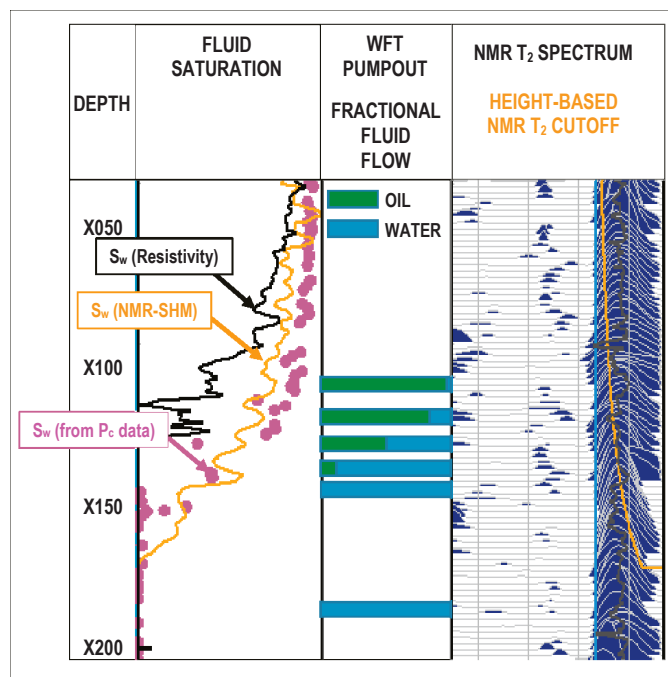


Fig. 15. Track 1: Comparison of fluid saturation calculations using conventional resistivity logs (black), NMR logs using a height-based variable  $T_2$  cutoff described by the NBHS model (orange), and MICP measurements on core plugs (magenta dots). Track 2: Fractional fluid flow measurements observed during wireline formation test pump out measurements. Track 3: NMR  $T_2$  spectrum with the height-based variable  $T_2$  cutoff.

Sample No.	$T_2$ Maximum (ms)	$T_2$ Minimum (ms)	$h_c$ (ft)	$\lambda$	Error Rate
1	1,122.02	141.2	6.74	1.77	0.14
2	1,122.02	125.89	4.65	1.73	0.36
3	707.95	100	8.87	1.92	0.11
4	707.95	100	9.3	2.05	0.02
5	1,000	89.13	8.38	1.59	0.07
6	1,122.02	125	6.92	2.06	0.25
7	891.25	100	6.9	1.54	0.27
8	1,778.28	79.43	5.31	1.42	0.27
9	707.94	89.13	9.39	1.65	0.10
10	562.34	79.43	15.96	1.99	0.15
11	1,122.02	70.79	8.24	1.44	0.16
12	562.34	79.43	15.11	1.58	0.04

Table 5. The results from fitting the NBHS model to the experimental data for the selected samples



where the logging program included conventional and NMR logs, and wireline formation testing. The NMR  $T_2$  spectrum is shown in Track 3 along with the height-based variable cutoff where prior information on the free water level from nearby wells has been in good consistency with the formation pressure gradient observations in this well.

In Track 1 is a comparison between water saturations calculated from conventional resistivity logs (black), the new NMR log-based saturation model (orange) and MICP data (magenta dots), converted to reservoir conditions using prior information on reservoir fluid densities, interfacial tension and a fluid-surface contact angle. The NMR-based saturation model is in excellent agreement with the MICP-based saturation calculation, commonly considered as the ground truth for the reservoir description. Track 2 shows fractional fluid production at six wireline formation test pump outs. The MICP and NMR-based saturation models are consistent with fluid production percentages.

## CONCLUSIONS

This article presents a two-step NMR calibration and log processing workflow to calculate fluid saturation in a low permeability carbonate formation where resistivity interpretation is challenging. First, a series of laboratory measurements was performed on 15 core samples from the transition zone of the target reservoir to calibrate NMR responses to capillary pressure data. Special care was taken to account for the effect of temperature for implementation to downhole measurements. Second, a model was developed to enumerate fluid saturation using a variable NMR  $T_2$  cutoff as a function of displacement pressure that is related to the height above the free water level. This model was implemented for the processing of downhole NMR logs to obtain a continuous fluid saturation profile across a wellbore. The following conclusions were drawn from this study:

1. A new, specifically customized equation was developed to model the HBVI cutoff in the LRP zones of a low permeability carbonate reservoir.
2. NMR-based capillary pressure data demonstrated good agreement with MICP-based capillary pressure data. This allowed the NMR relaxation spectrum to be calibrated with capillary pressure data at various reservoir displacement pressures.
3. The NMR  $T_2$  relaxation of the samples obtained at lab temperature (25 °C) shifted toward longer  $T_2$  relaxation times under reservoir temperature (95 °C). The average percentage change in the logarithmic mean of  $T_2$  (25 °C vs. 95 °C) of the three samples is 54.93%.
4. The results of log-based saturation modeling are in excellent agreement with capillary pressure-based saturation calculations and are consistent with fractional fluid flow observed

by wireline formation test pump out measurements.

5. Once the method is calibrated, the log processing workflow requires a basic NMR log only. The stand-alone NMR-based procedure is a good complement to saturation modeling based on other log measurements.
6. In view of considering the directional insensitivity of NMR measurements, the workflow is applicable for both vertical and horizontal wells without any modification.

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# Distributed Fiber Optic Sensing: A Technology Review for Upstream Oil and Gas Applications

Frode Hveding and Dr. Ahmed Y. Bukhamseen

## ABSTRACT

Real-time downhole measurement is essential for monitoring and optimizing well performance. For advanced wells, this enables zonal flow evaluation, which leads to production control adjustments and ultimately closed loop optimization. The challenge is to turn these real-time measurements into real-time decisions for effective reservoir and production management. Optical fibers provides a great opportunity to achieve this in an economic and safe manner. This is because fiber optics is a non-intrusive tool that has the ability to detect acoustic and thermal effects anywhere along the well with very high frequency sampling both in terms of space and time.

The article will establish the basic understanding of distributed measurement principles. Then, it will cover the different installation methods based on the parameter of interest. The fiber deployment can occur during initial well construction, or after completing the well as an intervention. The remainder of the article focuses on different possible applications of distributed acoustic sensing (DAS) and distributed temperature sensing (DTS) that strive to solve day-to-day oil field challenges. The task of using real-time fiber optics measurements to monitor well performance is very complex and requires involvement from several disciplines within an organization. To illustrate the complexity of this task, we discuss the application of using distributed measurements for production and injection profiling as an example. An overview of algorithms commonly used to interpret flow from DAS and DTS measurements is presented. Furthermore, the use of DAS and DTS for sand detection and wellbore integrity applications is explained. Each application is supported with examples, with the goal to provide reservoir and production engineers guidance to identify appropriate solutions for their challenges.

## INTRODUCTION

Distributed optical fiber sensing was first demonstrated by Southampton University in 1981. The oil industry was an early adopter and introduced distributed temperature sensing (DTS) in the early 1990s using intervention-based techniques to lower the fiber optic cable inside the wellbore<sup>1</sup>. The ability to observe an absolute temperature measurement every meter along

the fiber optic cable provided new insight to complex thermal effects inside the borehole. Since this early start, multiple advancements in the fiber optic domain has further enhanced the number of applications this technology can be used for.

The first application of distributed acoustic sensing (DAS) was completed in Canada in 2009 for fracture monitoring<sup>2</sup>. This was the start of a potential game changer for optical fiber optic sensing. New applications were added to the growing portfolio of fiber optic downhole sensing. Consequently, the introduction of DAS posed some unique challenges, in particular, how to handle the vast amount of data generated. Multiple gigabytes per minute were obtained during the sensing of a multiple km deep wellbore. This data volume has to be managed effectively to extract the information needed in a timely manner. Lately, introduction of edge computing and advanced machine learning algorithms for pattern recognition enables the data to be managed locally. The output is then communicated to central locations for further analysis. The raw data itself is in general too large to keep, therefore, smart processing algorithms are under constant development and continues to be introduced for improved solutions.

An additional aspect that makes the usage of fiber optic sensing both challenging and rewarding is the ability to combine different fiber optic cables and laser boxes. With the same installation, the user is able to solve multiple applications simultaneously using different algorithms and analysis methods. For instance, a tubing to annulus leak in the overburden is possible to find while performing flow allocation analysis of an injector or a producer across the reservoir section. Instant logging is possible where the fiber is replacing traditional production logging tools. Current solutions might not be 100% comparable to production logging, but the fiber optics provides the possibility of real-time analysis while capturing interesting aspects of the dynamic environment, although it is not possible to obtain the same information with traditional point measurements.

Due to the versatility of the measurement type and content from fiber optics, many applications have been identified in the oil and gas industry. Some of them are well-known and others are still in the research phase. The list is still growing and existing applications are improving as more trials are completed on the field. As such, it has been quite overwhelming for newcomers to get familiarized with the technology. The objective of this



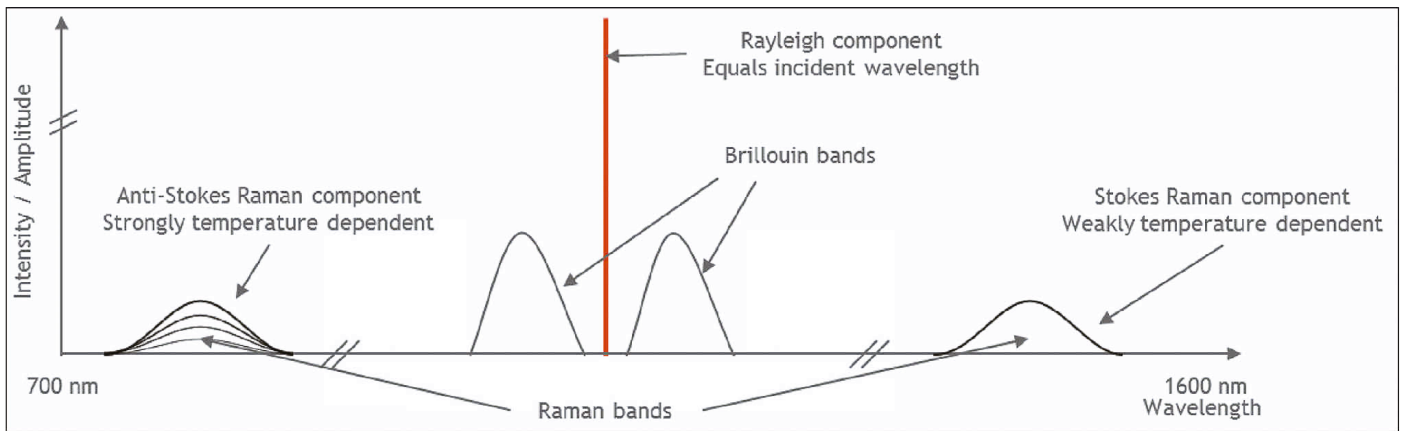


Fig. 1. Different wavelength bands of the laser's backscattered light.

article is to provide an easy entry point into distributed fiber optics by giving an overview of DAS and DTS applications in the upstream section. The review covers monitoring and installation methodologies along with the most common challenges that can be addressed with fiber optic sensing. Distributed pressure sensing and distributed chemical sensing are two of the latest additions to the growing fiber optic solutions, but they will not be discussed in this article.

## MEASUREMENT METHODS

Fiber optics have the unique advantage of instant measurement along the entire fiber optic cable. The laser acquires data thousands of times per second as it interacts with the crystalline structure in the silica-based core of a fiber optic cable. Physical effects, like thermal and pressure variations — noise/sound — will affect the glass structure causing oscillations in the glass core. As a result, the laser light is scattered in all directions with some of the light scattering back to the laser box. Basically, scattering losses are caused by the interaction of light with density fluctuations within a fiber. These density changes are impurities produced when the optical fibers are manufactured. As the optical pulse moves down the fiber, the glass, lattice structure and molecules are energized. Its backscattered spectrum consists of the Rayleigh band, the Brillouin band, and the Raman band, Fig. 1; where DAS is measured from Rayleigh scattering and DTS from Raman scattering.

The Rayleigh band is the strongest backscatter and is an elastic scattering mechanism, where the scattered photons have the same energy — frequency and wavelength — as the incident photon. A small fraction of the scattered photons are scattered by an excitation. This inelastic scattering, Raman scattering, leads to two possible outcomes: (1) Stokes Raman scattering, where the material absorbs energy and the emitted photon has a lower energy than the absorbed photon, and (2) Anti-Stokes Raman scattering, where the material loses energy and the emitted photon has a higher energy than the absorbed photon. Anti-Stokes scattering is temperature dependent while the Stokes scattering is not. The difference between these two

measurements determines the absolute temperature.

The Brillouin scatter is a nonlinear scattering effect involving acoustic photons. A frequency shift occurs, Brillouin frequency shift, and depends on the material composition and to some extent the temperature and pressure of the medium. The Brillouin shift can be calculated from the refractive index, the acoustic velocity and the vacuum wavelength. The Brillouin Stokes and anti-Stokes bands are affected by both temperature and strain.

The two main fiber optic measurements widely acquired today are DAS and DTS. In general, DTS is measured using multi-mode fiber optic cables while DAS is derived from single-mode fiber optic cables. The difference between the two fiber types are basically the size of the core, Fig. 2.

Generally, there are two main wavelengths used to detect DAS and DTS using standard silica-based fiber optic cables. There are certain wavelengths of the fiber optic signal that causes absorption of the light, Fig. 3. Water in silica glass forms a silicon-hydroxyl (Si-OH) bond. This bond has fundamental absorption at 2,700 nm and harmonics occurring at 950 nm, 1,250 nm, and 1,383 nm. These absorptions areas are referred to as the “water bands.”

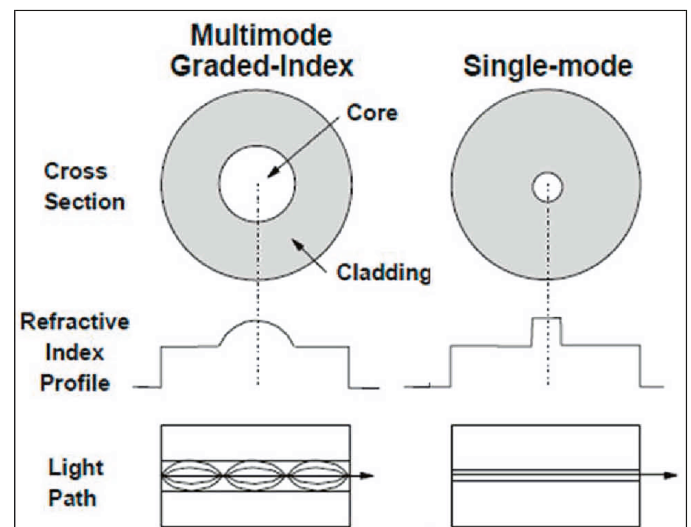


Fig. 2. Comparing multi-mode and single-mode fibers in terms of the cross-section, refractive index, and the laser light path.

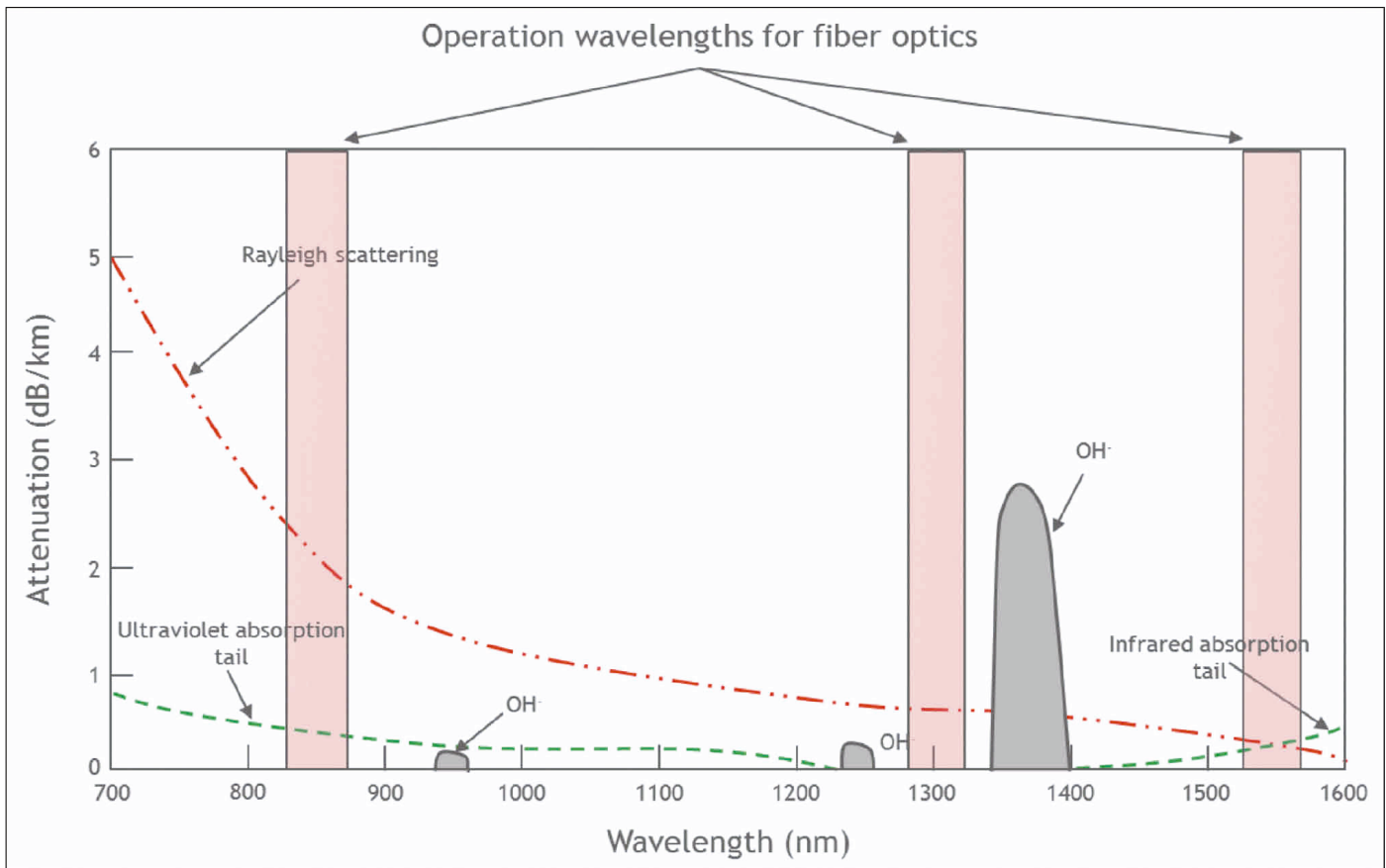


Fig. 3. The “water bands” plotted in an attenuation vs. wavelength plot to show common wavelengths that causes absorption of the light.

## INSTALLATION METHODS

There are three main methods for getting the fiber optic cable into the wellbore, where it is exposed to the variations in temperature and noise during production or injection<sup>3</sup>. These methods are permanent installations, semi-permanent installations, and intervention-based service.

Permanent installation is obtained by strapping a fiber optic cable outside the casing and cementing it in place, Fig. 4a. The fiber can then be used to observe the heat being generated during cement curing, and thereby give indications of the height

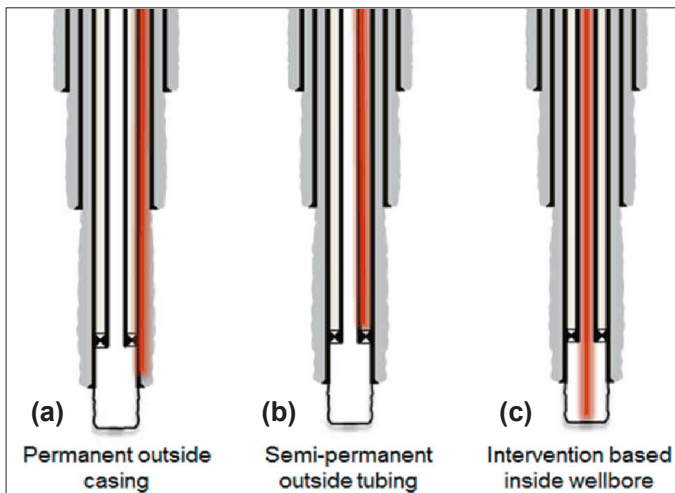


Fig. 4. Different methods to install a fiber optic line in the wellbore.

of cement and also its potential quality. In addition, since the fiber is directly coupled to the sand face, it will be able to provide valuable information about production related effects if it is placed across the reservoir. Other applications like vertical seismic profiling and geological subsidence can also be detected with this fiber placement using the right combination of laser box and fiber optic cable.

In a semi-permanent installation, the fiber optic cable is strapped outside a tubing and is exposed to the annulus between the tubing and the casing, Fig. 4b. If the tubing is pulled out, the fiber will also be removed. Normally, this installation limits the fiber to be in the upper completion only above the production packer. Although it is possible to also include the fiber in the lower completion, it is a complex process and not commonly utilized. This installation can be particularly useful for tubing to annulus leak detection. In populated areas, and with ground water protection in mind, it is very useful to obtain integrity information in real-time without having to open and enter a well.

Both of these methods require a higher capital cost and lower operational cost. Subsequently, the main advantage with these methods is that the user is able to acquire instant down-hole logging without accessing the wellbore simply by attaching either a DAS or DTS laser box (or both) to the fiber optic cable(s) available at the surface.

The third method involves running fiber optics downhole as an intervention-based service. This method can be very useful

in cases where the well does not initially include a fiber optic installation, Fig. 4c. The ability to position the fiber optic cable across the entire reservoir increases the value of this method. In addition to the applications enumerated for the permanent and semi-permanent installations, the flexibility enables the user to obtain information like production flow allocation, injection flow allocation, cross flow determination, flow behind casing, and much more<sup>4, 5</sup>.

Having the fiber optic cable inside the fluid flow in the tubing directly captures the fluid flow dynamics. A fiber optic cable can be run into the wellbore in three main intervention-based methods:

1. Fiber optic cable embedded in a coiled tubing. In this case, the fiber is located inside the coiled tubing and can provide information like injection profiling after a stimulation job.
2. Fiber optic cable embedded in a wireline or a slick line. This works well in low angled wellbores — typically < 60° deviation. If the hole angle is > 60°, a tractor can be connected to pull the fiber across a horizontal section. This can be an attractive solution to ensure the fiber is placed across the zones of interest and is a low cost solution in low angled wellbores.
3. Fiber optic included in a semi-stiff composite carbon rod<sup>6, 7</sup>. The slim design of the carbon rod (~0.6” outer diameter) enables easy access to horizontal wellbores that have high restrictions, e.g., a downhole electric submersible pump (ESP) with a Y-tool. In general, the Y-tool is too narrow for a tractor to pass through, therefore, the wireline/slick line option is no longer valid. The composite carbon rod can be pushed into long horizontal wellbores from the surface, without the need for tractors.

Once placed across the zones of interest, it is possible to investigate multiple applications during the same run. One example would be that leak detection behind casing can be investigated at the same time as downhole injection profiling.

## APPLICATIONS AND BEST PRACTICES

The applications discussed in this article focus on selected production related challenges, but other fields such as geophysics, have had positive results in using DAS for seismic application. Other current and potential applications for using DAS and DTS are listed in Table 1. We start by discussing inflow point identification applications as this demonstrates the basic capabilities of fiber optics. Then, details about other applications such as wellbore integrity, sand detection, and injection and production allocation are presented.

### Inflow Point Identification

The key to understand temperature logs is to connect the various temperature variations with flow conditions. Factors like geothermal gradient and the Joule-Thomson effect are important to understand to characterize and analyze the flow in the wellbore.

Reservoir or injection fluids, are either cooling or heating the environment downhole. The geothermal gradient is a temperature measurement of the Earth at various levels. In general, this gradient is increasing with increasing depth and is like a signature of the heat exchange factor for various geological layers. Although, if the well is being produced, or if there is injection into the well, the temperature measured will deviate from the geothermal temperature. The variation in temperature vs. the geothermal gradient can be used to quantify the production or injection. Figure 5 illustrates a good example of the dynamic temperature effects that can be observed over time depending on the fluid type flowing to the wellbore.

The Joule-Thomson effect is a well-known phenomenon that is actively used in the fiber optic analysis of DTS data<sup>8</sup>. In general, a gas entry into the wellbore with a certain pressure differential causes a cooling effect. The gas composition, delta pressure, and flow rate (volume) has an effect on the amount of cooling observed. Similarly, if a liquid enters the wellbore it experiences a heating effect due to the same pressure drop. This is more related to frictional heating.

The temperature is measured thousands of times per second over the entire length of the fiber optic cable. To improve the

Production	Reservoir	Geology	Geophysics	Integrity
Injection/Production flow allocation	Water breakthrough	Overpressured zones	Vertical Seismic Profiling	Tubing to annulus leaks
Injection/Production optimization	Bubble point production	Unconsolidated zones – sand production	Microseismic	Casing to casing leaks
Multiphase flow characterization	Fracture monitoring			Gas lift valve leak
Flow regime recognition	Cross flow identification			Scale/Wax build-up
	Well interference testing			ESP/Packer evaluation

Table 1. Summary of current and potential applications using DAS and DTS

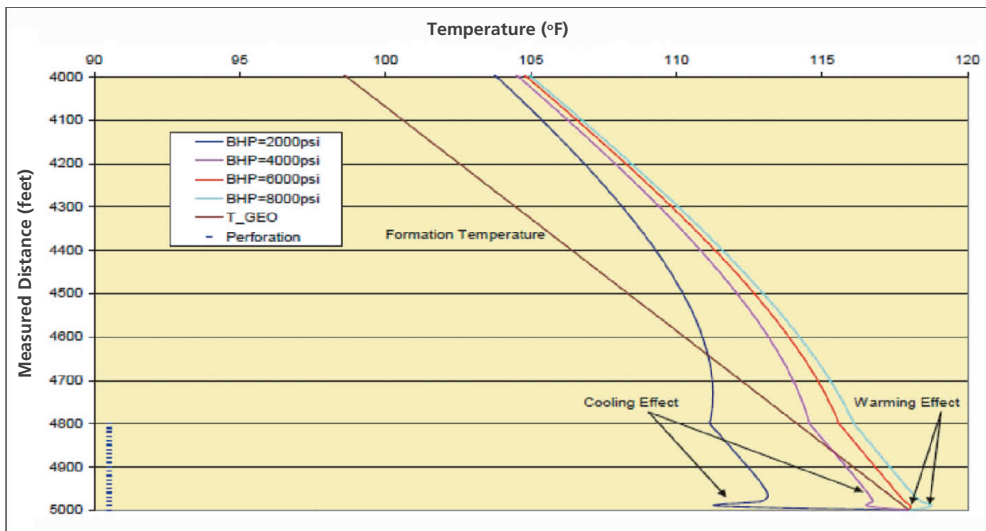


Fig. 5. Dynamic well flow conditions, including the cooling and warming effects that are easily captured by DTS<sup>8</sup>.

signal to noise ratio and increase the temperature resolution, it is normal to stack the readings over a period of time, Fig. 6<sup>9</sup>. The advantage of stacking the data is that the temperature resolution improves. The disadvantage with too long of stacking is that the small variations in temperature could be missed. For instance, gas can enter the wellbore in squirts instead of a steady flow. The local cooling effect would be visible only in a short period of time before potential liquid coming from below heats up the area again.

The second measurement gaining more popularity in this domain is the DAS. DAS is capable of measuring both the amplitude and the frequency of sound waves downhole, or noise as it is normally called. Noise logging is not a new technology in the oil industry and was first introduced in the early 1950s for leak detection. In Stein et al. (1972)<sup>10</sup> a method of using acoustics to establish maximum sand free production was described. McKinley et al. (1973)<sup>11</sup> presented work to characterize the noise amplitude and frequency spectrum for flow of air and water across a small orifice with certain pressure drops. When DAS was introduced, it opened up for all the classic noise logging methods in addition to much more. The ability to

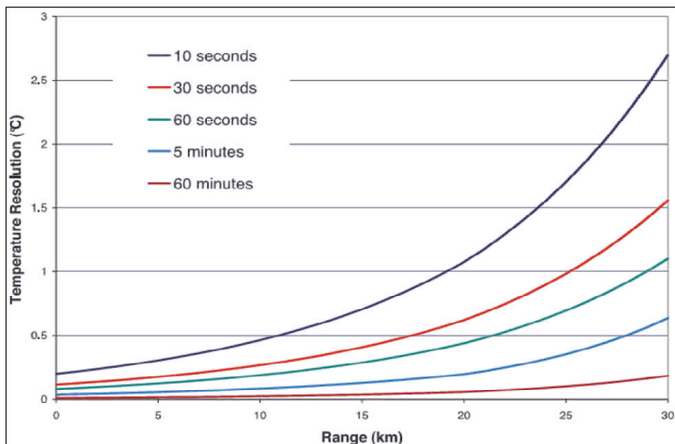


Fig. 6. Achieving improved DTS resolution with averaging temperature values over longer periods of time. Longer fiber optic cables require more stacking for improved resolution<sup>9</sup>.

listen to noise along the entire fiber optic cable establishes an opportunity to capture the dynamic variations caused by flow downhole. And not just that; sound effects of fracturing in neighboring wells, leak detection behind casing, sub-seismic events caused by overpressured zones, and much more, can be analyzed with DAS. A number of these applications will be discussed later.

With fiber optic across the reservoir, it is possible to capture information about the various areas of production all the time. In other words, the fiber has the ability to observe all parts of the well, all the

time. Conversely, traditional wireline-based production logging provides a point measurement and has to be moved up and down a wellbore to map the different production zones. For example, a point measurement method could not track a moving slug as it moves up the well. Having the ability to observe the entire wellbore simultaneously, with spatial resolutions lower than a meter, enables a new level of dynamic information. There are several ongoing research projects to further improve the understanding of DAS and DTS.

## Wellbore Integrity

Dealing with live hydrocarbons can be a challenge unless there are measures in place to handle it properly. Multiple barriers are installed to secure a safe production environment. In case of a downhole leak, it is important to identify the leak location and what kind of leak it is. There are multiple wellbore integrity scenarios that can take advantage of distributed fiber optics, such as: tubing to annulus leak (tubing to casing leak), flow behind casing (casing to casing leak), gas lift valve leak (plugged vs. active), and leaks around packers and the casing shoe. In addition, other challenges like high-pressure zones in the overburden that receives injection fluid from a nearby injector, can be monitored with distributed data.

In the first scenario, the tubing to casing leak, the leak is identified by a pressure buildup in the annulus. Depending on the severity of the leak, the pressure is bled off regularly to avoid unsafe pressure level; however, identifying the source of the leak can be a challenge. Fiber optics have been used successfully for this task several times. The ability of fiber optic to sense the entire length of the fiber simultaneously makes it possible to identify the source of the leak, or multiple sources, within the time it takes to bleed off the annulus pressure.

Both semi-permanent fiber optic and intervention-based fiber optic can solve this challenge quite effectively. Normally, even if only annulus A (between the tubing and first casing) has a pressure buildup, it is good to perform a health check



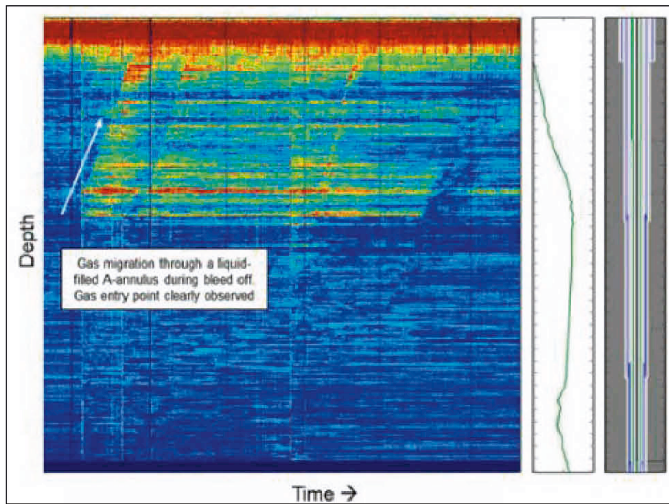


Fig. 7. A DAS waterfall plot in a wellbore integrity application to track gas leaking from a source in annulus A<sup>5</sup>.

between other casings as well. With fiber optics across the sensing area, we start by keeping everything shut-in for some time to establish a baseline. This baseline could last for 2 to 3 hours to ensure fluids have stabilized. Then, annulus C is bled off as quickly as possible while keeping the tubing, annulus A and B completely shut-in. The speed of bleeding off is important as we want to aggravate the potential flow or leak as much as possible to sense it. The only noise source now is the movement of fluid in the annulus, in particular if there is a leak at a certain point. After bleeding down to low pressure, the sequence can be repeated depending on the rate of pressure buildup. The same operation should be repeated for annulus A and B. Typically, you can spend a few hours on the buildup and a few hours on the bleed down. The whole operation can take up to 24 hours to complete, Fig. 7.

### Sand Detection

Unconsolidated reservoirs pose big challenges when it comes to sand production. Erosion of downhole and surfaces pipes can lead to catastrophic results. Fiber optic data is ideal to observe multiple zones at the same time. This enables the user to observe exactly the conditions when sand production starts. The well can be tuned to obtain maximum sand-free production. The key here is to distinguish formation sand ingress from other noisy phenomena in the well, such as fluid flow and background noise.

To accomplish that, the data has to go through rigorous testing to classify the noise pattern from DAS as sand production. Thiruvankatanathan et al. (2016)<sup>12</sup> have performed some long-term tests in multiphase flow loops with multiple vendors to be able to positively identify the sand signature. Once the acoustic fingerprint of sand production has been empirically derived, a model was constructed with the understanding of the underlying physics.

After establishing confidence in the models, data were collected from a well with known sand production problems. The

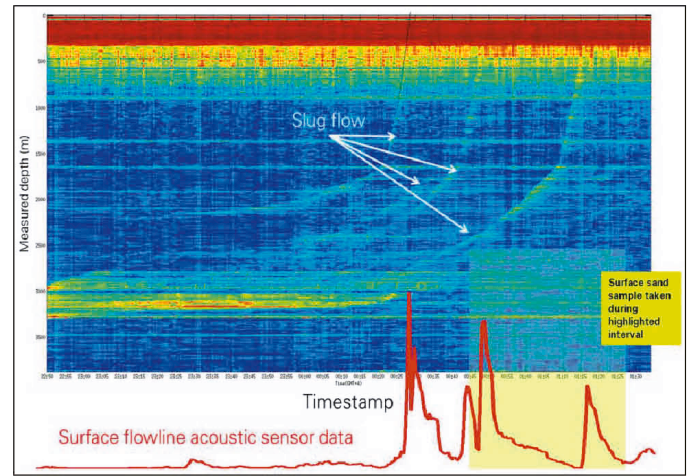


Fig. 8. A DAS waterfall plot showing sand slug movement up the wellbore. Peaks in acoustic noise in the surface coincides with the time of the slug arrival to the surface<sup>5</sup>.

data from this well was processed to filter out frequencies associated with background flow and instrumentation noise. The resulting signal was referred to as a “sand log” after averaging through time across the whole reservoir section. When time-depth DAS measurements are monitored over long periods of time, it is possible to track the transport of sand particles from the inflow point all the way to the surface. Figure 8 indicates consistency between the time that the sand slug hits the surface and a peak at the surface flow line acoustic sensor.

### Injection Profiling

An injection profile is something the fiber optic cable is able to resolve quite nicely. Two main methods are used to determine the injection profile: (1) hot slug tracking, and (2) warm back analysis. The hot slug method consists of tracking the movement of a slug at a different temperature than the surrounding fluid. Normally, in an injector well, this slug is generated by shutting in the well for a period of time and letting the temperature in the well increase toward the geothermal gradient. In the cased off section above the reservoir, the temperature profile is not affected by cold fluid previously injected and the temperature moves quite fast toward the original geothermal gradient. If the well has already been on injection for some period of time, the reservoir has cooled down to a lower temperature just because of a constant feed of colder fluid.

After an initial shut-in period to obtain a stable reference geothermal gradient, the well is put on injection. The hot slug is visible both on DAS and DTS and moves down with the speed of the fluid. On a depth time-based plot, the slope angle of the slug equals the flow velocity. If we assume that the top section takes some injected fluid volume, the remaining fluid available for zones below it will be less. In other words, the slug velocity will slow down. So, for a hot slug tracking, the slope of the hot slug front will be directly related to the amount of fluid lost in every injection zone.

The warm back method is considered more preferable for

quantitative injection allocation. Here, the geothermal gradient from the shut-in period is very important to obtain. This will act as the baseline for the quantitative analysis. Again, the well is put on injection for a certain period of time. A stable injection period — length depends on the flow rates and reservoir permeability — is needed to get representative values. Then, the well is shut-in while the fiber optic cable is still in place across the reservoir. Once the reservoir stops taking fluids, the temperature curve will slowly move toward the initial baseline. Zones with little injected fluid will move faster toward the baseline while zones with large quantities of cold injection fluid will heat up slower. The rate of warm back for each individual zone is therefore directly related to the amount of fluid injected into this zone.

Since the fiber can obtain real-time information from the entire wellbore while injecting, the operator can optimize the injection rate. For instance, if the user observes a cooling — from DTS — and high noises — from DAS — from just the heel of the well, it is clear that the remaining part of the reservoir does not receive any injection fluid. To test out the optimal injection rate, the operator can vary the injection rate until a better distribution is obtained. The optimization procedure can be made more effective if the well is equipped with smart completion to control intake for each zone. This real-time information is very important to tune the injection rate.

## Production Profiling

To use DTS for quantitative production analysis, multiple parameters must be considered. These include heat transfer due to both conduction and convection, frictional heating or cooling, skin effects, and phase changes in the wellbore. There are software that uses an enthalpy balance model to account for all these effects in an iterative process for a best possible match between the model and data. The challenge with DTS is potentially the delayed response in time. As previously shown in Fig. 6, to obtain high temperature accuracy, the user has to select a measurement period that is often one minute or longer. Another challenge arises in true horizontal wellbores where the geothermal gradient is almost the same, which means that the temperature along the entire reservoir area will be very similar. In this case, one cannot rely on DTS to obtain flow related information directly and DAS should also be used. When liquid or gas enters the wellbore through an inflow port, it creates noise, which is picked up by the DAS system. In general, the higher the amplitude, the more flow. In other words, there is a relationship between flow volume and the DAS amplitude. In addition, frequency can be used to potentially differentiate between gas and liquid.

Recently, DAS, either in combination with DTS or stand-alone, has been extensively analyzed for production profiling. We present three main methods that have been used in the literature to obtain quantitative flow information.

1. Combination of DTS and DAS amplitude and frequency.

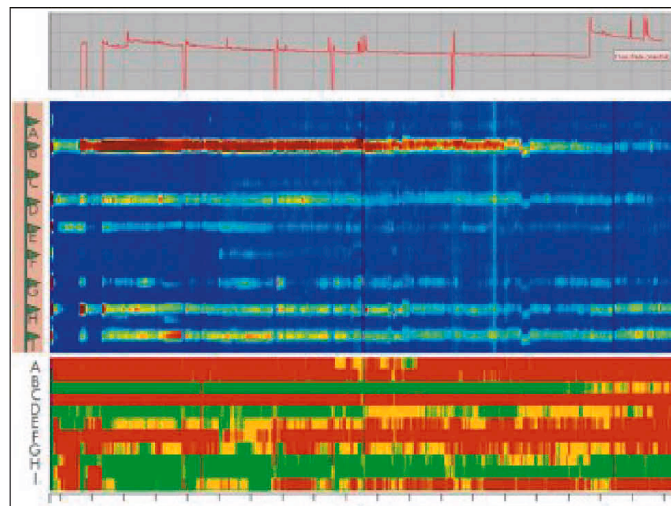


Fig. 9. The top graph shows the well surface production as a function of time. The middle graph shows a DAS waterfall plot with noise amplitudes — blue is silent and red is loud. The bottom graph converts the noise amplitude plot into production (green) and no production (red) for the various production zones<sup>11</sup>.

Van der Horst (2015)<sup>13</sup> developed a traffic light system that automatically relates the amplitude/frequency response to either production or no production. After selecting the DAS frequency band that correlates to fluid flow, peak amplitudes in each production zone are averaged over time. The sum of all production zones is normalized to the measured flow rate at the surface, and the production per zone is allocated proportionally, Fig. 9.

2. Focus on phase-based DAS data to obtain speed of sound. The calculation of speed of sound using DAS data depends on the ability to track phase coherent propagating acoustic waves in the frequency space ( $f$ - $k$ ) domain. This is an involved process, which starts by selecting a representative time-distance DAS window and then transform it to the  $f$ - $k$  domain by applying a 2D Fourier transform. The speed of sound within the fluid medium is estimated from the slope of high Fourier coefficients in the resulting plot. Flow velocity is then calculated by the difference between upgoing and downgoing speeds of sound — the Doppler shift principle. Similarly, in situ fluid phase fractions can be estimated by applying speed of sound mixing rules of the single phases involved. This procedure was summarized<sup>14</sup> and is depicted in Fig. 10.
3. Use of lower frequency DAS data to track velocity of flow eddy currents. Turbulent pipe flow is inherently associated with self-generating pressure fluctuations (eddies) that can be captured by the sensory array in the fiber optic cable. When this DAS data is transformed to the  $f$ - $k$  domain (similar to the previous method) the signal is deconvolved into its frequency and wavelength components. This would usually show a straight line in the lower frequencies in the  $f$ - $k$  plot, Fig. 11. As eddies travel with a velocity near the volumetrically averaged flow velocity, the flow velocity is estimated from the slope of that line<sup>15</sup>.



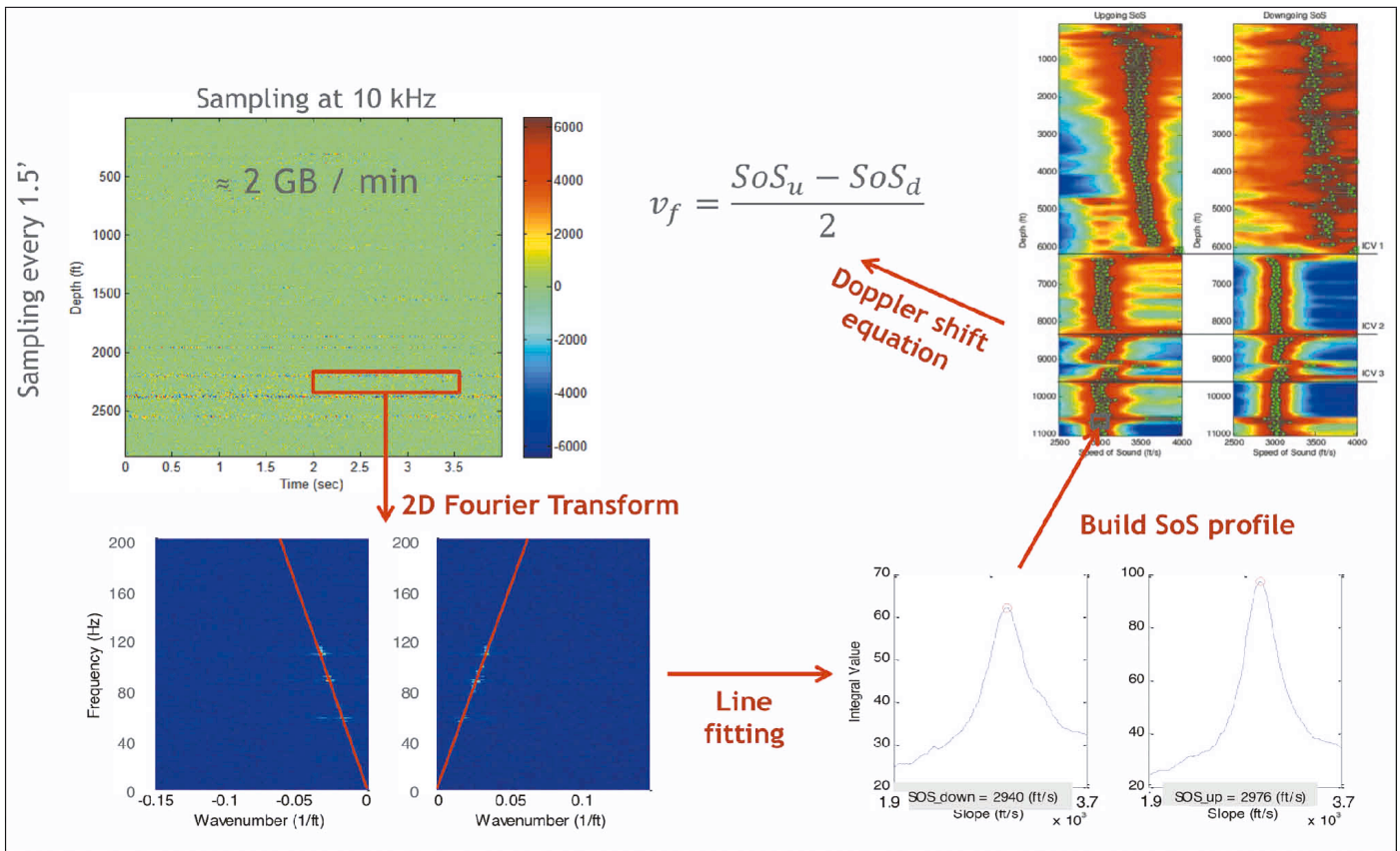


Fig. 10. Speed of sound calculation steps involving a  $f$ - $k$  slope line fitting and Doppler shift velocity estimation.

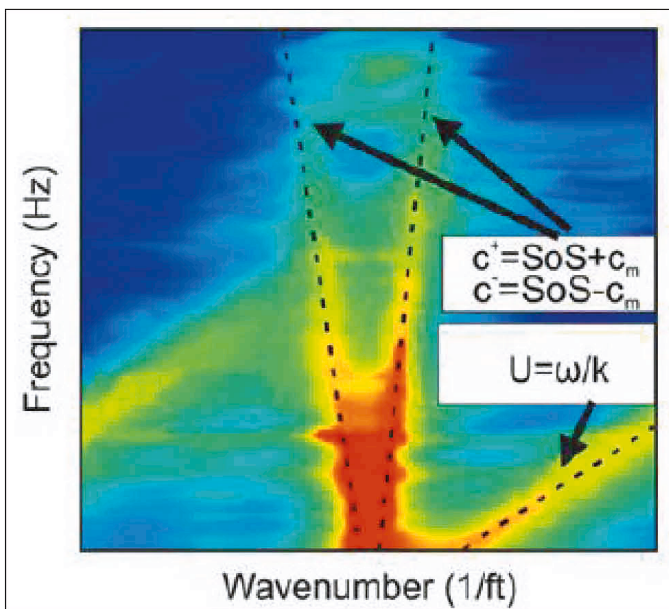


Fig. 11. Frequency wavenumber plot that results after applying 2D Fourier transform to DAS data. Convection velocity is shown as a straight line in the lower frequencies.

## CONCLUSIONS

As with other technologies in the industry, fiber optics monitoring systems have been progressively evolving. Nowadays, the different types of measurement can be collected continuously with time and distance, and with high measurement fidelity. Due to its relatively low cost and the wide distance range it

covers, distributed fiber optic systems are viewed as an attractive monitoring option for all well types. With the increasing data flow, new algorithms have been developed and demonstrated on the field to assist with real-time decisions and deliver value from the system. With the recent advancement in computational modeling, more emphasis should be placed on machine learning, automation, and data driven models, which work quite well with the high data flow rate in DAS applications.

In this article, we have discussed the basic working principles of distributed fiber optics and how to deploy the fiber in the well. Careful system design should be performed to place the fiber in the region of interest, depending on the desired application. Despite presenting several working applications here, many industry experts believe that we have not unlocked the full potential of the value that DAS and DTS promises to deliver.

## ACKNOWLEDGMENTS

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## BIOGRAPHIES



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### **Critical Factors Affecting Pulsed Neutron Saturation Monitoring in Carbonate Reservoirs**

*Yahia A. Eltaher, Dr. Shouxiang M. Ma, and Mamdouh N. Al-Nasser*

#### ABSTRACT

Pulsed neutron (PN) spectral carbon-oxygen (C/O) logging is a widely used shallow measurement for time-lapse reservoir saturation monitoring. Because of its shallow depth of investigation, its measurement is affected by several factors, among which the near wellbore logging environment is the most important. For example, hole condition, cement quality, and fluids in the wellbore have drastic effects on C/O measurement. Some of these effects, such as those due to oil holdup in the wellbore, can be corrected for in the data post-processing.

### **New, Integrated Approach to Diagnose, Characterize and Locate Interwell Fracture Connectivity in Carbonate Reservoirs from Transient Test Data**

*Omar H. Al-Obathani, Bandar A. Al-Wehaibi, Faisal M. Al-Thawad, and Dr. N.M. Anisur Rahman*

#### ABSTRACT

Characterization of natural fractures in carbonate reservoirs to the resolution of well tests is reliable for major fracture corridors. These fracture corridors, intersecting or nonintersecting the wells, impact the well's performance and the ultimate recovery in the field. Good transient test data is the key to diagnosing fractures and their characteristics. When fractures exist between the wells, it requires some additional efforts in locating these with respect to the wells.

### **Emulsifier Developed from Waste Vegetable Oil for Application in Invert Emulsion Oil-based Mud**

*Dr. Jothibasur Ramasamy, Dr. Md. Amanullah, and Mujtaba M. Al-Saihati*

#### ABSTRACT

Emulsifiers are a class of chemicals derived from fatty acids or their derivatives and used in water- and oil-based mud (OBM) — an invert emulsion. The role of an emulsifier in invert emulsion OBM is to lower the interfacial tension between water and oil to allow the formation of stable emulsion, which is an essential quality of the OBM. These emulsifiers surround the water droplets like an encapsulation with the fatty acid components extended into the oil phase, which acts like a small osmotic cell allowing only water to pass through, but not salts.

### **Customized Drilling Fluids Design to Drill Challenging Sections Using High Performance Water-based Mud**

*Rafael M. Pino Rojas, Ihab M. El-Habrouk, Ajay Kumar V. Addagalla, and Prakash B. Jadhav*

#### ABSTRACT

This article presents a customized water-based drilling fluids design for drilling challenging sections through varying formations. The offset wells were reviewed to identify the issues while drilling the trajectory through troublesome reactive and depleted formations that showed wellbore stability issues, stuck pipe incidents, and induced severe losses.

